EECS205003 Linear Algebra, Fall 2020 Quiz # 5, Solutions

<u>Prob. 1:</u>

Thus

- 1. According to the definition of functions, the domain of T is \mathbb{R}^4 and the codomain of T is \mathbb{R}^3 .
- 2. By elementary row operations, we have

$$\begin{bmatrix} 1 & -1 & 0 & 1 & 0 \\ -2 & 1 & -3 & 1 & 0 \\ 0 & -1 & -3 & 3 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 3 & -2 & 0 \\ 0 & 1 & 3 & -3 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

and the kernel of T is the solution set of

$$\begin{bmatrix} 1 & 0 & 3 & -2 \\ 0 & 1 & 3 & -3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$
$$\Rightarrow \begin{cases} x_1 &= -3x_3 + 2x_4 \\ x_2 &= -3x_3 + 3x_4 \end{cases} \Rightarrow \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = x_3 \begin{bmatrix} -3 \\ -3 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 2 \\ 3 \\ 0 \\ 1 \end{bmatrix}.$$
$$\operatorname{Ker}(T) = \{s(-3, -3, 1, 0) + t(2, 3, 0, 1) | t, s \in \mathbb{R}\}.$$

- 3. The range $T(\mathbb{R}^4)$ of T is the column space $\operatorname{Col}(A)$ of the matrix A, i.e., $T(\mathbb{R}^4) = \operatorname{Col}(A) = \operatorname{Span}\{(1, -2, 0), (-1, 1, -1), (0, -3, -3), (1, 1, 3)\}.$
- 4. Since $\text{Ker}(T) \neq \{0\}$, T is not injective by Theorem 5 in Section 2.3 of the textbook.
- 5. *T* is surjective if and only if $T(\mathbb{R}^4) = \mathbb{R}^3$, i.e., given any vector $\mathbf{y} = (y_1, y_2, y_3)$ in \mathbb{R}^3 , there is a vector $\mathbf{x} = (x_1, x_2, x_3, x_4)$ in \mathbb{R}^4 such that $T(\mathbf{x}) = A\mathbf{x} = \mathbf{y}$. By elementary row operations on the augmented matrix, we have

$$\begin{bmatrix} 1 & -1 & 0 & 1 & y_1 \\ -2 & 1 & -3 & 1 & y_2 \\ 0 & -1 & -3 & 3 & y_3 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 3 & -2 & -y_1 - y_2 \\ 0 & 1 & 3 & -3 & -2y_1 - y_2 \\ 0 & 0 & 0 & 0 & -2y_1 - y_2 + y_3 \end{bmatrix},$$

which shows that $A\mathbf{x} = \mathbf{y}$ is not always consistent for any given \mathbf{y} . Thus we conclude that T is not surjective.

<u>Prob. 2:</u>

Solution 1.

By inspection or by solving a linear system with an augmented matrix

$$\begin{bmatrix} -1 & 0 & | -3 \\ 1 & 1 & | 1 \end{bmatrix} \Rightarrow \begin{bmatrix} -1 & 0 & | -3 \\ 0 & 1 & | -2 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & | 3 \\ 0 & 1 & | -2 \end{bmatrix},$$

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we have that (-3,1) = 3(-1,1) - 2(0,1). If T is linear, we must have T(-3,1) = T(3(-1,1) - 2(0,1)) = 3T(-1,1) - 2T(0,1) = (-3,4,-2), which is not (2,-1,0), a contradiction. Thus there is no such a linear transformation.

Solution 2.

