

HW 11

Problem 1

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1. (5%)

The output ($y(t)$) of a continuous-time system is related to its input ($x(t)$) as $y(t) = e^{-t}x(t-2)$, $t > 0$.

Determine whether the system is (a) stable (2%), (b) causal (1%), (c) linear (1%), and (d) time invariant (1%).

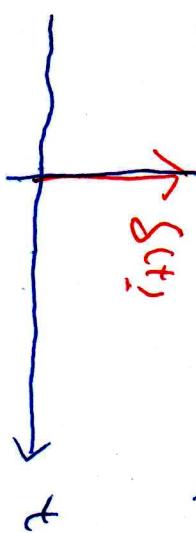
Ans.

Ans.

Ans.

Ans.

$$y(t) = e^{-t}x(t-2)$$



$$h(t) = e^{-t} \delta(t-2)$$

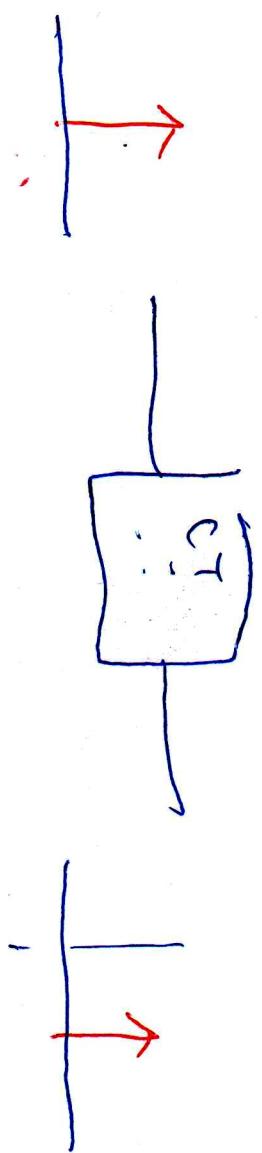
$$h(t) = e^{-2} \delta(t-2)$$

$$e^{-2} \delta(t-2)$$



$$\int_{-\infty}^{t-2} [e^{-2} \delta(t-2)] dt$$

$$= e^{-2} \cdot 1$$



Problem 2

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(2)

6. (6%)

Find the Laplace transforms of the following functions.

$$(1) h(t) = e^{-t}u(t)$$

$$(2) h(t) = te^{-t}u(t)$$

$$(1) h(t) = e^{-t}u(t)$$

$$H(s) = \frac{1}{s+1}, \text{Re}\{s\} > -1$$

$$(2) h(t) = t \cdot e^{-t}u(t)$$

$$H(s) = \frac{1}{(s+1)^2}, \text{Re}\{s\} > -1$$

Problem 3

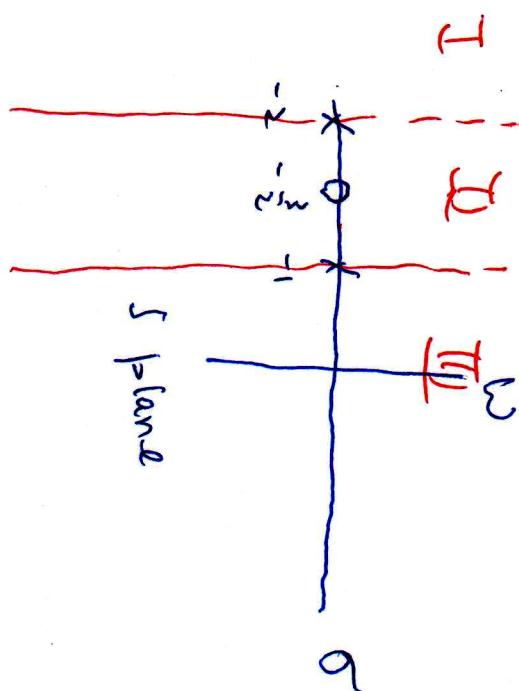
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8. (6%)

