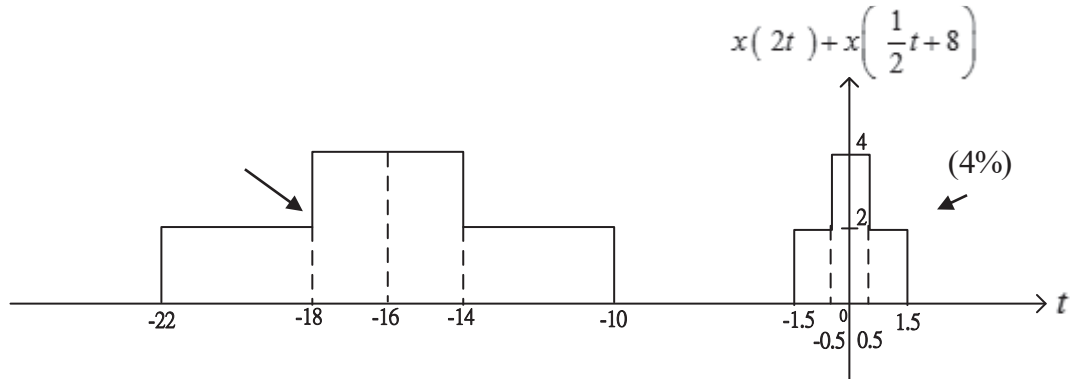


2018

1. Sketch the signal $x(2t) + x\left(\frac{1}{2}t + 8\right)$. (10%)



2. (15%)

(1) $y(t) = (\cos(\pi t))x(t)$

(i) memoryless: 輸出只與當時的輸入有關

(ii) causal

(iii) stable: $|y(t)| = |\cos(\pi t)x(t)| \leq M_x$

(iv) time-varying: $y(t) = H\{x(t)\} = \cos(\pi t)x(t)$
 $H\{x(t-t_0)\} = \cos(\pi t)x(t-t_0) \neq y(t-t_0)$

(v) linear: $ay_1(t) + by_2(t) = H\{ax_1(t) + bx_2(t)\}$

(2) $y[n] = x[n^2] 10$

(i) memory: 輸出與未來輸入有關

(ii) non-causal: 輸出與未來輸入有關

(iii) stable: $|y[n]| = |x[n^2]| \leq M_x$

(iv) time-varying: $y[n] = H\{x[n]\} = x[n^2]$
 $H\{x[n-1]\} = x[n^2 - 1] \neq y[n-1]$

(v) linear: $ay_1[n] + by_2[n] = H\{ax_1[n] + bx_2[n]\}$

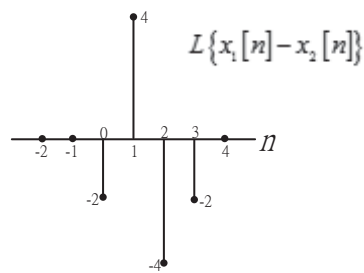
$$(3) \quad y[n] = x[n] \sum_{k=0}^{\infty} \delta[n-k] \Rightarrow \begin{cases} y[n] = 0 & \text{for } n < 0 \\ y[n] = x[n] & \text{for } n \geq 0 \end{cases}$$

- (i) memoryless: 輸出只與當時的輸入有關
- (ii) causal
- (iii) stable
- (iv) time-varying
- (v) linear: $ay_1[n] + by_2[n] = H\{ax_1[n] + bx_2[n]\}$

3. (15%)

(1)

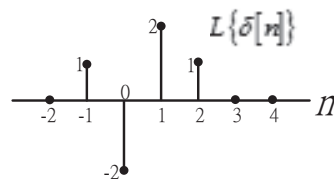
$$L\{x_1[n] - x_2[n]\} = y_1[n] - y_2[n]$$



(2)

$$\delta[n] = \frac{1}{2}x_1[n] - \frac{1}{2}x_2[n] + x_3[n]$$

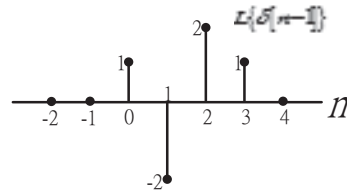
$$L\{\delta[n]\} = \frac{1}{2}y_1[n] - \frac{1}{2}y_2[n] + y_3[n]$$



(3)

$$\delta[n-1] = -\frac{1}{2}(x_1[n] - x_2[n])$$

$$L\{\delta[n-1]\} = -\frac{1}{2}(y_1[n] - y_2[n])$$



If the input $\delta[n]$ delay 1 unit, the output $L\{\delta[n]\}$ also delay 1 unit.

