

Homework #01

Problem 1

$$f_1 = 0.4$$

$$x_1(t) = \cos(2\pi f_1 t)$$

$$x_1[n] = \cos(2\pi f_1 n)$$

$$f_2 = 0.6$$

$$x_2(t) = \cos(2\pi f_2 t)$$

$$x_2[n] = \cos(2\pi f_2 n)$$

$$f_3 = 1.4$$

$$x_3(t) = \cos(2\pi f_3 t)$$

$$x_3[n] = \cos(2\pi f_3 n)$$

$$f_4 = 1.6$$

$$x_4(t) = \cos(2\pi f_4 t)$$

$$x_4[n] = \cos(2\pi f_4 n)$$

$x_1[n]$, $x_2[n]$, $x_3[n]$, and $x_4[n]$ are the point sampling of $x_1(t)$, $x_2(t)$, $x_3(t)$, and $x_4(t)$.

Use Matlab for the following questions.

($t=0:0.01:10$ and $n=0:1:10$)

- Plot $x_1(t)$ and $x_1[n]$ in figure 1.
- Plot $x_2(t)$ and $x_2[n]$ in figure 2.
- Plot $x_3(t)$ and $x_3[n]$ in figure 3.
- Plot $x_4(t)$ and $x_4[n]$ in figure 4.
- Plot $x_1(t)$, $x_2(t)$, $x_3(t)$, and $x_4(t)$ in figure 5.
- Plot $x_1[n]$, $x_2[n]$, $x_3[n]$, and $x_4[n]$ in figure 6.
- Observe (e) and (f), and discuss it.

Hint of Problem 1

Figure 1

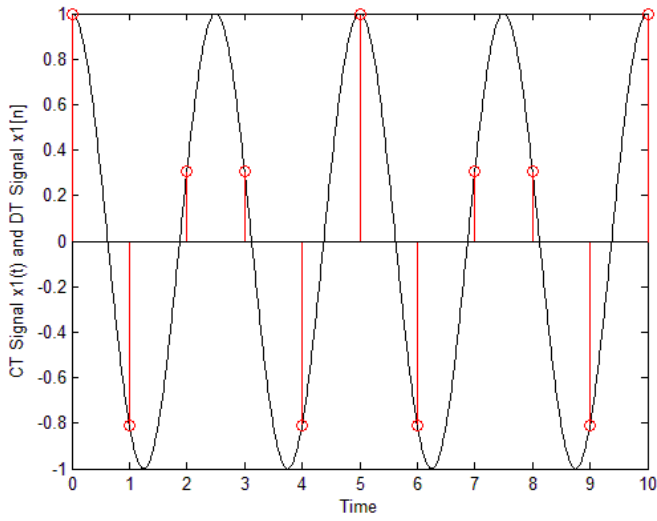


Figure 2

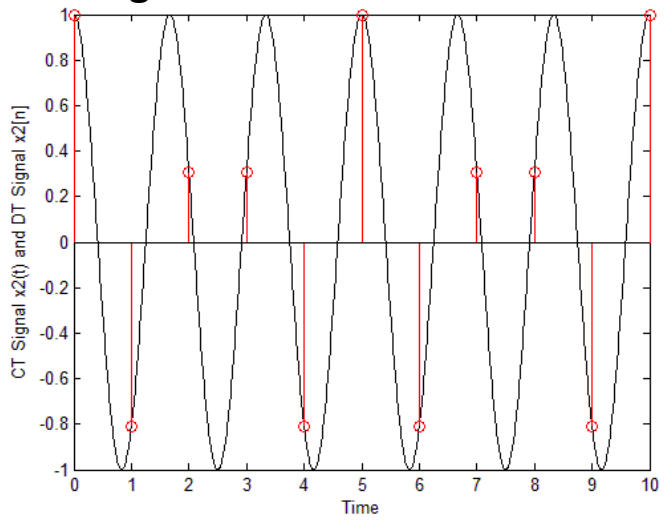


Figure 3

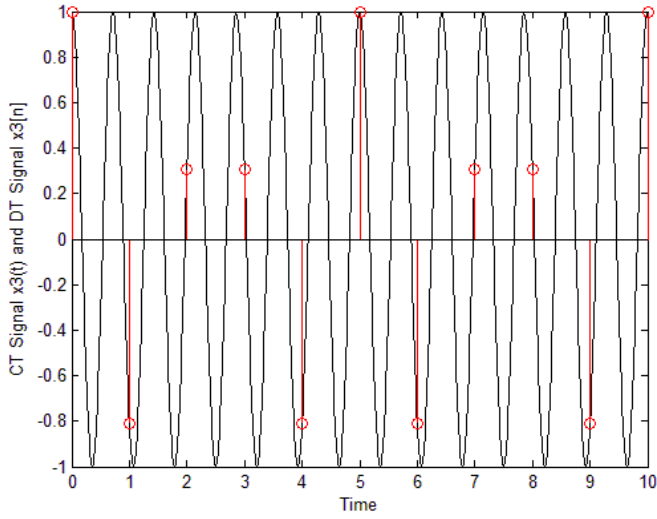


Figure 4

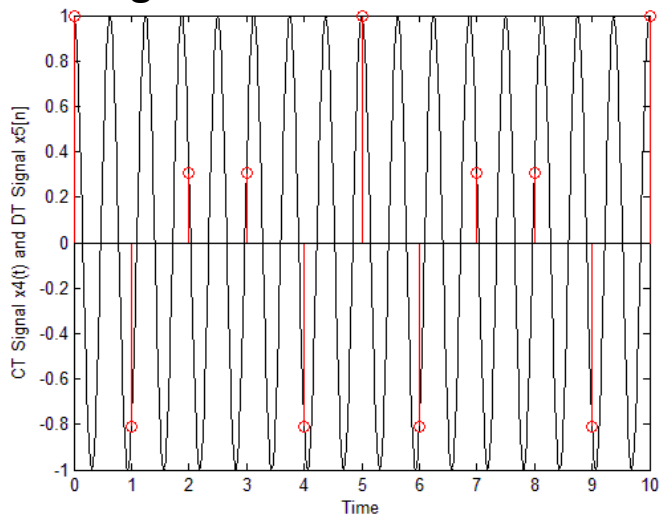


Figure 5

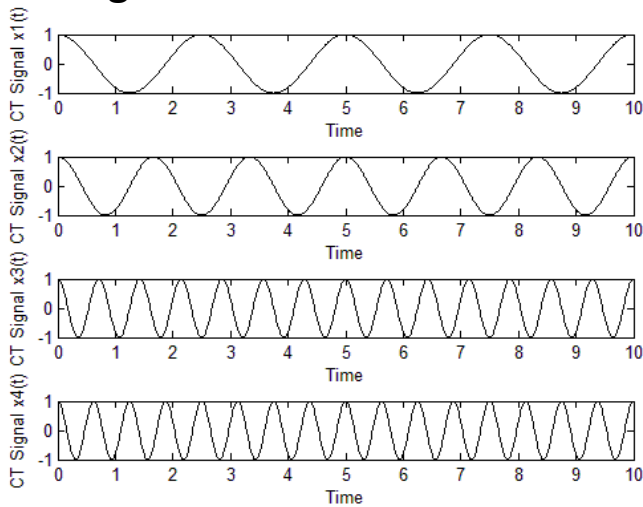


Figure 6