Find the locations of poles and zeros and discuss the causality and stability of the following s-domain transfer function.

$$H(s) = \frac{2s + 3}{s^2 + 3s + 2}$$

$$H(s) = \frac{2(s + \frac{3}{2})}{(s+1)(s+2)}$$



Causality	With causal	Non-causal	Causal
Stability	Not	Not (BIBO)	(Nyquist Stability)
Stability	BIBO Stabilizing		

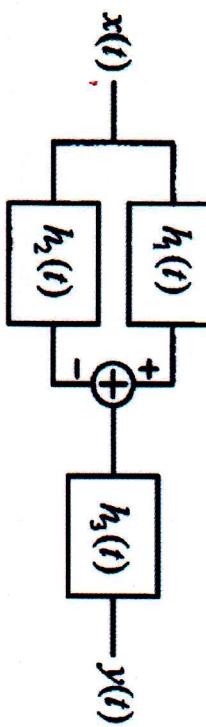
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Problem 4
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(4)

10. (8%)

Find the impulse response (i.e., $h(t)$) and the transfer function (i.e., $H(s)$) of the following CT LTI system. The input signal is $x(t)$ and the output signal is $y(t)$.



$h_1(t) = \delta(t)$, $h_2(t) = e^{-t}u(t)$, and $h_3(t) = e^{-t}u(t)$.

$$h(t) = (h_1(t) + h_2(t)) * h_3(t)$$

$$H(s) = (H_1(s) + H_2(s)) \times H_3(s)$$

$$h_2(t) = e^{-t}u(t)$$

$$H_2(s) = \frac{1}{s+1}$$

$$\text{Re}\{s\} > -1$$

$$h_3(t) = e^{-t}u(t)$$

$$H_3(s) = \frac{1}{s+1}$$

$$\text{Re}\{s\} > -1$$

(5)

$$H(s) = \left(s + \frac{1}{s+1} \right) \cdot \frac{1}{s+1}$$

$$H(s_1) = \boxed{\frac{1}{s_1 + 1} + \frac{1}{s_1 + 2}}$$

$$H(s) = \frac{s+2}{(s+1)^2}$$

$$h(t) = e^{-t} u(t) + e^{-t} u(t)$$

Problem 5

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五、(15%)

(一) (5%) Determine the Fourier representation of the following signal

$$x(t) = 2e^{-t}u(t) - 3e^{-2t}u(t)$$

(二) (10%) Find the time-domain signals corresponding to the following Fourier transform representations:

$$(5\%) \quad x(e^{j\omega}) = \frac{1}{1-ae^{-j(\omega+\frac{\pi}{4})}}, |\omega| < 1$$

$$Y(j\omega) = \frac{1}{2+j(\omega-3)} + \frac{1}{2+j(\omega+3)}$$

$$\rightarrow h(t) = 2e^{-t}u(t) - 3e^{-2t}u(t)$$

$$H(s) = 2 \frac{1}{s+1} - 3 \frac{1}{s+2}$$

$$H(s) = \frac{2s+4-3s-3}{s^2+3s+2}$$

$$H(s) = \frac{-s+1}{s^2+3s+2}$$

$$e^{-at} u(t) \leftrightarrow \frac{1}{a+j\omega}$$

$$e^{-at} u(-t) \leftrightarrow \frac{1}{a-j\omega}$$

$$Re\{s\} > Re\{-a\}$$

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$$H(j\omega n) = \frac{-j\omega n f_1}{(2 - 4n^2 f^2) + j\omega n f}$$

$$\Rightarrow Y(j\omega n) = \frac{1}{2 + j\omega n - j} + \frac{1}{2 + j\omega n + j}$$

$$= \frac{1}{(2 - 3j) + j\omega n} + \frac{1}{(2 + 3j) + j\omega n}$$

$$Y(t) = \frac{-e^{-(2-3j)t}}{e^{-(2+3j)t}} u(t) + \frac{e^{-(2+3j)t}}{e^{-(2-3j)t}} u(t)$$

$$Y(t) = e^{-2it} (e^{+3jt} + e^{-3jt}) u(t)$$

$$Y(t) = 2 e^{-2t} \cos 3t u(t)$$

Problem 6

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t · (10%)

