

Problem 1

107 台聯大訊號與系統

λ、(15%)

$$\propto \{n\}$$

If the input to an LTI system is $u[n]$, the output is $y[n] = (1/2)^{n-1} u[n]$.

(一) (6%) If $H(z)$ is the z-transform of the system impulse response, find its pole, zero, and the region of convergence.

(二) (5%) Find the impulse response $h[n]$ of this LTI system.

(三) (4%) Is the system stable? Is the system causal?

①

$$y(n) = \left(\frac{1}{2}\right)^{n-1} u(n) = 2\left(\frac{1}{2}\right)^n u(n)$$

$$x(n) = u(n)$$

$$x(n) = \frac{1}{r^n - 1}$$

$$y(n) = h(n) * x(n)$$

$$y(n) = h(x) \times x(n)$$

$$h(x) = \frac{x}{(x-1)}$$

$$\begin{aligned} &= \frac{x}{(x-1)} \cdot \frac{x^2 - 1}{x^2 - 1} \\ &= \frac{x^2 + 1}{x^2 - 1} \end{aligned}$$

$x = 0$ or zero

$$\begin{aligned} &= \frac{x^2 + 1}{x^2 - 1} \\ &= \frac{x^2 - 1 + 2}{x^2 - 1} \\ &= 1 + \frac{2}{x^2 - 1} \end{aligned}$$

$$\boxed{\frac{x^2 - 1}{x^2 - 1} - 2 = H(x)}$$

$$x_1(n) = u(n)$$

$$y_1(n) = 2 \left(\frac{1}{2}\right)^n u(n) \quad (3)$$

$$x_2(n) = u(n-1)$$

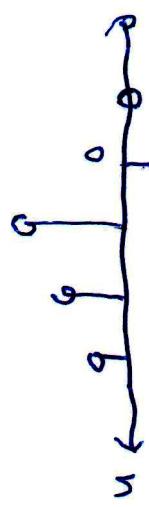
$$y_2(n) = 2 \left(\frac{1}{2}\right)^n u(n-1)$$

$$x(n) = s(n)$$

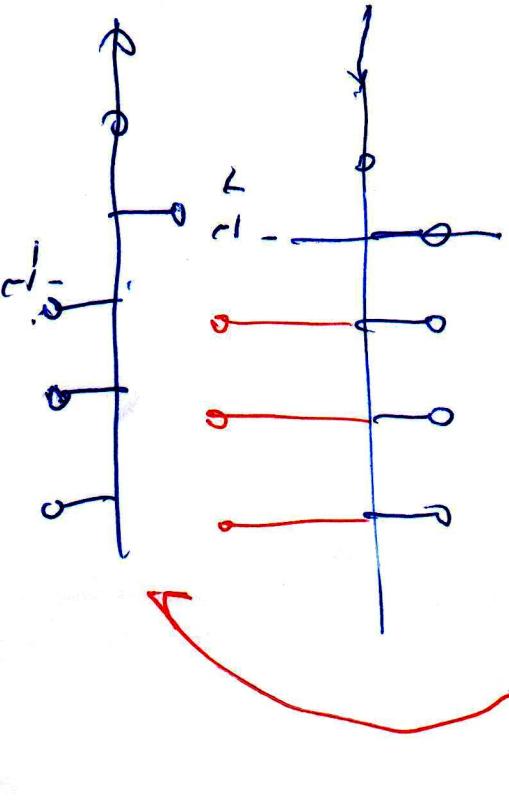
$$\begin{aligned} y(n) &= 2 \left[\left(\frac{1}{2}\right)^n u(n) \\ &\quad - \left(\frac{1}{2}\right)^{n-1} u(n-1) \right] \end{aligned}$$

