

Reference Solution of Midterm Exam II

1. $T = 6, \omega_0 = \frac{2\pi}{T} = \frac{\pi}{3}$

$$\begin{aligned}
 a_k &= \frac{1}{T} \int_T x(t) e^{-jk\omega_0 t} dt = \frac{1}{6} \int_{-3}^3 x(t) e^{-jk\omega_0 t} dt \\
 &= \frac{1}{6} \int_{-2}^{-1} e^{-jk\omega_0 t} dt - \frac{1}{6} \int_1^2 e^{-jk\omega_0 t} dt \\
 &= \frac{1}{6} \cdot \frac{1}{-jk\omega_0} (e^{jk\omega_0} - e^{j2k\omega_0}) - \frac{1}{6} \cdot \frac{1}{-jk\omega_0} (e^{-j2k\omega_0} - e^{-jk\omega_0}) \\
 &= \frac{j}{6k\omega_0} (e^{jk\omega_0} + e^{-jk\omega_0} - e^{j2k\omega_0} - e^{-j2k\omega_0}) \\
 &= \frac{j}{\pi k} [\cos(\frac{\pi k}{3}) - \cos(\frac{2\pi k}{3})] \quad (6\%) \\
 a_0 &= \frac{1}{6} \int_{-3}^3 x(t) e^{-j0\omega_0 t} dt = 0 \quad (4\%)
 \end{aligned}$$

2. 3 points for each subproblem

(1) $\int_{-\infty}^{\infty} X(j\omega) d\omega = 2\pi x(0) = 0$

(2) $\int_{-\infty}^{\infty} |X(j\omega)|^2 d\omega = 2\pi \int_{-\infty}^{\infty} |x(t)|^2 dt = 4\pi \int_1^4 |t-1|^2 dt = 4\pi \cdot 9 = 36\pi$

(3) $\int_{-\infty}^{\infty} X(j\omega) e^{j2\omega} d\omega = 2\pi x(2) = 2\pi$

(4)
 $\because x(t)$ is real and even

$$\therefore \text{Im } X(j\omega) \neq 0 \Leftrightarrow \left\{ \begin{array}{l} \text{Im } X(j\omega) \\ \text{Re } X(j\omega) \end{array} \right\} \neq 0$$

3.

(1) (3%)

$$Y(e^{j\Omega}) - \frac{3}{4} e^{-j\Omega} Y(e^{j\Omega}) + \frac{1}{8} e^{-j2\Omega} Y(e^{j\Omega}) = 2X(e^{j\Omega})$$

$$Y(e^{j\Omega}) \left(1 - \frac{3}{4} e^{-j\Omega} + \frac{1}{8} e^{-j2\Omega}\right) = 2X(e^{j\Omega})$$

$$H(e^{j\Omega}) = \frac{2}{1 - \frac{3}{4} e^{-j\Omega} + \frac{1}{8} e^{-j2\Omega}}$$

(2) (4%)

$$H(e^{j\Omega}) = \frac{2}{1 - \frac{3}{4}e^{-j\Omega} + \frac{1}{8}e^{-j2\Omega}} = \frac{2}{(1 - \frac{1}{2}e^{-j\Omega})(1 - \frac{1}{4}e^{-j\Omega})} = \frac{4}{1 - \frac{1}{2}e^{-j\Omega}} - \frac{2}{1 - \frac{1}{4}e^{-j\Omega}}$$

$$h[n] = 4(\frac{1}{2})^n u[n] - 2(\frac{1}{4})^n u[n]$$

(3) (5%)

$$X(e^{j\Omega}) = \frac{1}{1 - \frac{1}{2}e^{-j\Omega}}$$

$$Y(e^{j\Omega}) = X(e^{j\Omega})H(e^{j\Omega}) = \frac{2}{(1 - \frac{1}{2}e^{-j\Omega})^2(1 - \frac{1}{4}e^{-j\Omega})} = \frac{-4}{1 - \frac{1}{2}e^{-j\Omega}} + \frac{4}{(1 - \frac{1}{2}e^{-j\Omega})^2} + \frac{2}{1 - \frac{1}{4}e^{-j\Omega}}$$

$$y[n] = -4(\frac{1}{2})^n u[n] + 4(n+1)(\frac{1}{2})^n u[n] + 2(\frac{1}{4})^n u[n] = 4n(\frac{1}{2})^n u[n] + 2(\frac{1}{4})^n u[n]$$

