

## Problem 1

$$e^{-at} u(t) \xleftrightarrow{\text{LT}} \frac{1}{s+a}, \text{ ROC: } \operatorname{Re}\{s\} > \operatorname{Re}\{a\}$$

$$h(t-a) \xleftrightarrow{\text{LT}} e^{-as} H(s), \text{ ROC: } R_h$$

$$\frac{d}{dt} h(t) \xleftrightarrow{\text{LT}} s H(s), \text{ ROC: } R_h$$

$$e^{-3(t)} u(t) \xleftrightarrow{\text{LT}} \frac{1}{s+3}, \text{ } \operatorname{Re}\{s\} > -3$$

$$e^{-3(t-2)} u(t-2) \xleftrightarrow{\text{LT}} e^{-2s} \frac{1}{s+3}, \text{ } \operatorname{Re}\{s\} > -3$$

$$\frac{d^2}{dt^2} \left( e^{-3(t-2)} u(t-2) \right) \xleftrightarrow{\text{LT}} s^2 e^{-2s} \frac{1}{s+3}, \text{ } \operatorname{Re}\{s\} > -3$$

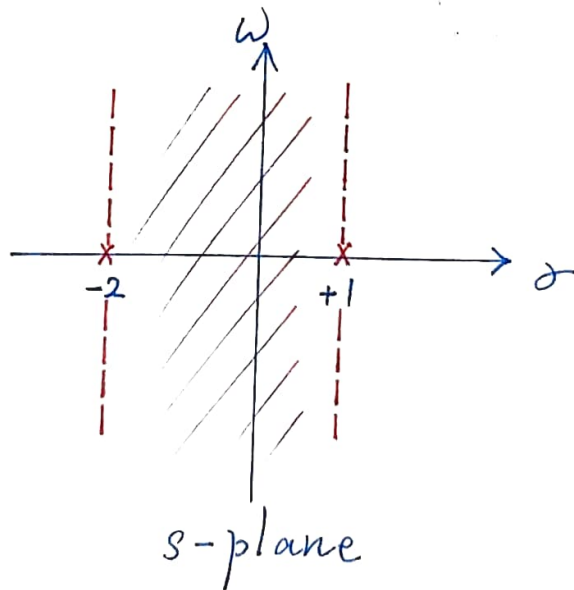
## Problem 2

$$y''(t) + y'(t) - 2y(t) = x(t)$$

$$s^2 Y(s) + s Y(s) - 2 Y(s) = X(s)$$

$$H(s) = \frac{Y(s)}{X(s)} = \frac{1}{s^2 + s - 2}$$
$$= \frac{1}{(s+2)(s-1)}$$

$$\text{ROC: } \operatorname{Re}\{s\} > -2, \operatorname{Re}\{s\} < 1$$



## Problem 2 (continued)

$$x(t) = \sum_{n=1}^{\infty} x_n(t)$$

$$x_n(t) = u(t-n)$$

$$X_n(s) = e^{-ns} \frac{1}{s}$$

$$y(t) = \sum_{n=1}^{\infty} y_n(t)$$

$$y_n(t) = ?$$

$$Y_n(s) = H(s) X_n(s)$$

## Problem 2 (continued)

$$Y_n(s) = H(s) X_n(s)$$

$$= \left[ \frac{1}{(s+2)(s-1)} \frac{1}{s} \right] e^{-ns}$$

$$= \left[ \frac{A}{s+2} + \frac{B}{s-1} + \frac{C}{s} \right] e^{-ns}$$

$$A = \frac{1}{6}$$

$$B = \frac{1}{3}$$

$$C = \frac{-1}{2}$$

$$Y_n(s) = \left[ \frac{\frac{1}{6}}{s+2} + \frac{\frac{1}{3}}{s-1} + \frac{\frac{-1}{2}}{s} \right] e^{-ns}$$

## Problem 2 (continued)

$$Y_n(s) = \frac{1}{6} e^{-ns} \frac{1}{s+2} + \frac{1}{3} e^{-ns} \frac{1}{s-1} + \frac{-1}{2} e^{-ns} \frac{1}{s}$$

$$y_n(t) = \frac{1}{6} e^{-2(t-n)} u(t-n) - \frac{1}{3} e^{t-n} u(-(t-n)) + \frac{-1}{2} u(t-n)$$

$$y(t) = \sum_{n=1}^{\infty} y_n(t)$$

### Problem 3

$$H(s) = \frac{A(s)}{1 + A(s)B(s)}$$

$$= \frac{\frac{s+2}{s^2+2s+4}}{1 + K \frac{s+2}{s^2+2s+4}}$$

$$= \frac{s+2}{(s^2+2s+4) + K(s+2)}$$

$$= \frac{s+2}{s^2 + (K+2)s + (2K+4)}$$

$$s^2 + (K+2)s + (2K+4) = 0$$

$$s = \frac{-(K+2) \pm \sqrt{(K+2)(K-6)}}{2}$$

### Problem 3 (continued)

$$\begin{aligned} \text{case } K < -2 & : -(K+2) > 0 \\ & + \sqrt{(K+2)(K-6)} > 0 \\ \Rightarrow \frac{-(K+2) + \sqrt{(K+2)(K-6)}}{2} & > 0 \\ & \text{unstable} \end{aligned}$$

