EECS205003 Linear Algebra, Fall 2020 Quiz $# 5$, Solutions

Prob. 1:

Thus

- 1. According to the definition of functions, the domain of T is \mathbb{R}^4 and the codomain of T is \mathbb{R}^3 .
- 2. By elementary row operations, we have

$$
\begin{bmatrix} 1 & -1 & 0 & 1 & 0 \ -2 & 1 & -3 & 1 & 0 \ 0 & -1 & -3 & 3 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 3 & -2 & 0 \ 0 & 1 & 3 & -3 & 0 \ 0 & 0 & 0 & 0 & 0 \end{bmatrix}
$$

and the kernel of T is the solution set of

$$
\begin{bmatrix} 1 & 0 & 3 & -2 \ 0 & 1 & 3 & -3 \ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \ x_2 \ x_3 \ x_4 \end{bmatrix} = \begin{bmatrix} 0 \ 0 \ 0 \end{bmatrix}
$$

\n
$$
\Rightarrow \begin{cases} x_1 = -3x_3 + 2x_4 \ x_2 = -3x_3 + 3x_4 \end{cases} \Rightarrow \begin{bmatrix} x_1 \ x_2 \ x_3 \ x_4 \end{bmatrix} = x_3 \begin{bmatrix} -3 \ -3 \ 1 \ 0 \end{bmatrix} + x_4 \begin{bmatrix} 2 \ 3 \ 0 \ 1 \end{bmatrix}
$$

\n
$$
Ker(T) = \{s(-3, -3, 1, 0) + t(2, 3, 0, 1)|t, s \in \mathbb{R}\}.
$$

- 3. The range $T(\mathbb{R}^4)$ of T is the column space $Col(A)$ of the matrix A, i.e., $T(\mathbb{R}^4)$ = $Col(A) = Span{(1, -2, 0), (-1, 1, -1), (0, -3, -3), (1, 1, 3)}.$
- 4. Since Ker(T) \neq {0}, T is not injective by Theorem 5 in Section 2.3 of the textbook.
- 5. T is surjective if and only if $T(\mathbb{R}^4) = \mathbb{R}^3$, i.e., given any vector $\mathbf{y} = (y_1, y_2, y_3)$ in \mathbb{R}^3 , there is a vector $\mathbf{x} = (x_1, x_2, x_3, x_4)$ in \mathbb{R}^4 such that $T(\mathbf{x}) = A\mathbf{x} = \mathbf{y}$. By elementary row operations on the augmented matrix, we have

$$
\begin{bmatrix} 1 & -1 & 0 & 1 & y_1 \\ -2 & 1 & -3 & 1 & y_2 \\ 0 & -1 & -3 & 3 & y_3 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 3 & -2 & -y_1 - y_2 \\ 0 & 1 & 3 & -3 & -2y_1 - y_2 \\ 0 & 0 & 0 & 0 & -2y_1 - y_2 + y_3 \end{bmatrix},
$$

which shows that $A\mathbf{x} = \mathbf{y}$ is not always consistent for any given y. Thus we conclude that T is not surjective.

Prob. 2:

Solution 1.

By inspection or by solving a linear system with an augmented matrix

$$
\begin{bmatrix} -1 & 0 & | & -3 \\ 1 & 1 & | & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} -1 & 0 & | & -3 \\ 0 & 1 & | & -2 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & | & 3 \\ 0 & 1 & | & -2 \end{bmatrix},
$$

 $\pmb{t} = \pm$

we have that $(-3, 1) = 3(-1, 1) - 2(0, 1)$. If T is linear, we must have $T(-3, 1) =$ $T(3(-1, 1) - 2(0, 1)) = 3T(-1, 1) - 2T(0, 1) = (-3, 4, -2)$, which is not $(2, -1, 0)$, a contradiction. Thus there is no such a linear transformation.

Solution 2.

A more systematic approach is to find a 3×2 matrix A such that

$$
T\left(\begin{bmatrix} -1 \\ 1 \end{bmatrix}\right) = A\begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ -2 \end{bmatrix}, T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = A\begin{bmatrix} 0 \\ 1 \\ -2 \end{bmatrix}, T\left(\begin{bmatrix} -3 \\ 1 \end{bmatrix}\right) = A\begin{bmatrix} -3 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \\ 0 \end{bmatrix}.
$$

This is equivalent to solving the matrix equation

$$
A\begin{bmatrix} -1 & 0 & -3 \ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ a_{31} & a_{32} \end{bmatrix} \begin{bmatrix} -1 & 0 & -3 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} -1 & 0 & 2 \\ 2 & 1 & -1 \\ -2 & -2 & 0 \end{bmatrix}
$$

By taking the transpose on both sides, we have

$$
\begin{bmatrix} -1 & 1 \ 0 & 1 \ -3 & 1 \end{bmatrix} \begin{bmatrix} a_{11} & a_{21} & a_{31} \ a_{12} & a_{22} & a_{32} \end{bmatrix} = \begin{bmatrix} -1 & 2 & -2 \ 0 & 1 & -2 \ 2 & -1 & 0 \end{bmatrix}.
$$

By elementary row operations on the augmented matrix, we have

which is inconsistent. Thus there is no such a matrix A and then no such a linear transformation.