The system is time-invariant.

4.

$$y[n] - y[n-1] + \frac{1}{4}y[n-2] = \frac{1}{2}x[n], \quad y[-1] = 1, \quad y[-2] = 0.$$

$$\Rightarrow y^{(h)}[n] = c_1\left(\frac{1}{2}\right)^n + c_2n\left(\frac{1}{2}\right)^n$$

(1) (7%)

$$\because x[n] = u[n] \therefore y^{(p)}[n] = A$$

$$\because y^{(p)}[n] - y^{(p)}[n-1] + \frac{1}{4}y^{(p)}[n-2] = \frac{1}{2}u[n]$$

$$\therefore A = 2 \Rightarrow y[n] = c_1\left(\frac{1}{2}\right)^n + c_2n\left(\frac{1}{2}\right)^n + 2u[n].$$

$$\because y[0] = \frac{3}{2}, \quad y[1] = \frac{7}{4} \therefore c_1 = \frac{-1}{2}, \quad c_2 = 0.$$

$$\Rightarrow y[n] = \frac{-1}{2}\left(\frac{1}{2}\right)^n + 2u[n].$$

(2) (8%)

$$y^{(n)}[n] = c_1\left(\frac{1}{2}\right)^n + c_2n\left(\frac{1}{2}\right)^n, \quad y[-1] = 1, \quad y[-2] = 0 \Rightarrow$$

$$c_1 = 1, \quad c_2 = \frac{1}{2} \Rightarrow y^{(n)}[n] = \left(\frac{1}{2}\right)^n + \frac{1}{2}n\left(\frac{1}{2}\right)^n.$$

$$y^{(f)}[n] = c_1 \left(\frac{1}{2}\right)^n + c_2 n \left(\frac{1}{2}\right)^n + 2u[n], \quad y[-1] = y[-2] = 0 \Rightarrow$$

$$y[0] = \frac{1}{2}, \quad y[1] = 1 \Rightarrow c_1 = \frac{-3}{2}, \quad c_2 = \frac{-1}{2} \Rightarrow$$

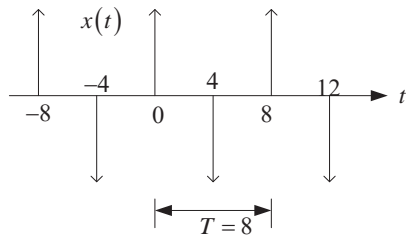
$$y^{(f)}[n] = \frac{-3}{2} \left(\frac{1}{2}\right)^n + \frac{-1}{2} n \left(\frac{1}{2}\right)^n + 2u[n].$$

5.

(10%)

(1)

Periodic, $T = 8$.



(2)

Periodic, $T_0 = \frac{2\pi}{10}$

(3)

Periodic, $N=8$

6.

(10%)

$$y(t) = 0, t < 0.5$$

$$2 \int_{-0.5}^{t-1} \cos(\pi\tau) d\tau = \frac{2}{\pi} \left\{ \sin[\pi(t-1)] + 1 \right\}, 0.5 \leq t < 2.5$$

$$2 \int_{-3+t}^{1.5} \cos(\pi\tau) d\tau = \frac{2}{\pi} \left\{ -\sin[\pi(t-3)] - 1 \right\}, 2.5 \leq t < 4.5$$

$$y(t) = 0, t > 4.5$$

7.