$$\begin{aligned} \text{case } -2 < K < 6 & : -(K+2) < 0 \\ \text{Re} \left\{ \pm \sqrt{(K+2)(K-6)} \right\} & = 0 \\ \Rightarrow \text{Re} \left\{ \frac{-(K+2) \pm \sqrt{(K+2)(K-6)}}{2} \right\} & < 0 \\ & \text{stable} \end{aligned}$$

$$\begin{aligned} \text{case } 6 < K & : \\ & S \\ & = \frac{-(K+2) \pm \sqrt{(K+2)(K-6)}}{2} \\ & \leq \frac{-(K+2) + \sqrt{(K+2)(K-6)}}{2} \\ & < \frac{-(K+2) + \sqrt{(K+2)(K+2)}}{2} \\ & = 0 \\ & \text{stable} \end{aligned}$$

$\therefore$  smallest value of  $K$  is  $-2$

## Problem 4

一、  $x \rightarrow \square \rightarrow y$

$ax \rightarrow \square \rightarrow ay$

$x_1 \rightarrow \square \rightarrow y_1$

$x_2 \rightarrow \square \rightarrow y_2$

$x_1 + x_2 \rightarrow \square \rightarrow y_1 + y_2$

二、

causal : ROC 在最右邊 pole 的右邊

BIBO stability : ROC 包含虛軸

三、

$x \rightarrow [A] \rightarrow y$

$y = Ax = \lambda x$

$x = \text{eigenvector}$

$x(t) \rightarrow [h(t)] \rightarrow y(t)$

$y(t) = h(t) * x(t) = H(s)x(t)$

$x(t) = e^{st}$



## Problem 5

$$s^2 Y(s) + 2\beta s Y(s) + \omega_0^2 Y(s) = \alpha X(s)$$

$$H(s) = \frac{Y(s)}{X(s)} = \frac{\alpha}{s^2 + 2\beta s + \omega_0^2}$$

$$H(j\omega) = \frac{\alpha}{-\omega^2 + 2\beta j\omega + \omega_0^2}$$

$$= \frac{\alpha}{(\omega_0^2 - \omega^2) + j(2\beta\omega)}$$

## Problem 6

$$h(t) = e^{-t} u(t)$$

$$H(s) = \frac{1}{s+1}$$

$$x(t) = u(t+1) - u(t-1)$$

$$X(s) = \frac{1}{s} e^{+s} - \frac{1}{s} e^{-s}$$

$$y(t) = h(t) * x(t)$$

$$Y(s) = H(s) \times X(s)$$

$$= \frac{1}{s+1} \left( \frac{1}{s} e^s - \frac{1}{s} e^{-s} \right)$$

$$= \frac{1}{(s+1)s} e^s - \frac{1}{(s+1)s} e^{-s}$$

$$= \left( \frac{1}{s} - \frac{1}{s+1} \right) e^s - \left( \frac{1}{s} - \frac{1}{s+1} \right) e^{-s}$$

$$= \frac{1}{s} e^s - \frac{1}{s+1} e^s - \frac{1}{s} e^{-s} + \frac{1}{s+1} e^{-s}$$