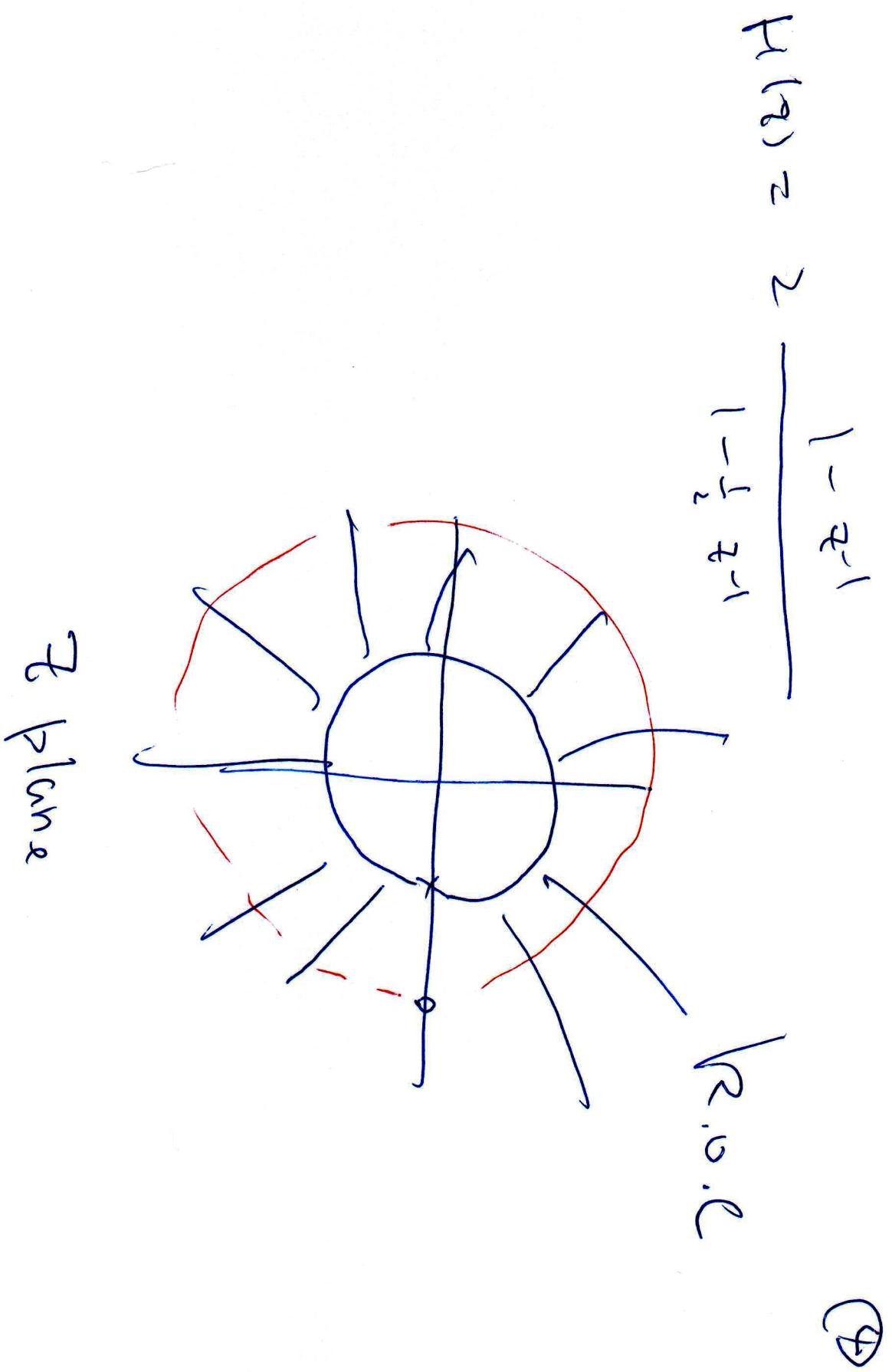
$$h(n) = 2 \left(\frac{1}{2}\right)^{n-1} \left[\frac{1}{2} u(n) - u(n-1) \right]$$

$$v(n) \neq$$



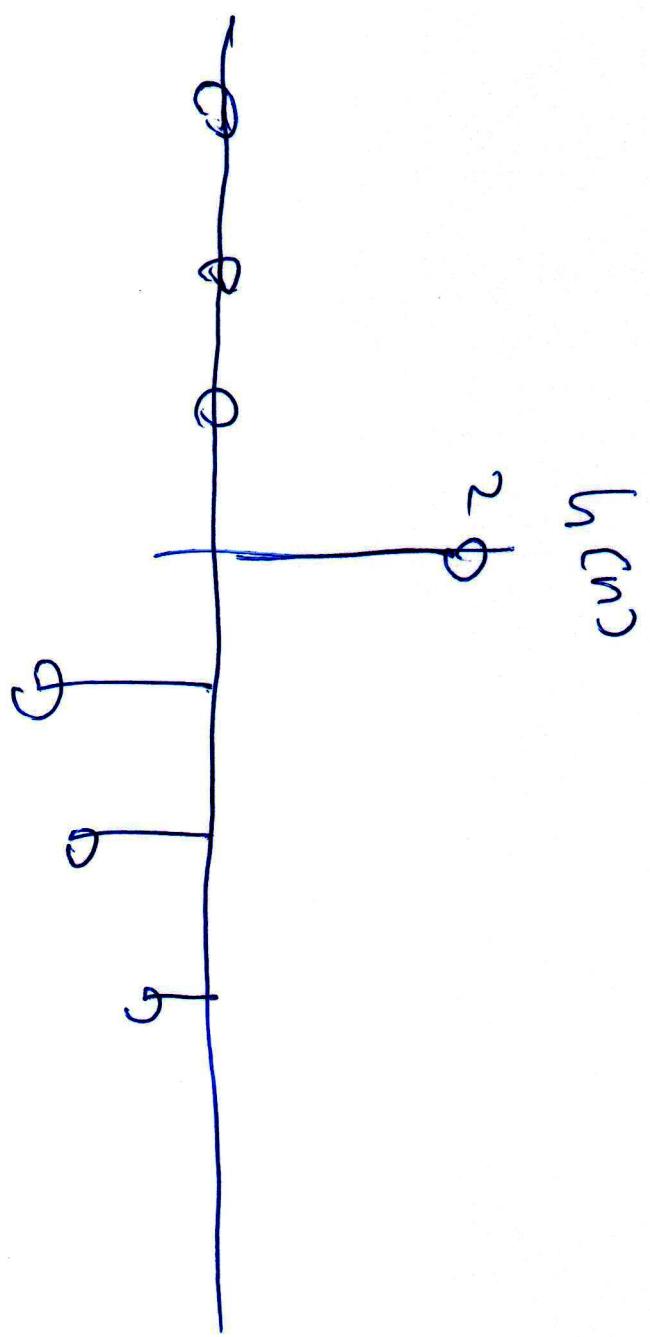
$$-\frac{1}{2} + 2 + \frac{1}{2}$$





⑤

$$H(x) = 2 - \frac{1}{1 + e^{-2x}}$$



$$h(u) = 2 \cdot \sinh\left(\frac{1}{2}u\right) - \left(\frac{1}{2}\right)^{u-1} \sinh(u-1)$$