A causal LTI system has an impulse response $h(t)$ that satisfies the differential equation

$$CT \quad \boxed{\frac{dh(t)}{dt} + 3h(t) = e^{-4t}u(t) + ce^{-5t}u(t),}$$

where c is a constant. Moreover, the system output is (2/15) e^t when the input to the system is e^t

- (一) (3%) Determine the constant c .
- (二) (3%) If the transfer function of this system is $H(s)$, find its poles.
- (三) (4%) Specify the region of convergence of $H(s)$ and tell whether or not the system is stable.

Ans:

$$S H(s) + 3H(s) = \frac{1}{s+4} + C \frac{1}{s+5}$$

$$H(s) = \frac{1}{s+3} \left(\frac{1}{s+4} + C \frac{1}{s+5} \right)$$

$$\frac{1}{15} e^t = H(1) e^{1t}$$

$$H(1) = \frac{1}{4} \times \left(\frac{1}{5} + \frac{C}{6} \right)$$

$$\frac{1}{15} = \frac{6 + 5C}{24} = \frac{16}{24} \quad [C=2]$$

$$e^{st} \rightarrow \boxed{H(s)} \rightarrow H(s) e^{st}$$

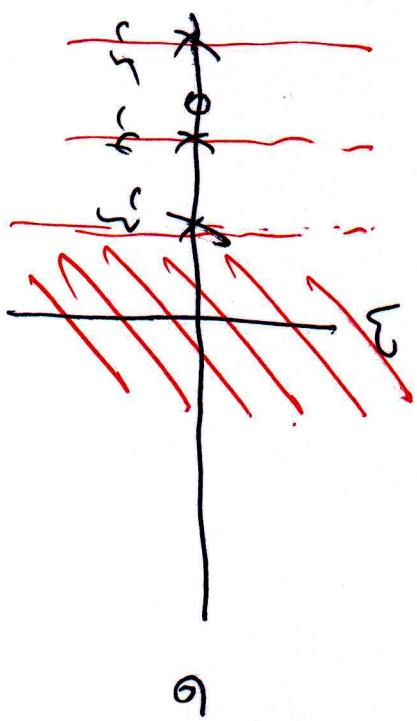
$$H(1) e^{1t}$$

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$$H(s) = \frac{1}{s+3} \left(\frac{1}{s+4} + \frac{2}{s+5} \right)$$

$$H(s) = \frac{(s+5) + 1(s+4)}{(s+3)(s+4)(s+5)}$$

$$\boxed{H(s) = \frac{s+13}{(s+3)(s+4)(s+5)}}$$



The system is stable because the ROC contains Imaginary axis.

s plane

(5)

Problem 7

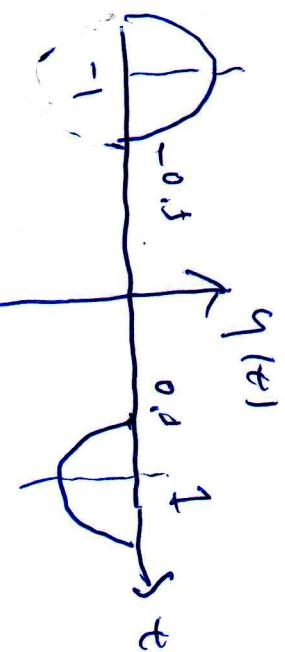
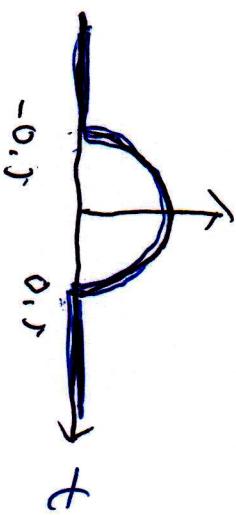
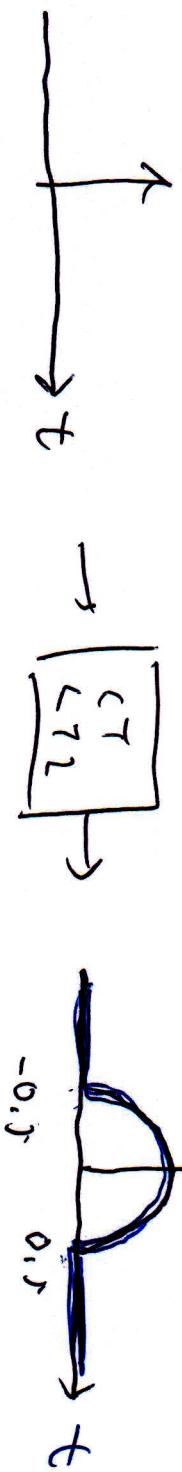
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二、(10%)