4. (10%)

$$x[n] = \sin(\frac{\pi n}{4}) + \cos(\frac{\pi n}{2}) = \frac{1}{2j}(e^{j\frac{\pi n}{4}} - e^{-j\frac{\pi n}{4}}) + \frac{1}{2}(e^{j\frac{\pi n}{2}} + e^{-j\frac{\pi n}{2}})$$

$$y[n] = \frac{1}{2j}[H(e^{j\frac{\pi}{4}})e^{j\frac{\pi n}{4}} - H(e^{-j\frac{\pi}{4}})e^{-j\frac{\pi n}{4}}] + \frac{1}{2}[H(e^{j\frac{\pi}{2}})e^{j\frac{\pi n}{2}} - H(e^{-j\frac{\pi}{2}})e^{-j\frac{\pi n}{2}}]$$

$$= \frac{1}{2j}[2(1+j)e^{j\frac{\pi n}{4}} - 2(1-j)e^{-j\frac{\pi n}{4}}] + \frac{1}{2}[\frac{4}{3}e^{j\frac{\pi n}{2}} - \frac{4}{3}e^{-j\frac{\pi n}{2}}]$$

$$= 2\sin(\frac{\pi n}{4}) + 2\cos(\frac{\pi n}{4}) + \frac{4}{3}\cos(\frac{\pi n}{2})$$

5.

$$x[n] = n(\frac{1}{2})^{|n|} \quad \xleftrightarrow{DTFT} \quad X(e^{j\Omega})$$

real, odd pure imaginary

(1) (3%)

$$Y(e^{j\Omega}) = \operatorname{Re}\{X(e^{j\Omega})\} = 0 \Rightarrow y[n] = 0$$

(2) (3%)

$$y[n] = -jnx[n] = -jn^2(1/2)^{|n|}.$$

(3) (4%)

$$y[n] = 2\pi \left[x[n](e^{j\frac{\pi n}{2}} x[n]) \right] = 2\pi n^2 (1/2)^{2|n|} e^{j\frac{\pi n}{2}}.$$

6.

$$x[n] = 2\delta[n] + \delta[n-1] + \delta[n-3]$$

(1) (4%)

$$X[k] = 2 + e^{-j\frac{2\pi}{5}k} + e^{-j3\frac{2\pi}{5}k}.$$

(2) (4%)

$$\begin{aligned} Y[k] &= X^2[k] = 4 + 4e^{-j\frac{2\pi}{5}k} + e^{-j2\frac{2\pi}{5}k} + 4e^{-j3\frac{2\pi}{5}k} + 2e^{-j4\frac{2\pi}{5}k} + e^{-j6\frac{2\pi}{5}k} \\ &= 4 + 5e^{-j\frac{2\pi}{5}k} + e^{-j2\frac{2\pi}{5}k} + 4e^{-j3\frac{2\pi}{5}k} + 2e^{-j4\frac{2\pi}{5}k} \\ \Rightarrow y[n] &= 4\delta[n] + 5\delta[n-1] + \delta[n-2] + 4\delta[n-3] + 2\delta[n-4] \end{aligned}$$

(3) (4%)

Not equal, N should be more than or equal to 7 such that

$$z[n] = x[n] * x[n] = IDFT\{X^2[k]\} = x[n] \otimes x[n]$$

7.