Problem 2

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(6)

二、(10%)

~~(a) (5%) The impulse response of an LTI system is $h(t) = \begin{cases} \cos(\pi t), & |t| < 0.5 \\ 0, & \text{otherwise} \end{cases}$. Use linearity and time-~~

~~invariance to determine and plot the output $y(t)$ for $x(t) = \delta(t+1) - \delta(t-1)$.~~

(b) (5%) Evaluate the convolution sum: $y[n] = (u[n+3] - u[n-1]) * u[n-4]$.

$$y[n] = u[n+3] * u[n-4] - u[n-1] * u[n-4]$$

$$Y(z) = \frac{z^4}{1-z^{-1}} * \frac{z^{-4}}{1-z^{-1}} = \frac{z^{-1}}{1-z^{-1}} * \frac{z^{-4}}{1-z^{-1}}$$

$$= z^{-1}$$

$$= \frac{(1-z^{-1})^2}{(1-z^{-1})^{n-1}} - \frac{(1-z^{-1})^2}{(1-z^{-1})^{n-5}}$$

$$u[n] =$$

$$(u[n+1] - u[n-1]) * u[n-4]$$

$$= u[n+1] - (n-4)u[n-5]$$

$$u(n) \hookrightarrow \frac{1}{1-z^{-1}} \quad |z| > 1$$

(1)

$$(n+1) u(n) \mapsto \frac{1}{(-z^{-1})^2} \quad |z| > 1$$

$$(n+1) u(n) \mapsto \frac{1}{(1-\alpha z^{-1})^2} \quad |z| > |\alpha|$$

Problem 3
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(8)

三、(15%)

- (a) (10%) Find the frequency response (5%) and impulse response (5%) of the discrete-time system described by $8y[n] - 2y[n-1] - y[n-2] = x[n] + x[n-1]$.
- (b) (5%) Draw direct form II implementation of the system in (a).

Causal

$$y[n] + \left(\frac{-2}{8}\right) y[n-1] + \left(\frac{-1}{8}\right) y[n-2] =$$

$$\cancel{x[n]} + \cancel{x[n-1]} + 0 \cdot x[n-2] =$$

$$(9) \quad g(n) - 2g(n-1) - g(n-2) = x(n) + x(n-1)$$

$$(2) \quad X_{1,-2} + (2)X = (2) \left[x_{-1} - x_0 - x_1 \right] + 8$$

$$\frac{x_{-2} - x_{-1} - x_0 - x_1}{1 - x + 1} = (2) \left[x_{-1} \right]$$

$$\frac{1 - x^2 \frac{8}{1} - 1 - x^{\frac{3}{2}} - 1}{1 - x + 1} = (2)H$$

$$\frac{\left(1 - x^{\frac{1}{2}} - 1 \right) \left(1 - x^{\frac{1}{2}} + 1 \right)}{1 - x + 1} = \frac{8}{1 - x^2}$$

$$H(e^{j\omega_n t})$$

$$= \frac{1}{1 + e^{j\omega_n t}}$$

$$= \frac{1}{1 - \frac{1}{4}e^{-j\omega_n t} - \frac{8}{16}e^{-j4\omega_n t}}$$

(c)

$$H(e^{j\omega_n t}) = \frac{\frac{8}{1}}{1 + e^{j\omega_n t}}$$

$$\begin{aligned} &= \frac{(x^{\frac{7}{4}} - 1)(x^{\frac{3}{4}} + 1)}{x + 1} \\ &\quad + \frac{x^{\frac{3}{4}} + 1}{x + 1} \\ &\quad \text{② } 5 \end{aligned}$$

$$\begin{aligned} 1 - &= \frac{a}{x^{\frac{1}{4}} - 1} \\ &+ \frac{(x^{\frac{7}{4}} + 1)}{x^{\frac{1}{4}} - 1} \\ &+ a \end{aligned}$$

$$h(u) = \frac{8}{1 - \left(-\frac{1}{4}\right)^2} u(u) + \frac{2}{2} \left(-\frac{1}{4}\right) h(u)$$

$$H(x) = \frac{\frac{8}{1 - \frac{1}{16}x^{-2}} + \frac{2}{1 - \frac{1}{16}x^{-2}}}{1 + \frac{1}{4}x^{-1}}$$

$$\frac{y_0}{y_1} = \frac{2}{3}$$

$$\frac{1}{1 + \frac{1}{4}x} = \frac{1}{1 - \frac{1}{2}x} + \frac{1}{1 + x}$$

(1)

$$y_n - y_{n-1} - y_{n-2} = x_n + x_{n-1}$$

(12)

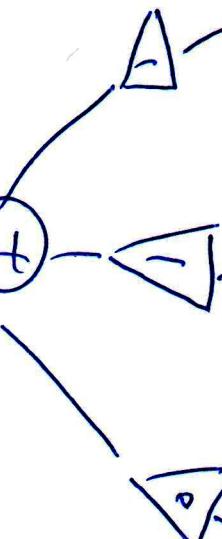
$$w_n = x_n + x_{n-1}$$

$$y_n - y_{n-1} - y_{n-2} = w_n$$

$$x_{n-1} + x_{n-2}$$

$$w_n$$

$$w_n = x_n + x_{n-1}$$



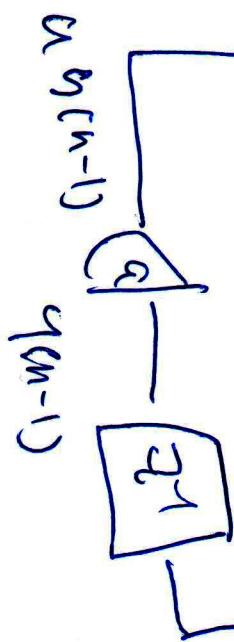
(13)