Homogeneous solution: $r^2 - 5r + 6 = 0 \Rightarrow r = 2, r = 3 \Rightarrow y^{(h)} = c_1 e^{2t} + c_2 e^{3t}$

(1) (6%)

$$y_p(t) = A \cos(3t) + B \sin(3t),$$

$$y_p'(t) = -3A \sin(3t) + 3B \cos(3t),$$

$$y_p''(t) = -9A \cos(3t) - 9B \sin(3t),$$

$$A = \frac{5}{39}, B = \frac{-1}{39}$$

$$\Rightarrow \therefore y_p(t) = \frac{-1}{39} \sin(3t) + \frac{5}{39} \cos(3t).$$

(2) (7%)

$$y_p(t) = Ate^{3t} + Bte^{2t},$$

$$y_p'(t) = Ae^{3t} + 3Ate^{3t} + Be^{2t} + 2Bte^{2t},$$

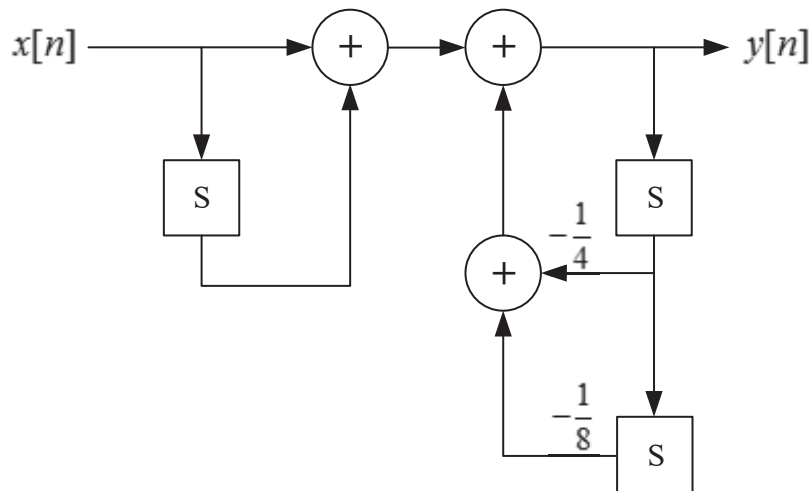
$$y_p''(t) = 6Ae^{3t} + 9Ate^{3t} + 2Be^{2t} + 4Bte^{2t},$$

$$A = 2, B = -2$$

$$\Rightarrow \therefore y_p(t) = 2te^{3t} - 2te^{2t}.$$

8. (12%)

(1)

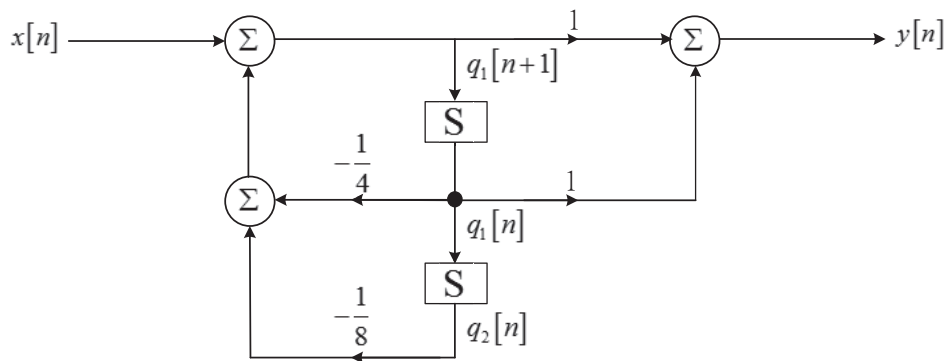


$$(I) \quad y[n] + \frac{1}{4}y[n-1] + \frac{1}{8}y[n-2] = x[n] + x[n-1]$$

or

$$(II) \quad y[n] = x[n] + x[n-1] - \frac{1}{4}y[n-1] - \frac{1}{8}y[n-2]$$

(2)



$$q_1[n+1] = -\frac{1}{4}q_1[n] - \frac{1}{8}q_2[n] + x[n]$$

$$q_2[n+1] = q_1[n]$$

$$y[n] = \frac{3}{4}q_1[n] - \frac{1}{8}q_2[n] + x[n]$$

$$\mathbf{A} = \begin{bmatrix} -\frac{1}{4} & -\frac{1}{8} \\ 1 & 0 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \quad \mathbf{c} = \begin{bmatrix} \frac{3}{4} & -\frac{1}{8} \end{bmatrix}, \quad D = 1$$