Prob. 3:

 $\mathbb{R}^n \Rightarrow$ " Since T is linear, for all scalars α and all vectors \mathbf{x}, \mathbf{y} in \mathbb{R}^n , we have

$$
T(\alpha \mathbf{x} - \mathbf{y}) = T(\alpha \mathbf{x} + (-1)\mathbf{y}) = \alpha T(\mathbf{x}) + (-1)T(\mathbf{y}) = \alpha T(\mathbf{x}) - T(\mathbf{y}).
$$

" \Leftarrow " We first note that

$$
T(0) = T(10 - 0) = 1T(0) - T(0) = T(0) - T(0) = 0
$$
\n(1)

and

$$
T(-y) = T(00 - y) = 0T(0) - T(y) = -T(y).
$$
 (2)

Now for all scalars α and all vectors **x** in \mathbb{R}^n , we have

$$
T(\alpha \mathbf{x}) = T(\alpha \mathbf{x} - \mathbf{0}) = \alpha T(\mathbf{x}) - T(\mathbf{0}) = \alpha T(\mathbf{x}) - \mathbf{0} = \alpha T(\mathbf{x}),
$$
(3)

where $T(0) = 0$ by (1). And then for all scalars α, β and all vectors **x**, **y** in \mathbb{R}^n , we have

$$
T(\alpha \mathbf{x} + \beta \mathbf{y}) = T(\alpha \mathbf{x} - (-(\beta \mathbf{y}))) = \alpha T(\mathbf{x}) - T(-(\beta \mathbf{y})) = \alpha T(\mathbf{x}) - (-T(\beta \mathbf{y})),
$$

where $T(-(\beta y)) = -T(\beta y)$ by (2), and then

$$
T(\alpha \mathbf{x} + \beta \mathbf{y}) = \alpha T(\mathbf{x}) + T(\beta \mathbf{y}) = \alpha T(\mathbf{x}) + \beta T(\mathbf{y}),
$$

where $T(\beta y) = \beta T(y)$ by (3).

Prob. 4:

By elementary row operations, we have

$$
\begin{bmatrix} a & 0 & 0 \ c & d & 0 \ -1 & f & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & -f & 0 \ 0 & af & 0 \ 0 & d+cf & 0 \end{bmatrix}.
$$

The linear transformation $T: \mathbf{x} \mapsto A\mathbf{x}$ is not one to one if and only if $\text{Ker}(A) \neq \{0\}$ if and only if

$$
af = 0 \text{ and } d + cf = 0
$$

Thus the linear transformation $T: \mathbf{x} \mapsto A\mathbf{x}$ is one to one if and only if either $af \neq 0$ or $d + cf \neq 0$. For example, with $a = f = 1$ and c, d arbitrary, $T : \mathbf{x} \mapsto A\mathbf{x}$ is one to one.

Prob. $5:$

With proof by contrapositive, we show that if $m > n$, then any linear transformation T from \mathbb{R}^n to \mathbb{R}^m is not a surjective.

Consider a linear transformation $T(\mathbf{x}) = A\mathbf{x}$ from \mathbb{R}^n to \mathbb{R}^m with

$$
A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}.
$$

T is surjective if and only if $T(\mathbb{R}^n) = \mathbb{R}^m$, i.e., given any vector $\mathbf{y} = (y_1, y_2, \dots, y_m)$ in \mathbb{R}^m , there is a vector $\mathbf{x} = (x_1, x_2, \dots, x_n)$ in \mathbb{R}^n such that $T(\mathbf{x}) = A\mathbf{x} = \mathbf{y}$. Since $m > n$, there are at most *n* pivot positions in *A*. By elementary row operations on the augmented matrix, we must have

$$
\left[\begin{array}{cccc|c} a_{11} & a_{12} & \cdots & a_{1n} & y_1 \\ a_{21} & a_{22} & \cdots & a_{2n} & y_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} & y_m \end{array}\right] \Rightarrow \left[\begin{array}{c|c} U & y'_1 \\ \vdots \\ y'_n \\ \hline 0 \\ \vdots \\ 0 \\ y'_m \end{array}\right]
$$

where $\begin{bmatrix} U \\ 0 \end{bmatrix}$ is in the reduced row echelon form of A with U an $n \times n$ matrix and 0 the $(m-n) \times n$ zero matrix and y'_1, y'_2, \cdots, y'_m are linear combinations of y_1, y_2, \cdots, y_m . It is clear that the linear system $A\mathbf{x} = \mathbf{y}$ is not always consistent for any given y in \mathbb{R}^m . Thus we conclude that T is not surjective.

Prob. $6:$

Let $T: \mathbb{R}^n \to \mathbb{R}^m$ be a linear transformation. Let $S = {\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k}$ be a finite linearly dependent indexed subset of \mathbb{R}^n . Then there is a linear relation in S

$$
\alpha_1 \mathbf{v}_1 + \alpha_2 \mathbf{v}_2 + \cdots + \alpha_k \mathbf{v}_k = 0
$$

with $\alpha_1, \alpha_2, \ldots, \alpha_k$ not all zeros. Now the image $T(S)$ of S under T is the indexed subset $\{T(\mathbf{v}_1), T(\mathbf{v}_2), \ldots, T(\mathbf{v}_k)\}\$ of \mathbb{R}^m . Since

$$
\mathbf{0} = T(\mathbf{0}) = T(\alpha_1 \mathbf{v}_1 + \alpha_2 \mathbf{v}_2 + \cdots + \alpha_k \mathbf{v}_k) = \alpha_1 T(\mathbf{v}_1) + \alpha_2 T(\mathbf{v}_2) + \cdots + \alpha_k T(\mathbf{v}_k),
$$

 $T(S)$ is a linearly dependent indexed set.

Prob. 7:

A linear transformation may not map a finite linearly independent indexed set into a linearly independent indexed set. For example, consider the zero map 0 which maps all vectors **x** in \mathbb{R}^n to the zero vector **0** in \mathbb{R}^m . Then for any finite linearly independent indexed subset $S = {\mathbf{v}_1, \mathbf{v}_2, ..., \mathbf{v}_k}$ of \mathbb{R}^n , we have the image $0(S) = \{0, 0, \ldots, 0\}$ which is clearly a linearly dependent indexed set.