$$w(n) = a_0 \rightarrow (n) + a_1 x^{(h-1)} + a_2 x^{(h-2)}$$
$$x^{(h-1)} \quad x^{(h-2)}$$
$$x^{(h-1)} \quad x^{(h-2)}$$
$$x^{(h-1)} \quad x^{(h-2)}$$

$$x(n) + \alpha y(n-1)$$

$y(n)$

14



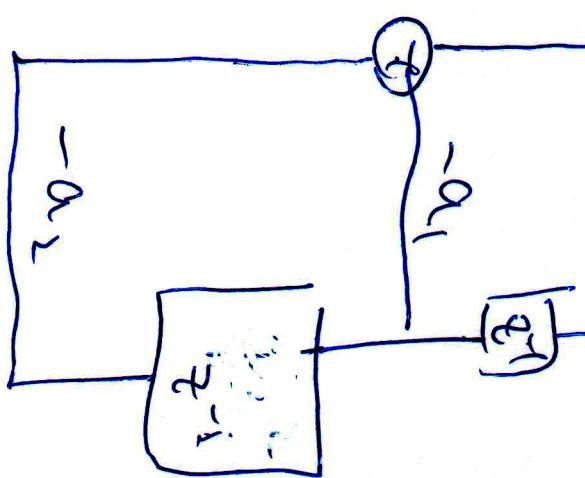
$$y(n) = \alpha y(n-1) + x(n)$$

$$y(n) = \alpha y(n-1) + x(n)$$

$$y_m + \alpha_1 y_{m-1} + \alpha_2 y_{m-2} = w_m$$

$$y_m = w_m + (\alpha_1 y_{m-1} + (-\alpha_2) y_{m-2})$$

$$w_m =$$



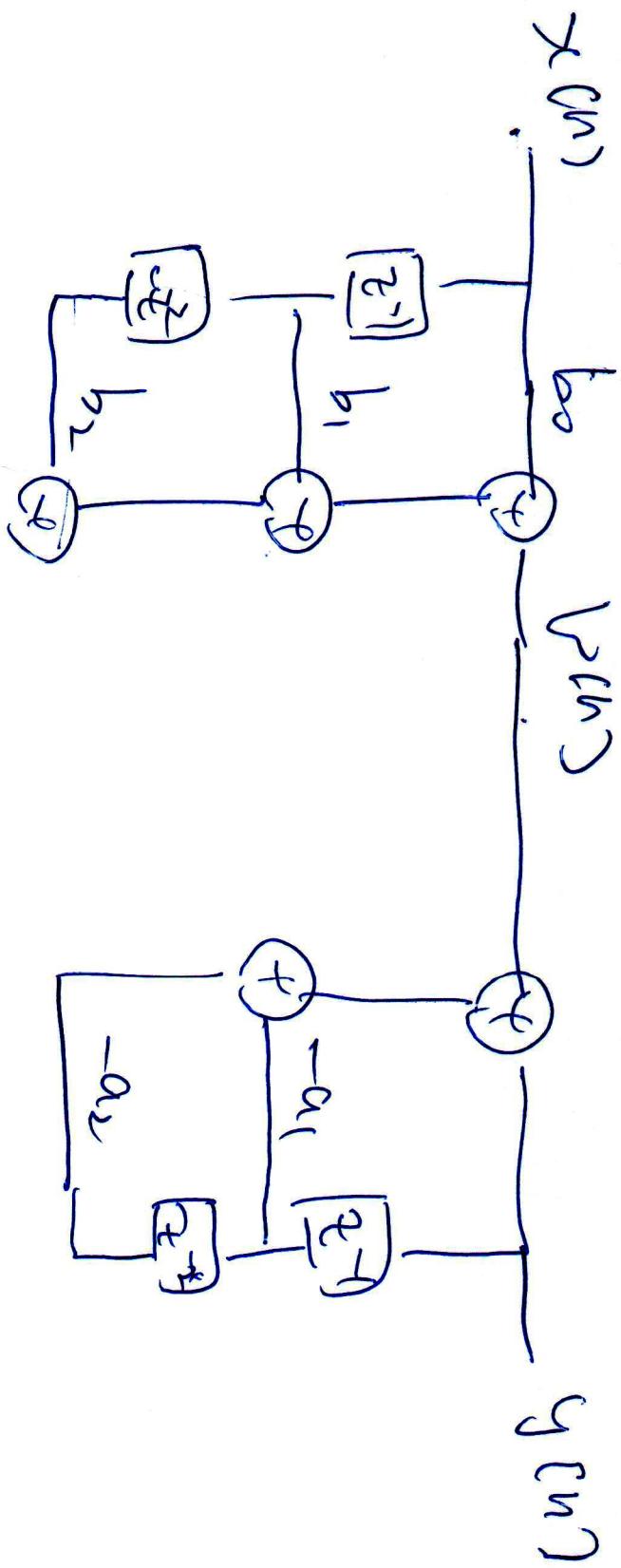
(15)