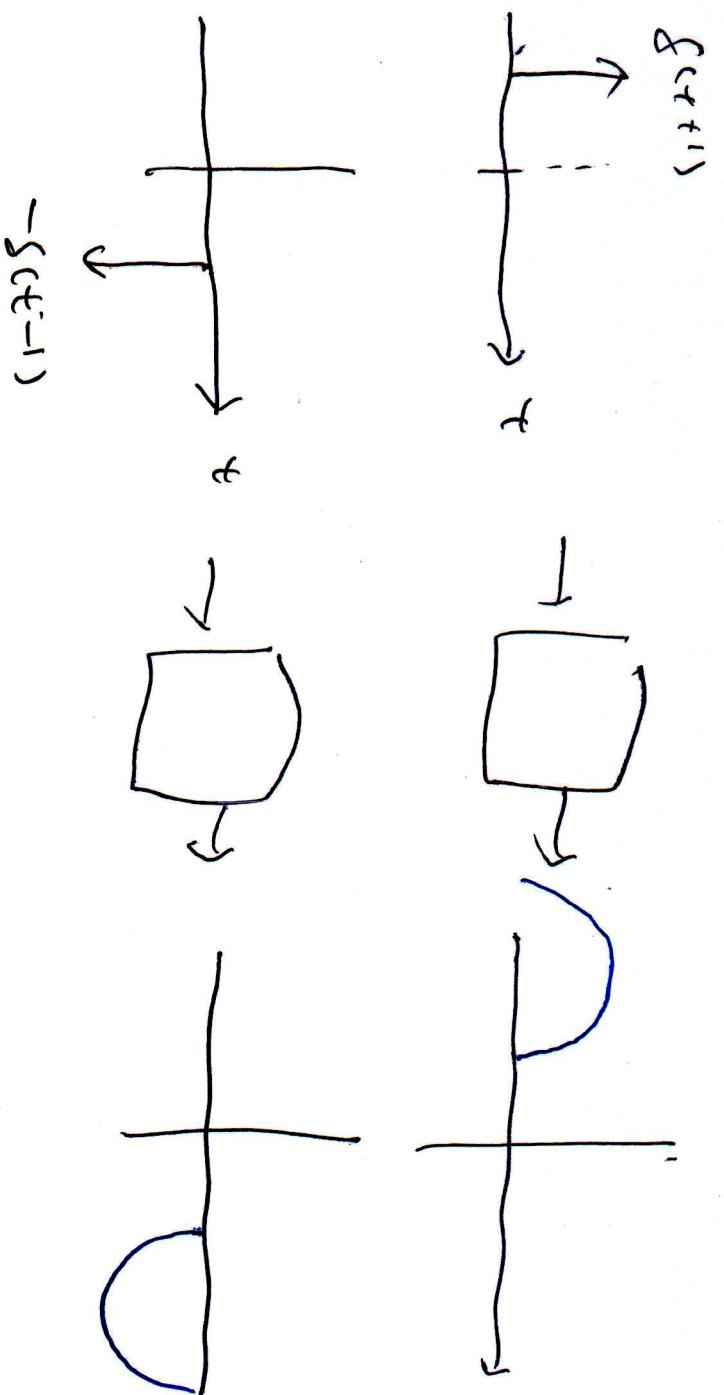
- (a) (5%) The impulse response of an LTI system is $h(t) = \begin{cases} \cos(\pi t), & |t| < 0.5 \\ 0, & \text{otherwise} \end{cases}$. Use linearity and time

invariance to determine and plot the output $y(t)$ for $x(t) = \delta(t+1) - \delta(t-1)$.