A more systematic approach is to find a 3×2 matrix A such that

$$T\left(\begin{bmatrix}-1\\1\end{bmatrix}\right) = A\begin{bmatrix}-1\\1\end{bmatrix} = \begin{bmatrix}-1\\2\\-2\end{bmatrix}, \ T\left(\begin{bmatrix}0\\1\end{bmatrix}\right) = A\begin{bmatrix}0\\1\end{bmatrix} = \begin{bmatrix}0\\1\\-2\end{bmatrix}, \ T\left(\begin{bmatrix}-3\\1\end{bmatrix}\right) = A\begin{bmatrix}-3\\1\end{bmatrix} = \begin{bmatrix}2\\-1\\0\end{bmatrix}.$$

This is equivalent to solving the matrix equation

$$A\begin{bmatrix} -1 & 0 & -3\\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12}\\ a_{21} & a_{22}\\ a_{31} & a_{32} \end{bmatrix} \begin{bmatrix} -1 & 0 & -3\\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} -1 & 0 & 2\\ 2 & 1 & -1\\ -2 & -2 & 0 \end{bmatrix}$$

By taking the transpose on both sides, we have

$$\begin{bmatrix} -1 & 1 \\ 0 & 1 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} a_{11} & a_{21} & a_{31} \\ a_{12} & a_{22} & a_{32} \end{bmatrix} = \begin{bmatrix} -1 & 2 & -2 \\ 0 & 1 & -2 \\ 2 & -1 & 0 \end{bmatrix}.$$

By elementary row operations on the augmented matrix, we have

Γ	-1	1	-1	2	-2		[1	-1 1	-2	2		[1	0 1	-1	0]
	0	1	0	1	-2	\Rightarrow	0	1 0	1	-2	\Rightarrow	0	1 0	1	-2	,
L	-3	1	2	-1	0		0	-2 5	-7	6		0	0 5	-5	2	

which is inconsistent. Thus there is no such a matrix A and then no such a linear transformation.

<u>Prob. 3:</u>

" \Rightarrow " Since T is linear, for all scalars α and all vectors \mathbf{x}, \mathbf{y} in \mathbb{R}^n , we have

$$T(\alpha \mathbf{x} - \mathbf{y}) = T(\alpha \mathbf{x} + (-1)\mathbf{y}) = \alpha T(\mathbf{x}) + (-1)T(\mathbf{y}) = \alpha T(\mathbf{x}) - T(\mathbf{y}).$$

" \Leftarrow " We first note that

$$T(\mathbf{0}) = T(1\mathbf{0} - \mathbf{0}) = 1T(\mathbf{0}) - T(\mathbf{0}) = T(\mathbf{0}) - T(\mathbf{0}) = \mathbf{0}$$
(1)

and

$$T(-\mathbf{y}) = T(0\mathbf{0} - \mathbf{y}) = 0T(\mathbf{0}) - T(\mathbf{y}) = -T(\mathbf{y}).$$
(2)

Now for all scalars α and all vectors **x** in \mathbb{R}^n , we have

$$T(\alpha \mathbf{x}) = T(\alpha \mathbf{x} - \mathbf{0}) = \alpha T(\mathbf{x}) - T(\mathbf{0}) = \alpha T(\mathbf{x}) - \mathbf{0} = \alpha T(\mathbf{x}),$$
(3)

where $T(\mathbf{0}) = \mathbf{0}$ by (1). And then for all scalars α, β and all vectors \mathbf{x}, \mathbf{y} in \mathbb{R}^n , we have

$$T(\alpha \mathbf{x} + \beta \mathbf{y}) = T(\alpha \mathbf{x} - (-(\beta \mathbf{y}))) = \alpha T(\mathbf{x}) - T(-(\beta \mathbf{y})) = \alpha T(\mathbf{x}) - (-T(\beta \mathbf{y})),$$

where $T(-(\beta \mathbf{y})) = -T(\beta \mathbf{y})$ by (2), and then

$$T(\alpha \mathbf{x} + \beta \mathbf{y}) = \alpha T(\mathbf{x}) + T(\beta \mathbf{y}) = \alpha T(\mathbf{x}) + \beta T(\mathbf{y}),$$

where $T(\beta \mathbf{y}) = \beta T(\mathbf{y})$ by (3).