(6)

$$y(n) + a_1 y(n-1) + a_2 y(n-2) = b_1 x(n) + b_2 x(n-1)$$

$$w(n) = b_1 x(n) + b_2 x(n-1)$$

$$y(n) + a_1 y(n-1) + a_2 y(n-2) = w(n)$$

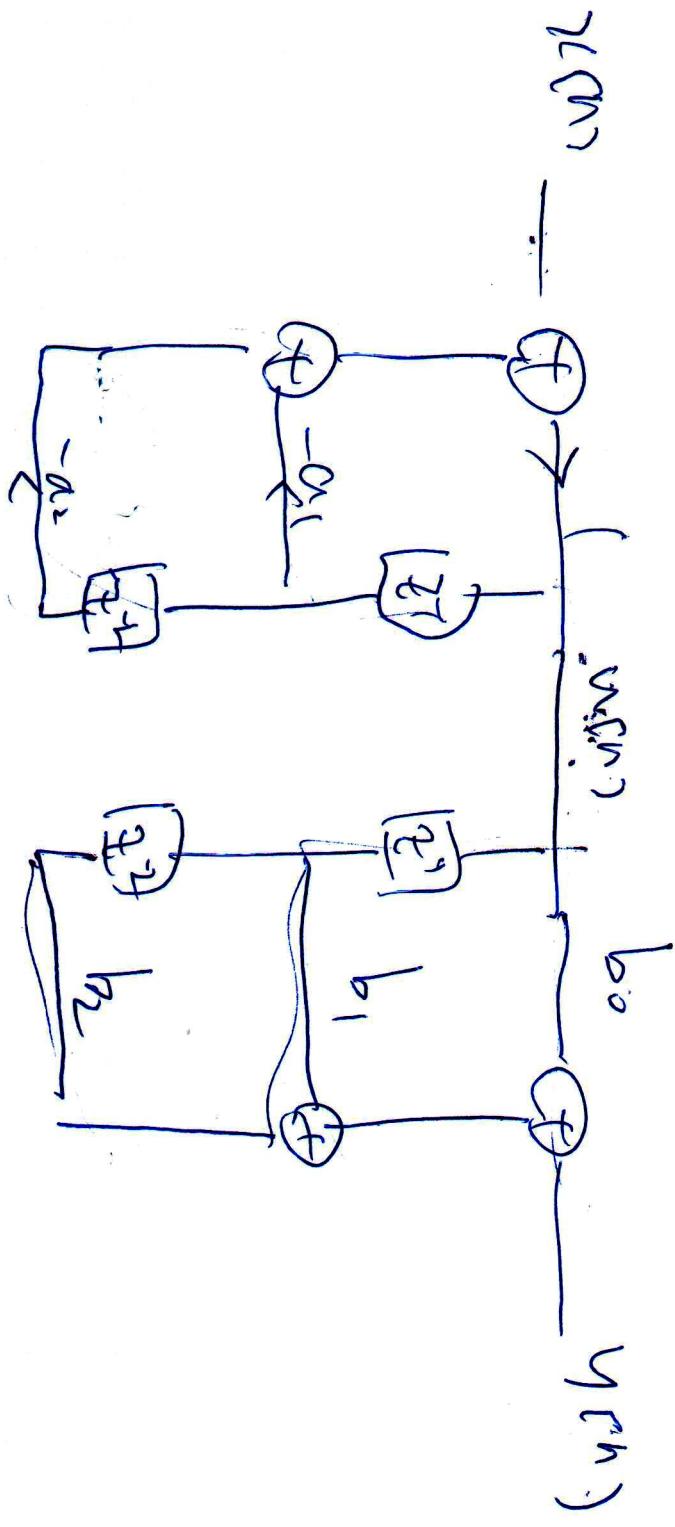
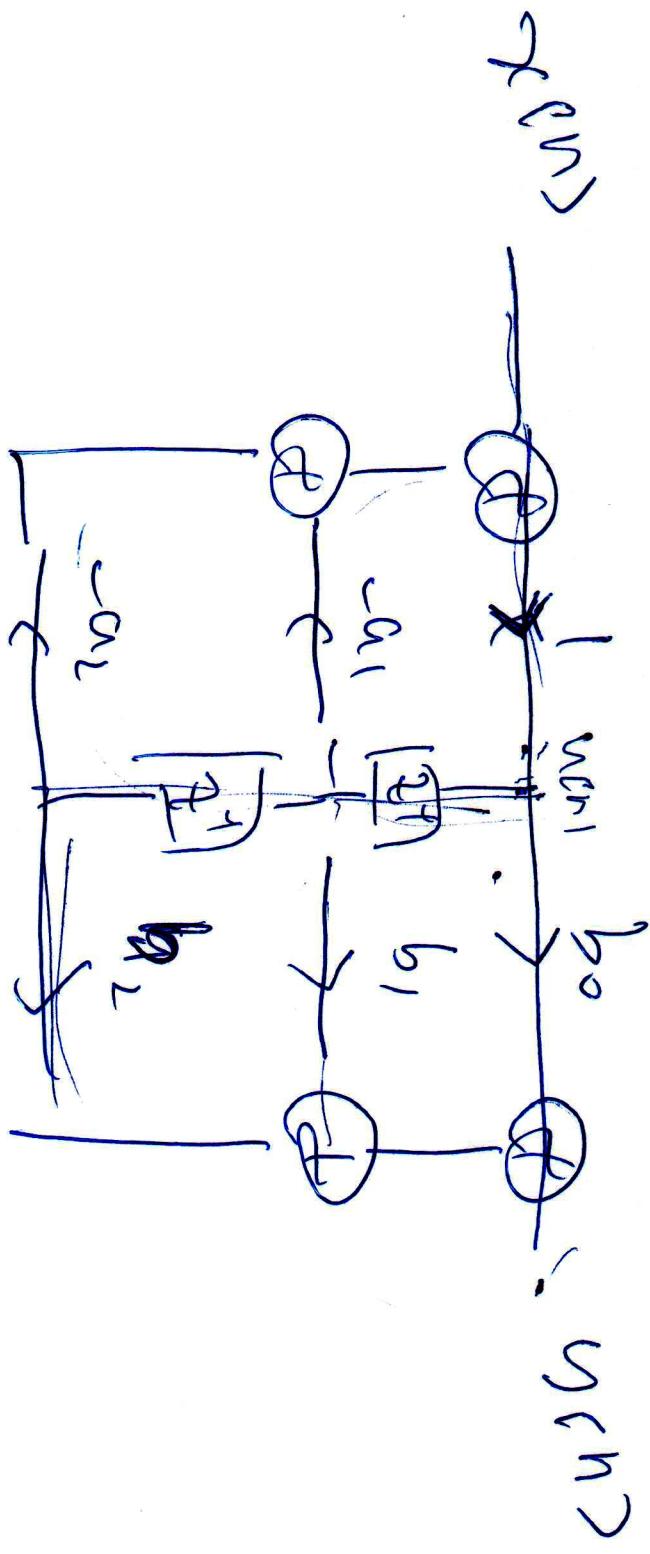