$$\delta(\tau)$$



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Problem 8

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二、(10%)

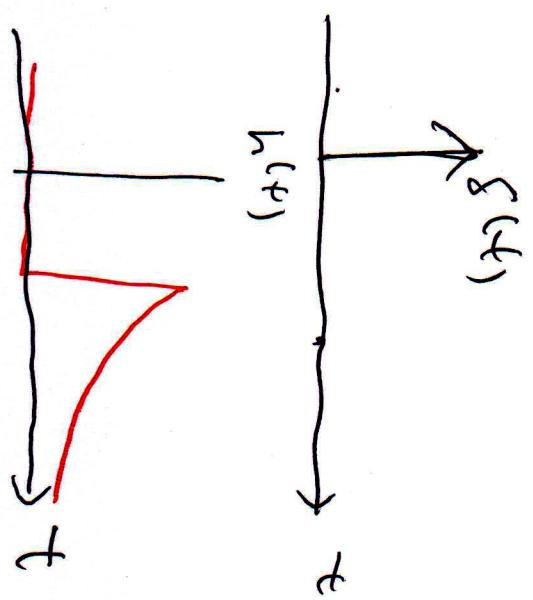
- (a) (5%) Consider [an] LTI system with input and output related through the equation:

$$y(t) = \int_{-\infty}^t e^{r-t} x(r-1) dr$$

The impulse response $h(t)$ for this system = _____. Is the system causal? Yes (simply answer yes or no)

$$\begin{aligned}
 h(t) &= \int_{-\infty}^t e^{\tau-t} \delta(\tau-1) d\tau \\
 &= \int_{-\infty}^t e^{\tau-t} \left[\int_{-\infty}^{\tau} \delta(\tau-1) d\tau \right] d\tau \\
 &= e^{-(t-1)} \left[\int_{-\infty}^t \delta(\tau-1) d\tau \right] \\
 &\quad \xrightarrow{\hspace{1cm}} \begin{cases} 0, & t < 1 \\ 1, & t \geq 1 \rightarrow u(t-1) \end{cases}
 \end{aligned}$$

11.



(12)

Problem 9

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(b)

- t · (15%) Consider the continuous-time LTI system with input $x(t)$, output $y(t)$ and impulse response $h(t)$, for which we are given the following information:

$$x(t) = 0, t > 0 \text{ and } X(s) = (s + 2)/(s - 2), \text{ and } y(t) = -\frac{2}{3}e^{2t}u(-t) + \frac{1}{3}e^{-t}u(t).$$

- (a) (10%) Determine the transfer function, $H(s)$, of the system (3%), its region of convergence (2%), and the impulse response $h(t)$ of the system (5%).
- (b) (5%) What is the output $y(t)$ if the input to the LTI system is $x(t) = e^{-3t}$, $-\infty < t < \infty$?

$$H(s) = \frac{Y(s)}{X(s)}$$

$$Y(t) = -\frac{2}{3}e^{-2t}u(-t) + \frac{1}{3}e^{-t}u(t)$$

$$Y(s) = \frac{-2}{s+2} - \frac{1}{s-2} + \frac{1}{s+1}$$

$$\text{Re}\{s\} < -2$$

$$\text{Re}\{s\} > -1$$

$$X(s) = \frac{s+2}{s-2} = \frac{s-2+t}{s-2} = 1 + \frac{4}{s-t+2}$$

$$x(t) = g(t) + 4(-1)e^{2t}u(-t)$$

$$H(s) = \frac{Y(s)}{X(s)} = \frac{\frac{1}{s} - \frac{1}{s+2} + \frac{1}{s+1}}{\frac{s+2}{s+1}}$$

$$= \frac{\cancel{s-2}}{(s+2)(s+1)} = \frac{\frac{2}{s}(s+1) + \frac{1}{s}(s-2)}{(s+2)(s+1)}$$

