

Homework No. 8 Solution

1.

$$(1) \quad x(t) = \frac{d^2}{dt^2} \left(e^{-3(t-2)} u(t-2) \right) \quad (10\%)$$

$$e^{-3t} u(t) \xrightarrow{\mathcal{L}} \frac{1}{s+3}, \text{ with ROC } \operatorname{Re}\{s\} > -3$$

$$e^{-3(t-2)} u(t-2) \xrightarrow{\mathcal{L}} \frac{1}{s+3} e^{-2s}, \text{ with ROC } \operatorname{Re}\{s\} > -3$$

$$x(t) = \frac{d^2}{dt^2} \left(e^{-3(t-2)} u(t-2) \right) \xrightarrow{\mathcal{L}} X(s) = \frac{s^2}{s+3} e^{-2s}, \text{ with ROC } \operatorname{Re}\{s\} > -3$$

$$(2) \quad X(s) = s^{-1} \frac{d}{ds} \left(\frac{e^{-3s}}{s} \right) \text{ with ROC } \operatorname{Re}\{s\} > 0 \quad (10\%)$$

$$A(s) = \frac{1}{s} \xrightarrow{\mathcal{L}} a(t) = u(t)$$

right-sided

$$B(s) = e^{-3s} A(s) \xrightarrow{\mathcal{L}} b(t) = a(t-3) = u(t-3)$$

$$C(s) = \frac{d}{ds} B(s) \xrightarrow{\mathcal{L}} c(t) = -tb(t) = -tu(t-3)$$

$$X(s) = \frac{1}{s} C(s) \xrightarrow{\mathcal{L}} \begin{aligned} x(t) &= u(t) * c(t) = \int_{-\infty}^t c(\tau) d\tau = -\int_3^t \tau d\tau \\ &= -\frac{1}{2} (t^2 - 9) u(t-3) \quad (\because u(t) * c(t), 3 \leq t < \infty). \end{aligned}$$

$$2. \quad X(s) = \frac{-s-4}{s^2+3s+2} = \frac{-3}{s+1} + \frac{2}{s+2}$$

$$(1) \quad \text{With ROC } \operatorname{Re}\{s\} < -2$$

$$\text{Left-sided: } x(t) = (3e^{-t} - 2e^{-2t}) u(-t). \quad (5\%)$$

$$(2) \quad \text{With ROC } \operatorname{Re}\{s\} > -1$$

$$\text{Right-sided: } x(t) = (-3e^{-t} + 2e^{-2t}) u(t). \quad (5\%)$$

$$(3) \quad \text{With ROC } -2 < \operatorname{Re}\{s\} < -1$$

$$\text{Two-sided: } x(t) = 3e^{-t} u(-t) + 2e^{-2t} u(t). \quad (5\%)$$

$$3. \quad H(s) = \frac{2s^2 + 2s - 2}{s^2 - 1} = 2 + \frac{1}{s+1} + \frac{1}{s-1}$$

$$(a) \quad \text{Causal system: } h(t) = 2\delta(t) + (e^{-t} + e^t) u(t). \quad (5\%)$$

$$(b) \quad \text{Stable system: } h(t) = 2\delta(t) + e^{-t} u(t) - e^t u(-t). \quad (5\%)$$

4.

zero at: -5

poles at: $-1 \pm 3j$

- (1) All poles are in the left half of s-plane, and with ROC: $\text{Re}\{s\} > -1$, the system is both stable and causal. (7%)
- (2) All zeros are in the left half of s-plane, so a stable and causal inverse system exists. (8%)

5.

(1) $x(t) = u(t) - u(t-6) \Rightarrow X(s) = \int_0^6 e^{-st} dt = \frac{1-e^{-6s}}{s}$. (10%)

(2)

$$\begin{aligned} X(s) &= \int_0^1 \frac{1}{2j} (e^{j\pi t} - e^{-j\pi t}) e^{-st} dt \\ &= \frac{1}{2j} \left[\frac{1}{j\pi - s} (e^{j\pi - s} - 1) - \frac{1}{-j\pi - s} (e^{-j\pi - s} - 1) \right] \\ &= \frac{1}{2j} \left[\frac{1}{j\pi - s} (-e^{-s} - 1) + \frac{1}{j\pi + s} (-e^{-s} - 1) \right] \\ &= \frac{1}{2j} \frac{(-e^{-s} - 1)(j\pi + s + j\pi - s)}{-\pi^2 - s^2} = \frac{\pi(1 + e^{-s})}{s^2 + \pi^2}. \end{aligned} \quad (10\%)$$

6.

(1) $x(t-1) \xrightarrow{\mathcal{L}} e^{-s} X(s) = e^{-s} \frac{2s}{s^2 + 2}$. (5%)

(2) $x(t) * \frac{d}{dt} x(t)$

$$b(t) = \frac{d}{dt} x(t) \xrightarrow{\mathcal{L}} B(s) = sX(s)$$

$$y(t) = x(t) * b(t) \xrightarrow{\mathcal{L}} Y(s) = X(s)B(s) = sX^2(s) = s \left(\frac{2s}{s^2 + 2} \right)^2. \quad (5\%)$$

(3) $e^{-3t} x(t) \xrightarrow{\mathcal{L}} X(s+3) = \frac{2(s+3)}{(s+3)^2 + 2}$. (5%)

(4) $\int_0^t x(3\tau) d\tau \xrightarrow{\mathcal{L}} Y(s) = \frac{X(s/3)}{3s} = \frac{2}{s^2 + 18}$. (5%)