$H_1 \times H_2$ $\cong H_1 \times H_2$

(1)

$$\begin{array}{c} \gamma(w) \\ \downarrow \\ [h_1(w)] \longrightarrow [h_2(w)] \longrightarrow \gamma(w) \\ (z) = h_1(z) \times h_2(z) \end{array}$$

$$\begin{array}{c} x(w) \\ \downarrow \\ [h_1(w)] \longrightarrow [\overline{h_1(w)}] \longrightarrow x(w) \\ \text{End} \end{array}$$



(1)

$$y(n) + a_1 y(n-1) + a_2 y(n-2) = b_0 x(n) + b_1 x(n-1) + b_2 x(n-2)$$

(9)

$x(n)$



$$a_1^{-1}$$

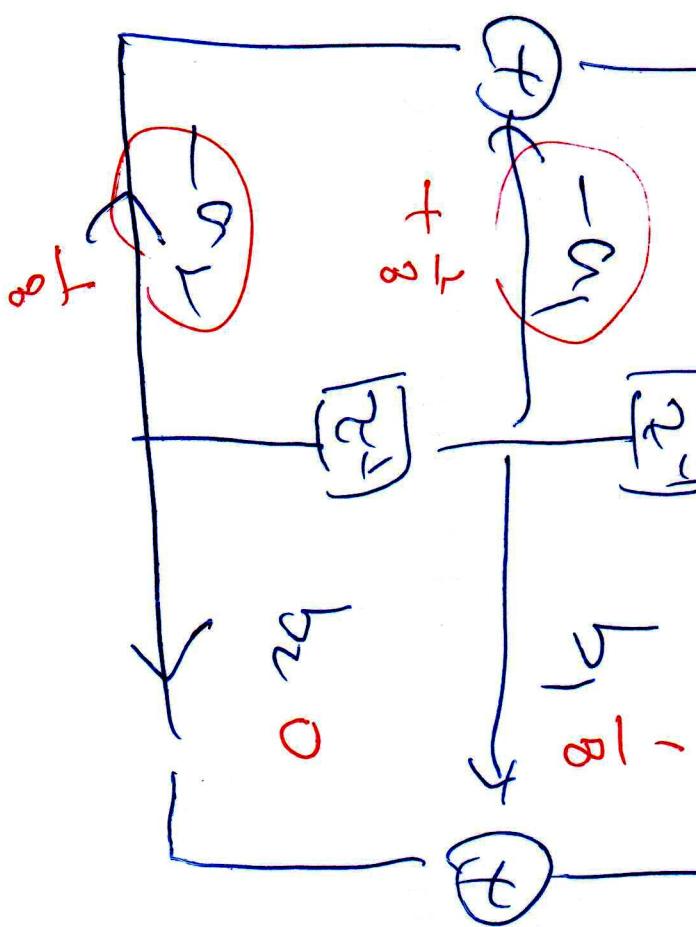
$$a_2^{-1}$$

$$b_0^{-1} a_1^{-1}$$

$$b_1^{-1}$$

$y(n)$

$$b_2^{-1}$$



Problem 4
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(25)

)(· (15%) When the input to a causal LTI system is $x[n] = -\frac{1}{3}\left(\frac{1}{3}\right)^n u[n] - \frac{4}{3}2^n u[-n-1]$, the z-

transform of the output is $Y(z) = \frac{1+z^{-1}}{(1-z^{-1})(1+0.5z^{-1})(1-2z^{-1})}$.