(1) (4%)

$$\begin{aligned} H_1(e^{j\Omega}) &= |A(e^{j\Omega})|e^{-j\alpha\Omega}, \quad H_2(e^{j\Omega}) = |B(e^{j\Omega})|e^{-j\beta\Omega} \\ H_3(e^{j\Omega}) &= H_1(e^{j\Omega})H_2(e^{j\Omega}) = |A(e^{j\Omega})||B(e^{j\Omega})|e^{-j(\alpha+\beta)\Omega} \\ \angle H_3(e^{j\Omega}) &= -(\alpha + \beta)\Omega \Rightarrow \text{is linearly proportional to } \Omega \end{aligned}$$

A cascade system of two linear phase systems is linear phase.

(2) (4%)

$$\begin{aligned} H_4(e^{j\Omega}) &= H_1(e^{j\Omega}) + H_2(e^{j\Omega}) = |A(e^{j\Omega})|e^{-j\alpha\Omega} + |B(e^{j\Omega})|e^{-j\beta\Omega} \\ \angle H_4(e^{j\Omega}) &\neq -(\alpha + \beta)\Omega \end{aligned}$$

A parallel system of two linear phase systems is not linear phase.

8. (10%)

$$a_k = \frac{1}{N} \sum_{n=\langle N \rangle} x[n] e^{-j\frac{2\pi k}{N} n}, \quad N = 7$$

$$\begin{aligned} a_k &= \frac{1}{7} \sum_{n=0}^6 (\delta[n] + \delta[n-3] - \delta[n-4]) e^{-j\frac{2\pi k}{7} n} \\ &= \frac{1}{7} (1 + e^{-j\frac{6\pi k}{7}} - e^{-j\frac{8\pi k}{7}}) \end{aligned}$$

9.

(1)

$$\begin{aligned} H(j\omega) &= \frac{Y(j\omega)}{X(j\omega)} = \frac{j\omega + 4}{6 + 5j\omega + (j\omega)^2} \\ \Rightarrow 6Y(j\omega) + 5(j\omega)Y(j\omega) + (j\omega)^2 Y(j\omega) &= (j\omega)X(j\omega) + 4X(j\omega) \\ \Rightarrow \frac{d^2y(t)}{dt^2} + 5\frac{dy(t)}{dt} + 6y(t) &= \frac{dx(t)}{dt} + 4x(t) \end{aligned}$$

(2)

$$\begin{aligned} H(j\omega) &= \frac{j\omega + 4}{6 + 5j\omega + (j\omega)^2} = \frac{A}{j\omega + 2} + \frac{B}{j\omega + 3} \\ A &= \left. \frac{j\omega + 4}{j\omega + 3} \right|_{j\omega=-2} = 2, \quad B = \left. \frac{j\omega + 4}{j\omega + 2} \right|_{j\omega=-3} = -1 \\ \Rightarrow H(j\omega) &= \frac{2}{j\omega + 2} + \frac{-1}{j\omega + 3} \\ \Rightarrow h(t) &= 2e^{-2t}u(t) - e^{-3t}u(t) \end{aligned}$$

(3)

$$\begin{aligned} x(t) = e^{-4t}u(t) - te^{-4t}u(t) &\leftrightarrow X(j\omega) = \frac{j\omega + 3}{(j\omega + 4)^2} \\ Y(j\omega) = H(j\omega)X(j\omega) &= \frac{j\omega + 4}{(j\omega + 2)(j\omega + 3)} \cdot \frac{j\omega + 3}{(j\omega + 4)^2} \\ &= \frac{1}{(j\omega + 2)(j\omega + 4)} = \frac{C}{j\omega + 2} + \frac{D}{j\omega + 4} \\ C &= \left. \frac{1}{j\omega + 4} \right|_{j\omega=-2} = \frac{1}{2}, \quad D = \left. \frac{1}{j\omega + 2} \right|_{j\omega=-4} = -\frac{1}{2} \\ \Rightarrow Y(j\omega) &= \frac{0.5}{j\omega + 2} + \frac{-0.5}{j\omega + 4} \\ \Rightarrow y(t) &= \frac{1}{2}e^{-2t}u(t) - \frac{1}{2}e^{-4t}u(t) \end{aligned}$$

10.