$$y(t) = u(t+1) - e^{-(t+1)} u(t+1) - u(t-1) + e^{-(t-1)} u(t-1)$$

$$= u(t+1) [1 - e^{-(t+1)}] - u(t-1) [1 - e^{-(t-1)}]$$

# Problem 7

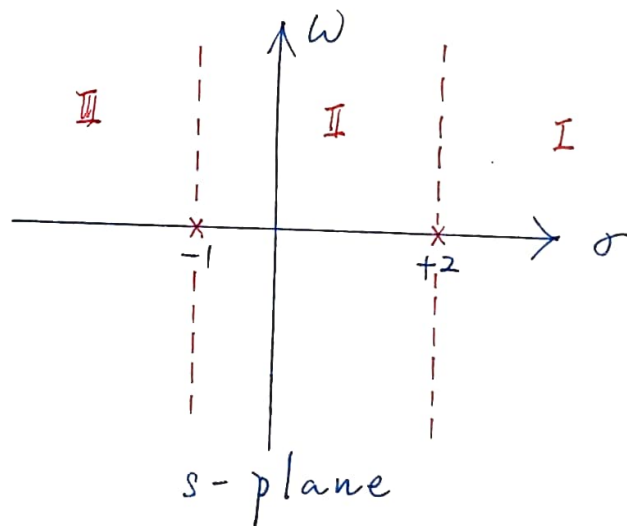
$$H(s) = \frac{s-1}{(s+1)(s-2)}$$

$$= \frac{A}{s+1} + \frac{B}{s-2}$$

$$A = \frac{2}{3}$$

$$B = \frac{1}{3}$$

$$H(s) = \frac{2}{3} \frac{1}{s+1} + \frac{1}{3} \frac{1}{s-2}$$



region III	region II	region I
$h(t) =$ $-\frac{2}{3}e^{-t}u(-t)$ $-\frac{1}{3}e^{2t}u(-t)$	$h(t) =$ $\frac{2}{3}e^{-t}u(t)$ $-\frac{1}{3}e^{2t}u(-t)$	$h(t) =$ $\frac{2}{3}e^{-t}u(t)$ $+\frac{1}{3}e^{2t}u(t)$
anti-causal unstable	noncausal stable	causal unstable

# Problem 8

$$\sin(\omega_0 t) u(t) \xleftrightarrow{\text{LT}} \frac{\omega_0}{s^2 + \omega_0^2}, \quad \text{Re}\{s\} > 0$$

$$\sin(5t) u(t) \xleftrightarrow{\text{LT}} \frac{5}{s^2 + 25}$$

$$\frac{1}{5} \sin(5t) u(t) \xleftrightarrow{\text{LT}} \frac{1}{s^2 + 25}$$

$$t^2 \frac{1}{5} \sin(5t) u(t) \xleftrightarrow{\text{LT}} \frac{d^2}{dt^2} \frac{1}{s^2 + 25}$$

$$t \cdot \frac{2}{5} \sin(5t) u(t)$$

+

$$t^2 \cdot \cos(5t) u(t)$$

+

$$t^2 \cdot \frac{1}{5} \sin(5t) \delta(t)$$

$$\xleftrightarrow{\text{LT}} s \frac{d^2}{dt^2} \frac{1}{s^2 + 25}, \quad \text{Re}\{s\} > 0$$

# Problem 9

$$h(t) = e \cdot e^{-(t+1)} u(t+1)$$

$$H(s) = e \cdot \frac{1}{s+1} \cdot e^s$$

$$= \frac{1}{s+1} e^{s+1}$$

$$x(t) = \sin^2 t$$

$$= \frac{1}{2} - \frac{1}{2} \cos 2t$$

$$= \frac{1}{2} - \frac{1}{2} \frac{e^{j2t} + e^{-j2t}}{2}$$

$$= \frac{1}{2} e^{0t} - \frac{1}{4} e^{(j2)t} - \frac{1}{4} e^{(-j2)t}$$

$$y(t) = \frac{1}{2} H(0) e^{0t} - \frac{1}{4} H(j2) e^{j2t} - \frac{1}{4} H(-j2) e^{-j2t}$$

$$= \frac{1}{2} \frac{1}{1} e^1 - \frac{1}{4} \frac{1}{j2+1} e^{j2+1} e^{j2t} - \frac{1}{4} \frac{1}{-j2+1} e^{-j2+1} e^{-j2t}$$

Problem 10

$$X(s) = \frac{(s+4)}{(s+2)(s^2+6s+13)}$$

$$= \frac{A}{s+2} + \frac{Bs+C}{s^2+6s+13}$$

$$s+4 = (s^2+6s+13)A + (s+2)(Bs+C)$$

$$= As^2+6As+13A + Bs^2+(2B+C)s+2C$$

$$0s^2+1s+4 = (A+B)s^2 + (6A+2B+C)s + 13A+2C$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 6 & 2 & 1 \\ 13 & 0 & 2 \end{pmatrix} \begin{pmatrix} A \\ B \\ C \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 4 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 0 & 0 \\ 6 & 2 & 1 & 1 \\ 13 & 0 & 2 & 4 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & -4 & 1 & 1 \\ 0 & -13 & 2 & 4 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & -4 & 1 & 1 \\ 0 & 0 & 5 & -3 \end{pmatrix}$$

$$5C = -3$$

$$C = -\frac{3}{5}$$

$$-4B + \frac{-3}{5} = 1$$

$$B = \frac{-2}{5}$$

$$A + \frac{-2}{5} = 0$$

$$A = \frac{2}{5}$$

$$X(s) = \frac{2}{5} \frac{1}{s+2} + \frac{-2s-3}{5(s^2+6s+13)}$$

$$x(t) = \frac{2}{5} \left( -e^{-2t} u(-t) \right) + \left( -\frac{2}{5} e^{-3t} \cos(2t) u(t) \right)$$

$$+ \left( \frac{3}{10} e^{-3t} \sin(2t) u(t) \right) \quad \text{選(B)}$$