<u>Prob. 4:</u>

By elementary row operations, we have

$$\begin{bmatrix} a & 0 & 0 \\ c & d & 0 \\ -1 & f & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & -f & 0 \\ 0 & af & 0 \\ 0 & d+cf & 0 \end{bmatrix}.$$

The linear transformation $T : \mathbf{x} \mapsto A\mathbf{x}$ is not one to one if and only if $\text{Ker}(A) \neq \{\mathbf{0}\}$ if and only if

$$af = 0$$
 and $d + cf = 0$

Thus the linear transformation $T : \mathbf{x} \mapsto A\mathbf{x}$ is one to one if and only if either $af \neq 0$ or $d + cf \neq 0$. For example, with a = f = 1 and c, d arbitrary, $T : \mathbf{x} \mapsto A\mathbf{x}$ is one to one.

<u>Prob. 5:</u>

With proof by contrapositive, we show that if m > n, then any linear transformation T from \mathbb{R}^n to \mathbb{R}^m is not a surjective.

Consider a linear transformation $T(\mathbf{x}) = A\mathbf{x}$ from \mathbb{R}^n to \mathbb{R}^m with

$$A = egin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \ a_{21} & a_{22} & \cdots & a_{2n} \ dots & dots & \ddots & dots \ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}.$$

T is surjective if and only if $T(\mathbb{R}^n) = \mathbb{R}^m$, i.e., given any vector $\mathbf{y} = (y_1, y_2, \dots, y_m)$ in \mathbb{R}^m , there is a vector $\mathbf{x} = (x_1, x_2, \dots, x_n)$ in \mathbb{R}^n such that $T(\mathbf{x}) = A\mathbf{x} = \mathbf{y}$. Since m > n, there are at most n pivot positions in A. By elementary row operations on the augmented matrix, we must have

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} & y_1 \\ a_{21} & a_{22} & \cdots & a_{2n} & y_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} & y_m \end{bmatrix} \Rightarrow \begin{bmatrix} U & \vdots \\ U & \vdots \\ y'_n \\ \vdots \\ 0 & \vdots \\ y'_m \end{bmatrix}$$

where $\begin{bmatrix} U \\ \mathbf{0} \end{bmatrix}$ is in the reduced row echelon form of A with U an $n \times n$ matrix and $\mathbf{0}$ the $(m-n) \times n$ zero matrix and y'_1, y'_2, \cdots, y'_m are linear combinations of y_1, y_2, \cdots, y_m . It is clear that the linear system $A\mathbf{x} = \mathbf{y}$ is not always consistent for any given \mathbf{y} in \mathbb{R}^m . Thus we conclude that T is not surjective.

<u>Prob. 6:</u>

Let $T : \mathbb{R}^n \to \mathbb{R}^m$ be a linear transformation. Let $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$ be a finite linearly dependent indexed subset of \mathbb{R}^n . Then there is a linear relation in S

$$\alpha_1 \mathbf{v}_1 + \alpha_2 \mathbf{v}_2 + \dots + \alpha_k \mathbf{v}_k = 0$$

with $\alpha_1, \alpha_2, \ldots, \alpha_k$ not all zeros. Now the image T(S) of S under T is the indexed subset $\{T(\mathbf{v}_1), T(\mathbf{v}_2), \ldots, T(\mathbf{v}_k)\}$ of \mathbb{R}^m . Since

$$\mathbf{0} = T(\mathbf{0}) = T(\alpha_1 \mathbf{v}_1 + \alpha_2 \mathbf{v}_2 + \dots + \alpha_k \mathbf{v}_k) = \alpha_1 T(\mathbf{v}_1) + \alpha_2 T(\mathbf{v}_2) + \dots + \alpha_k T(\mathbf{v}_k),$$

T(S) is a linearly dependent indexed set.

<u>Prob. 7:</u>

A linear transformation may not map a finite linearly independent indexed set into a linearly independent indexed set. For example, consider the zero map 0 which maps all vectors \mathbf{x} in \mathbb{R}^n to the zero vector $\mathbf{0}$ in \mathbb{R}^m . Then for any finite linearly independent indexed subset $S = {\mathbf{v}_1, \mathbf{v}_2, \ldots, \mathbf{v}_k}$ of \mathbb{R}^n , we have the image $0(S) = {\mathbf{0}, \mathbf{0}, \ldots, \mathbf{0}}$ which is clearly a linearly dependent indexed set.