- (a) (5%) Find the z-transform of $x[n]$. $H(z)$
- (b) (4%) What is the region of convergence of $H(z)$?
- (c) (4%) Find the impulse response of the system.
- (d) (2%) Is the system stable? No, unstable



(a)

$$x[n] = -\frac{1}{2} \left(\frac{1}{2} \right)^n u[n] + \frac{4}{3} \left(-\left(\frac{1}{2}\right)^n u[n-1] \right)$$

(21)

 $\alpha^n u[n] \leftrightarrow \frac{1}{1-\alpha z^{-1}}$

$$\alpha^n u[n-1] \leftrightarrow \frac{1}{1-\alpha z^{-1}}$$

 $|z| > |\alpha|$ $-\alpha^n u[n-1] \leftrightarrow \frac{1}{1-\alpha z^{-1}}$

$$|z| < |\alpha|$$

$$X(z) = -\frac{\frac{1}{2}}{1-\frac{1}{2}z^{-1}} + \frac{\frac{4}{3}}{1-z^{-1}}$$

$|z| > \frac{1}{2}$
 $|z| < 1$

$$\left(1 - \frac{1}{2}z^{-1} \right) \left(1 - z^{-1} \right)$$

$$\frac{(-x_1, (1+0.5x_2, -1))}{(1-x_2, (1+0.5x_2, -1))} = H(x)$$

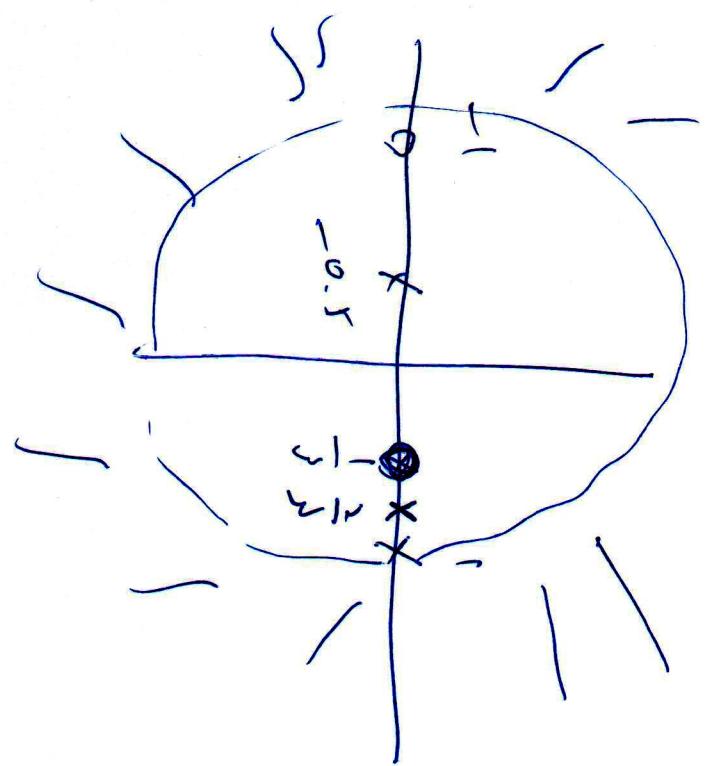
$$\frac{\cancel{(1-x_2, (1-x_1, -1))}}{(1-x_2, (1-x_1, -1))} = \frac{x(x)}{x(x)} = x(x) \quad (\text{Q})$$

$$\frac{\cancel{(1-x_2, (1-x_1, -1))}}{(1-x_2, (1-x_1, -1))} = \frac{1-x_2}{1-x_2+1} = \frac{1-x_2}{2-x_2} = x(x) \quad (\text{Q})$$

$$\frac{(1-x_2, (1-x_1, -1))}{(1-x_2, (1-x_1, -1))} = \frac{(1-x_2)(1+x_0.5x_2, -1)}{1-x_2+1} = x(x)$$

$$\boxed{\frac{(-x_2, -1), (1-x_2, -1)}{1-x_2, -1} = x(x) \quad X}$$

(2) $\frac{1}{x} - \frac{1}{2} +$



$R_0(\tau) > 1$

(52)

$$H(x) = \frac{(1-x)(-1-\frac{1}{x})}{(1-x^2)(-1-\frac{1}{x^2})(-1-\frac{1}{x^3})}$$

$$(1+x-\frac{1}{x})(-1)(\frac{1}{1-x^2})$$

$$= \frac{a}{1-x^{-1}} + b \underbrace{\frac{1}{1+x^{-1}x^{-1}}} + c \frac{1}{1-x^{-2}}$$

$$h(n) = \alpha u[n] + b (-0.5)^n u[n] + (\frac{2}{3})^n u[n]$$

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Problem 5

1.04 台聯大訊號與系統

(25)

$$\text{四} \cdot (15 \text{ pts}) \text{ Let } H_1(z) = \frac{z^{-1}}{1 - 2.5z^{-1} + z^{-2}} \quad H_2(z) = \frac{0.5z^{-1}}{1 - 2z^{-1} + 0.75z^{-2}}. \text{ Answer the following questions:}$$

- (一) (3 pts) Find the region of convergence so that $H_1(z)$ is stable. Also, find the corresponding time domain sequence $\{h_1[n]\}$.

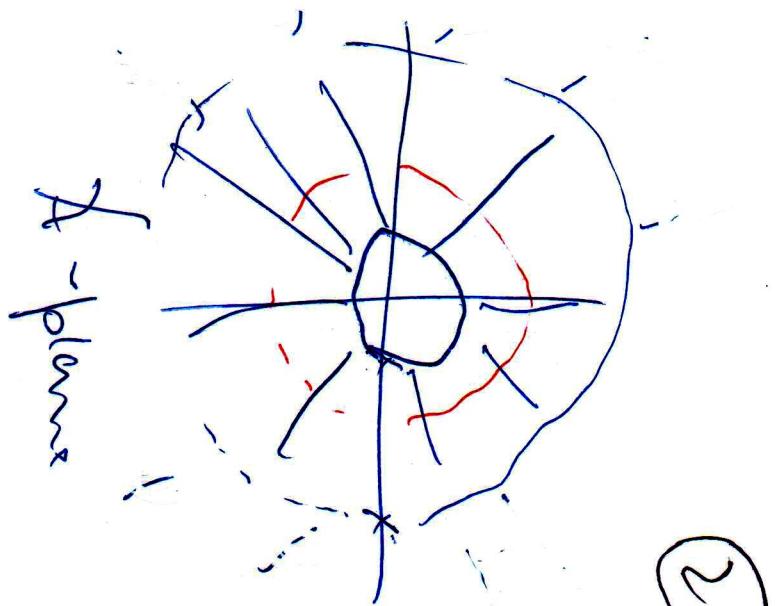
- (二) (3 pts) Find the region of convergence so that $H_2(z)$ is causal. Also, find the corresponding time domain sequence $\{h_2[n]\}$.

