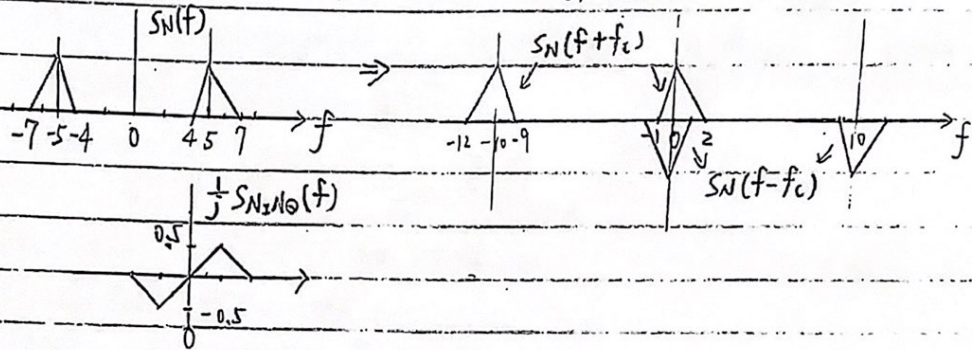


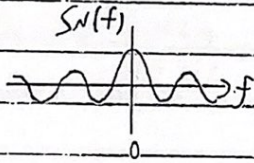
2021 Final Exam Reference Solution.

1. (a) No, For this result, the probability of H is $\frac{6}{10}$ and T is $\frac{4}{10}$, but they should be $\frac{1}{2}$ for a fair coin.

(b)
$$S_{N_2 N_0}(f) = \begin{cases} j[S_N(f+f_c) - S_N(f-f_c)] & -B \leq f \leq B \\ 0 & \text{elsewhere} \end{cases}$$



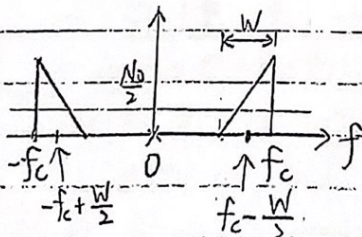
(c)
$$R(\tau) = \begin{cases} 1 & -1 \leq \tau \leq 1 \\ 0 & \text{elsewhere} \end{cases} \Rightarrow S_N(f) = \mathcal{F}\{R(\tau)\} = \int_{-1}^1 e^{-j2\pi f\tau} d\tau = \frac{\sin(\pi f)}{\pi f} = \text{sinc}(f)$$



This power spectral density function exists negative values at some frequencies, which is against that PSD ≥ 0 for all frequencies. \therefore It's not a valid autocorrelation function for a communication signal.

(d) No. The f^2 term comes from $\frac{d}{dt}$ function in FM discriminator. For PM detector, we don't have a slope circuit in it, so PM doesn't have f^2 noise reduction advantage.

2. (a)



Since it's a LSB signal, the BPF is with bandwidth W centered at $f_c - \frac{W}{2}$

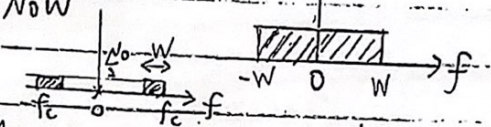
\therefore The filtered narrow band noise

$$n(t) = N_1 \cos(2\pi(f_c - \frac{W}{2})t) - N_0 \sin(2\pi(f_c - \frac{W}{2})t)$$

$$\begin{aligned} x(t) = s(t) + n(t) &= A_c m(t) \cos(2\pi f_c t) + A_c \hat{m}(t) \sin(2\pi f_c t) \\ &\quad + N_1(t) \cos(2\pi(f_c - \frac{W}{2})t) - N_0(t) \sin(2\pi(f_c - \frac{W}{2})t) \quad (4\%) \end{aligned}$$

$$\begin{aligned}
 v(t) &= x(t) \cos(2\pi f_c t) \\
 &= [A_c m(t) \cos(2\pi f_c t) + A_c \hat{m}(t) \sin(2\pi f_c t) + n_z \cos(2\pi(f_c - \frac{W}{2})t) \\
 &\quad - n_q(t) \sin(2\pi(f_c - \frac{W}{2})t)] \cos(2\pi f_c t) \\
 &= \frac{1}{2} A_c m(t) + \frac{1}{2} A_c m(t) \cos(4\pi f_c t) + \frac{1}{2} A_c \hat{m}(t) \sin(4\pi f_c t) \\
 &\quad + \frac{1}{2} n_z(t) \cos(2\pi \cdot \frac{W}{2} t) + \frac{1}{2} n_z(t) \cos(2\pi(2f_c - \frac{W}{2})t) \\
 &\quad + \frac{1}{2} n_q(t) \sin(2\pi \cdot \frac{W}{2} t) - \frac{1}{2} n_q(t) \sin(2\pi(2f_c - \frac{W}{2})t) \quad (4\%)
 \end{aligned}$$