(1) Impulse train in time domain \xleftrightarrow{F} Impulse train in frequency domain

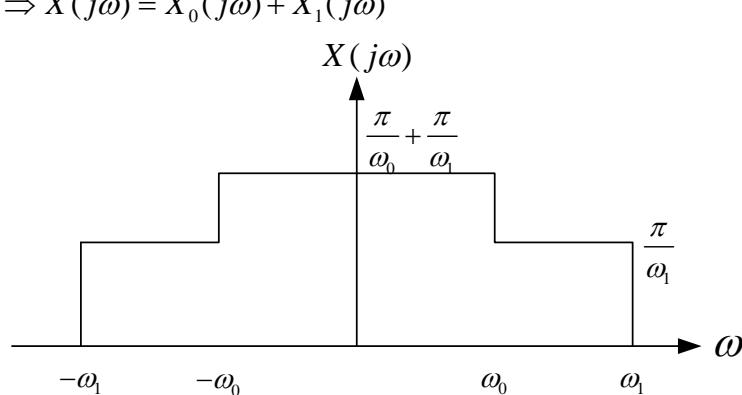
$$\begin{aligned} p(t) &= \sum_{k=-\infty}^{\infty} \delta(t - kT) = \sum_{k=-\infty}^{\infty} a_k e^{j\omega_0 t} \\ a_k &= \frac{1}{T} \int_{-T/2}^{T/2} \delta(t) e^{-j\omega_0 t} dt = \frac{1}{T} \Rightarrow p(t) = \frac{1}{T} \sum_{k=-\infty}^{\infty} e^{j\omega_0 t} \\ \Rightarrow P(j\omega) &= \frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta(\omega - k\omega_0) = \frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta(\omega - \frac{2\pi k}{T}) \end{aligned}$$

(2) From the given table

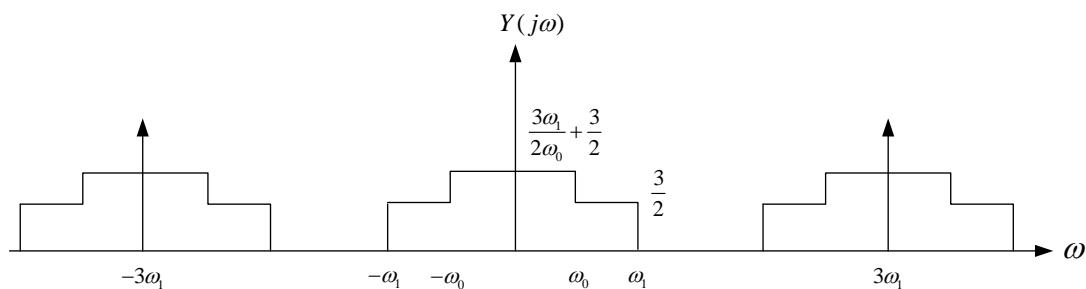
$$x(t) = x_0(t) + x_1(t) = \frac{\sin(\omega_0 t)}{\omega_0 t} + \frac{\sin(\omega_1 t)}{\omega_1 t}$$

$$X_0(j\omega) = \begin{cases} \frac{\pi}{|\omega_0|}, & |\omega| < \omega_0 \\ 0, & o.w. \end{cases}, \quad X_1(j\omega) = \begin{cases} \frac{\pi}{|\omega_1|}, & |\omega| < \omega_1 \\ 0, & o.w. \end{cases}$$

$$\Rightarrow X(j\omega) = X_0(j\omega) + X_1(j\omega)$$



(3)



Yes, it can be recovered from $y(t)$ because there is no aliasing in the spectrum.

(4)

$$T_{\max} = T_1 / 2$$