

Homework No. 8 Solution

1. (5%)

$$\begin{aligned}\int_{-\infty}^{\infty} e^{-10|t|} e^{-(\sigma+j\omega)t} dt &= \int_{-\infty}^0 e^{10t} e^{-(\sigma+j\omega)t} dt + \int_0^{\infty} e^{-10t} e^{-(\sigma+j\omega)t} dt \\ &= \int_{-\infty}^0 e^{-(10+\sigma)t} e^{-j\omega t} dt + \int_0^{\infty} e^{-(10+\sigma)t} e^{-j\omega t} dt\end{aligned}$$

The first integral converges for $-10 + \sigma < 0 \Rightarrow \sigma < 10$. The second integral converges if $10 + \sigma > 0 \Rightarrow \sigma > -10$. Therefore, the given integral converges when $|\sigma| < 10$.

2.

(1) $x(t) = e^{-t}u(t+3)$ (7%)

$$\begin{aligned}X(s) &= \int_{-\infty}^{\infty} e^{-t}u(t+3)e^{-st} dt = \int_{-3}^{\infty} e^{-t} e^{-st} dt \\ &= \int_{-3}^{\infty} e^{-t(1+s)} dt = \frac{-e^{-t(1+s)}}{1+s} \Bigg|_{-3}^{\infty} = \frac{e^{3(1+s)}}{1+s}, \quad \text{Re}\{s+1\} > 0 \Rightarrow \text{ROC} : \text{Re}\{s\} > -1\end{aligned}$$

(2) $x(t) = \sin(t)u(t)$ (8%)

$$\begin{aligned}X(s) &= \int_0^{\infty} \frac{1}{2j} (e^{jt} - e^{-jt}) e^{-st} dt = \int_0^{\infty} \frac{1}{2j} e^{t(j-s)} dt - \int_0^{\infty} \frac{1}{2j} e^{-t(j+s)} dt \\ &= \frac{1}{2j} \left(\frac{-1}{j-s} - \frac{1}{j+s} \right) = \frac{1}{1+s^2} \\ \text{Re}\{j-s\} < 0 \text{ and } \text{Re}\{j+s\} > 0 &\Rightarrow \text{ROC} : \text{Re}\{s\} > 0\end{aligned}$$

3.

(1) $X(s) = e^{5s} \frac{1}{s+3}$ with ROC $\text{Re}\{s\} < -3$ (7%)

$$\begin{aligned}A(s) &= \frac{1}{s+3} \xleftarrow{\mathcal{L}} a(t) = -e^{-3t}u(-t) \\ &\quad \text{left-sided} \\ X(s) &= e^{5s} A(s) \xleftarrow{\mathcal{L}} x(t) = a(t+5) = -e^{-3(t+5)}u(-t-5)\end{aligned}$$

(2) $X(s) = s^{-1} \frac{d}{ds} \left(\frac{e^{-3s}}{s} \right)$ with ROC $\text{Re}\{s\} > 0$ (8%)

$$\begin{aligned}A(s) &= \frac{1}{s} \xleftarrow{\mathcal{L}} a(t) = u(t) \\ &\quad \text{right-sided} \\ B(s) &= e^{-3s} A(s) \xleftarrow{\mathcal{L}} b(t) = a(t-3) = u(t-3)\end{aligned}$$

$$C(s) = \frac{d}{ds} B(s) \xrightarrow{\mathcal{L}} c(t) = -tb(t) = -tu(t-3)$$

$$X(s) = \frac{1}{s} C(s) \xrightarrow{\mathcal{L}} x(t) = u(t) * c(t) = \int_{-\infty}^t c(\tau) d\tau = -\int_3^t \tau d\tau \\ = -\frac{1}{2}(t^2 - 9)u(t-3) \quad (\because u(t) * c(t), 3 \leq t < \infty)$$

$$4. \quad X(s) = \frac{2s^2 + 2s - 2}{s^2 - 1} = \frac{2s^2 - 2}{s^2 - 1} + \frac{2s}{s^2 - 1} = 2 + \frac{1}{s-1} + \frac{1}{s+1}$$

(1) With ROC $\text{Re}\{s\} < -1$ (5%): Left-sided: $x(t) = 2\delta(t) - (e^t + e^{-t})u(-t)$

(2) With ROC $\text{Re}\{s\} > 1$ (5%): Right-sided: $x(t) = 2\delta(t) + (e^t + e^{-t})u(t)$

(3) With ROC $-1 < \text{Re}\{s\} < 1$ (5%):

$$\text{Two-sided: } x(t) = 2\delta(t) - e^t u(-t) + e^{-t} u(t)$$

5.