(b) After LPF, $y(t) = \frac{1}{2} A_c m(t) + \frac{1}{2} n_z(t) \cos(2\pi \cdot \frac{W}{2} t) + \frac{1}{2} n_q(t) \sin(2\pi \cdot \frac{W}{2} t)$ (4%)
 At the output, the demodulated message power is $\frac{1}{4} A_c^2 P$. (4%)
 the demodulated noise power is $\frac{1}{8} \times \frac{N_0}{2} \times 2W + \frac{1}{8} \times \frac{N_0}{2} \times 2W = \frac{1}{4} N_0 W$.
 $\therefore (SNR)_0 = \frac{\frac{1}{4} A_c^2 P}{\frac{1}{4} N_0 W} = \frac{A_c^2 P}{N_0 W}$

(c) $(SNR)_I = \frac{P_s}{P_N} = \frac{A_c^2 P}{N_0 W}$ 
 Since $m(t)$ and $\hat{m}(t)$ carry the same power $\Rightarrow P_s = \frac{1}{2} A_c^2 P + \frac{1}{2} A_c^2 P = A_c^2 P$
 $P_N = \frac{N_0}{2} \times W \times 2 = N_0 W$

(d) $(SNR)_c = \frac{P_s}{P_N}$ where $P_s = A_c^2 P$.
 $P_N = \frac{N_0}{2} \times 2W = N_0 W$
 $\therefore (SNR)_c = \frac{A_c^2 P}{N_0 W}$

(e) $(FDM) = \frac{(SNR)_0}{(SNR)_c} = \frac{A_c^2 P / N_0 W}{A_c^2 P / N_0 W} = 1$

3. (a) Θ is not a random variable $\Rightarrow z(t) = x(t) \cos(2\pi f_c t + \theta_1)$
 $M_z = E[x(t) \cos(2\pi f_c t + \theta_1)] = E[x(t)] \cos(2\pi f_c t + \theta_1)$
 $= M_x \cdot \cos(2\pi f_c t + \theta_1) = 0$. \leftarrow stationary to the 1st order
 $R_z(t_2, t_1) = E[z(t_2) z(t_1)] = E[x(t_2) \cos(2\pi f_c t_2 + \theta_1) x(t_1) \cos(2\pi f_c t_1 + \theta_1)]$
 $= E[x(t_2) x(t_1)] \cdot \frac{1}{2} [\cos(2\pi f_c (t_2 - t_1)) + \cos(2\pi f_c (t_2 + t_1) + 2\theta_1)]$
 $= R_x(t_2 - t_1) \cdot \frac{1}{2} [\cos(2\pi f_c (t_2 - t_1)) + \cos(2\pi f_c (t_2 + t_1) + 2\theta_1)]$
 $\therefore \cos(2\pi f_c (t_2 + t_1) + 2\theta_1)$ is not a function of $t_2 - t_1$, thus
 $R_z(t_2, t_1)$ is not simply a function of $t_2 - t_1 = \tau$.
 $\therefore z(t)$ is not wide sense stationary.

(b) If Θ is also a random variable and is independent of $x(t)$
 Then $M_z = E[z(t)] = E[x(t) \cos(2\pi f_c t + \Theta)] = E[x(t)] E[\cos(2\pi f_c t + \Theta)]$

$$= \mu_x \mathbb{E}[\cos(2\pi f_c t + \theta)] = 0 \cdot 0 = 0$$

$\therefore \mu_z$ is a constant.

$$\begin{aligned} R_z(t_2, t_1) &= \mathbb{E}[z(t_2)z(t_1)] = \mathbb{E}[x(t_2)\cos(2\pi f_c t_2 + \theta) \cdot x(t_1)\cos(2\pi f_c t_1 + \theta)] \\ &= \mathbb{E}[x(t_2)x(t_1)] \mathbb{E}[\cos(2\pi f_c t_2 + \theta)\cos(2\pi f_c t_1 + \theta)] \\ &= R_x(t_2 - t_1) \cdot \frac{1}{2} \cos(2\pi f_c (t_2 - t_1)) \end{aligned}$$

$\therefore R_x(t_2 - t_1) = R_x(\tau)$ is a function of $\tau = t_2 - t_1$,

and $\frac{1}{2} \cos(2\pi f_c (t_2 - t_1)) = \frac{1}{2} \cos(2\pi f_c \tau)$ is also a function

of $\tau = t_2 - t_1$, only $\Rightarrow R_z(t_2 - t_1) = R_z(\tau)$ is a function of τ .