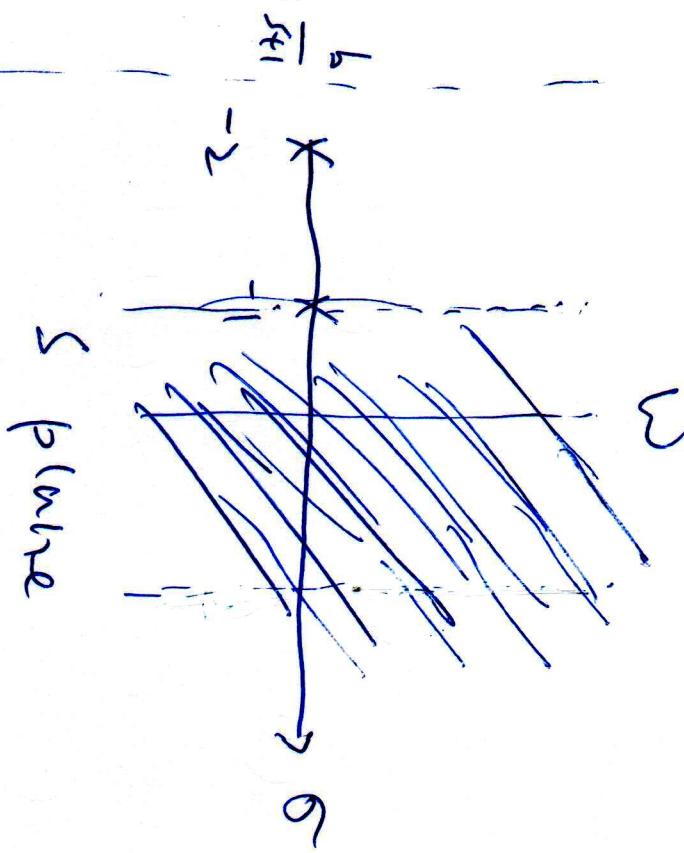
$$H(s) = \frac{s}{(s+2)(s+1)} = \frac{a}{s+2} + \frac{b}{s+1}$$

$$H(s) = \frac{2(s+1) - (s+2)}{(s+2)(s+1)} = \frac{(s+2)(s+1)}{(s+2)(s+1)}$$

$$H(s) = \frac{2}{s+2} - \frac{1}{s+1}$$

$$h(t) = 2 e^{-2t} u(t) - e^{-t} u(t)$$

$h(t)$



(14)

$$x(t) = e^{st} t$$

$$y(t) = H(s) e^{st}$$

$$x(t) = e^{-\beta t}$$

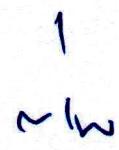
$$y(t) = H(-s) e^{-\beta t}$$



$$H(s) = \frac{(s+1)(s+2)}{s}$$

$$H(-\beta) = \frac{(-\beta+1)(-\beta+2)}{-\beta}$$

$$y(t) = -\frac{3}{2} e^{-3t}$$



Problem 10
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五、(5 pts) A continuous-time linear system S with input $x(t)$ and output $y(t)$ yields the following input-output pairs:

$$x(t) = e^{ju} \xrightarrow{s} y(t) = e^{ju} = \dots$$

$$x(t) = e^{-ju} \xrightarrow{s} y(t) = e^{-ju}$$

(一)(2 pts) Is this system linear time-invariant? Just simply answer yes or no.

Not linear system

$$e^{\int u} \xrightarrow{\square} e^{\int 3u}$$

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