(1) (8%) $H(s) = \frac{2s-1}{s^2+2s+1} = \frac{2}{s+1} + \frac{-3}{(s+1)^2}, \left(\frac{d}{ds} \left(\frac{1}{s+1} \right) = \frac{-1}{(s+1)^2} \right)$

(a) Causal system (right-sided system): $h(t) = (2e^{-t} - 3te^{-t})u(t)$.

(b) Stable system (The ROC must include the $j\omega$ -axis.):

$$h(t) = (2e^{-t} - 3te^{-t})u(t)$$

(2) (7%) $x(t) = e^{-2t}u(t), y(t) = -2e^{-t}u(t) + 2e^{-3t}u(t)$

$$X(s) = \frac{1}{s+2}; Y(s) = \frac{-2}{s+1} + \frac{2}{s+3}$$

$$H(s) = Y(s)/X(s) = \frac{-4}{(s+1)(s+3)} \bigg/ \frac{1}{s+2} = \frac{-4(s+2)}{(s+1)(s+3)} = \frac{-2}{s+1} + \frac{-2}{s+3}$$

$$h(t) = (-2e^{-t} - 2e^{-3t})u(t)$$

(\because For a stable system, the ROC must include the $j\omega$ -axis.)

6.

(1) (7%) $x(t) = u(t) - u(t-10) \Rightarrow X(s) = \int_0^{10} e^{-st} dt = \frac{1 - e^{-10s}}{s}$

(2) $x(t) = \begin{cases} \sin(\pi t), & 0 < t < 1 \\ 0, & \text{otherwise} \end{cases}$ (8%)

$$\begin{aligned}
X(s) &= \int_{0^-}^1 \frac{1}{2j} (e^{j\pi t} - e^{-j\pi t}) e^{-st} dt \\
&= \frac{1}{2j} \left[\frac{1}{j\pi - s} (e^{j\pi - s} - 1) - \frac{1}{-j\pi - s} (e^{-j\pi - s} - 1) \right] \\
&= \frac{1}{2j} \left[\frac{1}{j\pi - s} (-e^{-s} - 1) + \frac{1}{j\pi + s} (-e^{-s} - 1) \right] \\
&= \frac{1}{2j} \frac{(-e^{-s} - 1)(j\pi + s + j\pi - s)}{-\pi^2 - s^2} = \frac{\pi(1 + e^{-s})}{s^2 + \pi^2}
\end{aligned}$$

7. (20%)

$$(1) \quad x(t-3) \xleftrightarrow{\mathcal{L}} e^{-3s} X(s) = e^{-3s} \frac{2s}{s^2 + 2}$$

$$(2) \quad x(3t) \xleftrightarrow{\mathcal{L}} \frac{1}{3} X\left(\frac{s}{3}\right) = \frac{1}{3} \times \frac{2 \frac{s}{3}}{\frac{s^2}{9} + 2} = \frac{2s}{s^2 + 18}$$

$$(3) \quad x(t) * \frac{d}{dt} x(t)$$

$$b(t) = \frac{d}{dt} x(t) \xleftrightarrow{\mathcal{L}} B(s) = sX(s)$$

$$y(t) = x(t) * b(t) \xleftrightarrow{\mathcal{L}} Y(s) = X(s)B(s) = sX^2(s) = s \left(\frac{2s}{s^2 + 2} \right)^2$$

$$(4) \quad e^{-2t} x(t) \xleftrightarrow{\mathcal{L}} X(s+2) = \frac{2(s+2)}{(s+2)^2 + 2}$$

$$(5) \quad \int_0^t x(3\tau) d\tau \xleftrightarrow{\mathcal{L}} Y(s) = \frac{X(s/3)}{3s} = \frac{2}{s^2 + 18}$$

$$\text{(From (2), } x(3t) \xleftrightarrow{\mathcal{L}} \frac{1}{3} X\left(\frac{s}{3}\right)\text{.)}$$