$\therefore z(t)$ is wide sense stationary.

$$4. (a) \quad (SNR)_0 = \frac{3}{2} \frac{A_c^2 k_f^2 P}{N_0 W} \quad CNR = \frac{\frac{1}{2} A_c^2}{\frac{1}{2} N_0 B_T} = \frac{A_c^2}{N_0 B_T} = \rho$$

$$\therefore \Delta f = k_f A_m \Rightarrow A_m = \Delta f / k_f \quad P = \frac{1}{2} A_m^2 = \frac{1}{2} \left(\frac{\Delta f}{k_f}\right)^2, \quad f_m = W$$

$$\therefore B_T = 2(\Delta f + W) \approx 2\Delta f \Rightarrow \Delta f \approx B_T/2 \Rightarrow P = \frac{1}{2} \left(\frac{B_T}{2k_f}\right)^2$$

$$\Rightarrow (SNR)_0 = \frac{A_c^2}{2N_0 B_T} \times 3 \times \frac{1}{8} \left(\frac{B_T}{W}\right)^3 = 3\rho \cdot \left(\frac{B_T}{2W}\right)^3$$

(b) To enhance $(SNR)_0$, we can either increase (1) CNR, ρ or (2) $\frac{B_T}{2W}$, that is transmission bandwidth (4%)

Since $(SNR)_0$ is linearly proportional to CNR, ρ , but is cubically proportional to B_T , so increasing B_T is more efficient. (4%)

(c) For AM, $\max\{FOM\} = 1/3$

$$(FOM)_{FM} = \frac{3k_f P}{W} = \frac{3}{2} \left(\frac{\Delta f}{W}\right)^2 \approx \frac{3}{2} \left(\frac{B_T}{2W}\right)^2$$

$$\text{If FM outperforms AM: } \frac{3}{2} \left(\frac{B_T}{2W}\right)^2 \geq 1/3 \Rightarrow B_T \geq \frac{2\sqrt{2}}{3} W$$

$$\therefore B_T \geq 0.943W$$

$\Rightarrow \therefore B_T = 2(\Delta f + W) \gg W$, So we can guarantee FM is always better than AM.

$$5. (a) \quad h(t) = 20e^{-5t} u(t) \Rightarrow H(f) = \int_0^{\infty} 20e^{-5t} e^{-j2\pi ft} dt = \frac{20}{5 + j2\pi f}$$

$$(b) \quad S_N(f) = |H(f)|^2 S_W(f) = \frac{400}{25 + (2\pi f)^2} \cdot S_W(f)$$

$$\therefore N_0 = 2 \times 10^{-2} \text{ W/Hz} \Rightarrow N_0/2 = 10^{-2} \text{ W/Hz}$$

$$\therefore S_N(f) = \frac{N_0}{2} |H(f)|^2 = \frac{400}{25 + (2\pi f)^2} \times 10^{-2} = \frac{4}{25 + (2\pi f)^2} \text{ W/Hz}$$

$$(c) \quad R_N(\tau) = \mathcal{F}^{-1}\{S_N(f)\} = \mathcal{F}^{-1}\left\{\frac{4}{25 + (2\pi f)^2}\right\}$$

$$\text{From } e^{-a|t|} \Leftrightarrow \frac{2a}{a^2 + (2\pi f)^2} \Rightarrow a = 5 \Rightarrow S_N(f) = \frac{4}{10} \times \frac{10}{25 + (2\pi f)^2}$$

$$\Rightarrow R_N(\tau) = \frac{2}{5} \times e^{-5|\tau|}$$

$$(d) \quad n(t) = w(t) \otimes h(t)$$

$$\therefore \mu_N(t) = E[n(t)] = E[w(t) \otimes h(t)] = E[w(t)] \otimes h(t) = \mu_w \otimes h(t)$$

$$= 0 \otimes h(t) = 0.$$

$$(e) \quad \sigma_N^2 = E[(N(t) - \mu_N)^2] = E[N(t)^2] = E[N(t)N(t)] = R_N(0)$$

$$= \frac{2}{5} \times e^{-5|\tau|} \Big|_{\tau=0} = \frac{2}{5}$$

(f) $n(t)$ is not a white noise because $R_N(\tau) = \frac{2}{5} e^{-5|\tau|} \neq \delta(\tau)$,
or because $S_N(f)$ is not a constant at all frequencies.

So, the answer is NO.

(g) Yes, $n(t)$ is still a Gaussian noise. This is because, according to the property of Gaussian process, any Gaussian processed signal passes a linear time invariant system, the output is also Gaussian.

$\therefore w(t)$: additive white Gaussian noise

$h(t)$: linear time invariant

$n(t) = w(t) \otimes h(t)$: still Gaussian

$$(h) \quad \mu_N = 0 \quad \sigma_N^2 = \frac{2}{5}$$

$$f_N(n) = \frac{1}{\sqrt{2\pi}\sigma_N} e^{-\frac{(n-\mu_N)^2}{2\sigma_N^2}} = \frac{1}{\sqrt{2\pi} \times \sqrt{\frac{2}{5}}} \times e^{-\frac{n^2}{2 \times \frac{2}{5}}} = \sqrt{\frac{5}{4\pi}} e^{-\frac{5n^2}{4}}$$