(三) (0 pts) Let $X(z)$ be the input and $Y(z)$ be the output. $X(z)$ has the same condition in (a) and $Y(z)$ has the same condition in (b), find the system transfer function $H(z)$. Is $H(z)$ stable? Is $H(z)$ causal?

Explain your answer.

$$\begin{aligned}
 & H(z) = \frac{z - 1}{z + 1} \\
 & \alpha = -\frac{1}{2} \\
 & \alpha = \alpha + \frac{1}{2} = \frac{-z^2 - 1}{z^2 - 1} \\
 & \left(\frac{-z^2 - 1}{z^2 - 1} \right)^{-1} = \frac{z^2 - 1}{z^2 + 1} \\
 & \text{Residue at } z = i \\
 & \text{Residue at } z = -i \\
 & \text{Residue at } z = \infty
 \end{aligned}$$

$$z \in \mathbb{C} \setminus \mathbb{R}$$



26

✓

✓

✓

$$h(n) = \frac{1}{n!} \left(\frac{1}{2} n^2 - 2 n + (-1)^n \right)$$

$$\begin{aligned} h(r) &= \frac{1}{r!} \\ &= \frac{\frac{1}{2} r^2 - 1}{r!} + \frac{(-1)^r}{r!} \end{aligned}$$

$$\begin{aligned} q &= \frac{1}{r!} \\ &= \frac{1}{r!} \left(\frac{1}{2} r^2 - 1 \right) + \frac{(-1)^r}{r!} \\ &= \frac{1}{r!} \left(\frac{1}{2} r^2 - 1 \right) + \frac{(-1)^r}{r!} \end{aligned}$$

$$= (x)^2 H$$

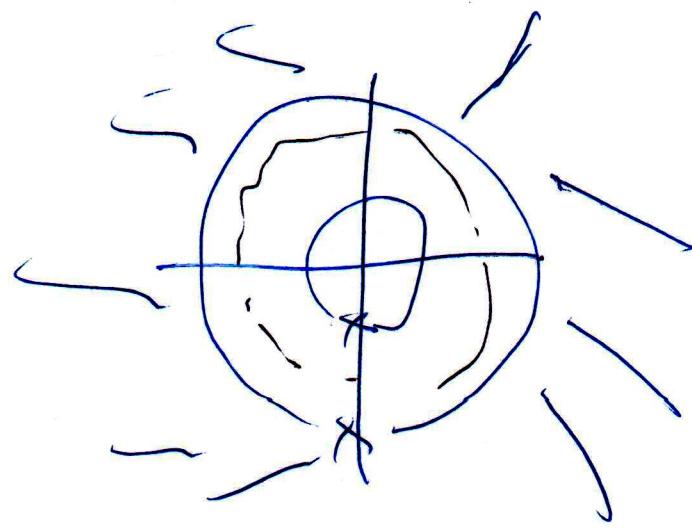
$$\begin{pmatrix} 0 & -2 & 5 \\ -2 & 0 & 1 \\ 5 & -1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & -2 & 5 \\ -2 & 0 & 1 \\ 5 & -1 & 0 \end{pmatrix}$$

$$= (x)^2 H$$

$$\begin{pmatrix} 0 & -1 & x \\ -1 & 0 & 1 \\ x & 1 & 0 \end{pmatrix}$$

$$(1-x^2)(x^2-1)$$



(82)

$$\begin{aligned}
 & Q = \frac{(-3)}{1} - \frac{5}{x+1} + \frac{1}{x-1} \\
 & \text{L.H.S.} = \frac{1}{x-1} + \frac{1}{x+1} - \frac{5}{x^2-1} \\
 & \quad = \frac{x+1+x-1-5}{x^2-1} \\
 & \quad = \frac{2x-4}{x^2-1} \\
 & \quad = \frac{2(x-2)}{(x-1)(x+1)} \\
 & \quad = \frac{2}{x+1} - \frac{4}{x-1} \\
 & \quad = \frac{2}{x+1} - \frac{4}{x-1} + 0
 \end{aligned}$$

Q

$$H(x) = \begin{pmatrix} - & - \\ - & - \\ - & - \\ - & - \end{pmatrix}$$

$$H(u) = \begin{pmatrix} - & - \\ - & - \\ - & - \\ - & - \end{pmatrix}$$

$$\begin{pmatrix} - & - \\ - & - \end{pmatrix}$$

$$\begin{pmatrix} - & - \\ - & - \end{pmatrix}$$

$$\begin{pmatrix} - & - \\ - & - \end{pmatrix}$$

$$\begin{pmatrix} - & - \\ - & - \end{pmatrix}$$

$$\begin{pmatrix} - & - \\ - & - \end{pmatrix}$$

1 < 2

30