

# EECS 205003 Session 2

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## The geometry of linear equations

### Central problem of linear algebra

#### Solving a system of linear equation

#### Ex

$$x - 2y = 1$$

$$3x + 2y = 11 \text{ (2 equations, 2 unknowns)}$$

[We can have 3 different views on this!]

#### Row Picture

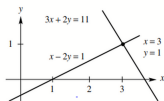


Figure 11: Row picture: The point (3, 1) where the lines meet is the solution.

**Solution  $x=3, y=1$  is where the two lines meet**

**$x=3, y=1$  is the point that satisfies both linear equations**

Column Picture

See the same line equations as vector equations

$$\Rightarrow \mathbf{x} \begin{bmatrix} 1 \\ 3 \end{bmatrix} + \mathbf{y} \begin{bmatrix} -2 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 11 \end{bmatrix} = \mathbf{b}$$

$\mathbf{c}$                        $\mathbf{d}$

$$\Rightarrow \mathbf{xc} + \mathbf{yd} = \mathbf{b}$$

(linear combination of two column vector gives b)

Now we need to find scalars  $\mathbf{x}$  &  $\mathbf{y}$

s.t  $\mathbf{x}$  copies of  $\begin{bmatrix} 1 \\ 2 \end{bmatrix} + \mathbf{y}$  copies

of  $\begin{bmatrix} -2 \\ 2 \end{bmatrix}$  equals the vector  $\begin{bmatrix} 1 \\ 11 \end{bmatrix}$

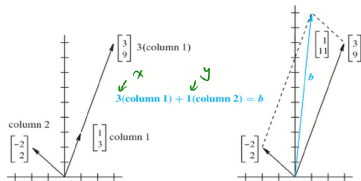


Figure 12: Column picture: A combination of columns produces the right side (1,11).

## Linear combination

$$3 \begin{bmatrix} 1 \\ 3 \end{bmatrix} + 1 \begin{bmatrix} -2 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 11 \end{bmatrix}$$

(same solution  $x = 3, y = 1$ , but different views)

### Matrix Picture

$$\begin{array}{l} x - 2y = 1 \\ 3x + 2y = 11 \end{array} \Rightarrow \begin{array}{c} A \\ \left[ \begin{array}{cc} 1 & -2 \\ 3 & 2 \end{array} \right] \end{array} \begin{array}{c} \mathbf{x} \\ \left[ \begin{array}{c} x \\ y \end{array} \right] \end{array} = \begin{array}{c} \mathbf{b} \\ \left[ \begin{array}{c} 1 \\ 11 \end{array} \right] \end{array}$$

$\Downarrow \qquad \Downarrow$

coefficient matrix    vector of unknown

$$\Rightarrow A \cdot \mathbf{x} = \mathbf{b}$$

## Matrix multiplication

### Method 1

$$\begin{bmatrix} 1 & -2 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 3 \end{bmatrix} + 1 \begin{bmatrix} -2 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 11 \end{bmatrix}$$

(based on column picture)

### Method 2

$$\begin{bmatrix} 1 & -2 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \cdot 3 - 2 \cdot 1 \\ 3 \cdot 3 + 2 \cdot 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 11 \end{bmatrix}$$

dot product

(based on row picture)

## Three equation in three unknowns

$$A\mathbf{x} = \mathbf{b} \Leftrightarrow \begin{bmatrix} x + 2y + 3z = 6 \\ 2x + 5y + 2z = 4 \\ 6x - 3y + z = 2 \end{bmatrix}$$

**Row Picture** (3 equations + 3 unknowns: usually one solution.)

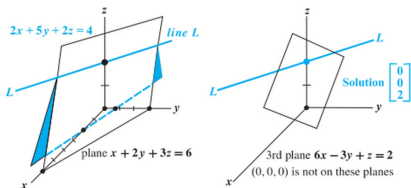


Figure 13: Row picture: Two planes meet at a line, three planes at a point.

**Note:**

$x + 2y + 3z = 0$  passes through origin  
 $x + 2y + 3z = 6$  does NOT, but is  
 parallelly shifted

(Solution is difficult to visualize & find)

## Column Picture

$$x \begin{bmatrix} 1 \\ 2 \\ 6 \end{bmatrix} + y \begin{bmatrix} 2 \\ 5 \\ -3 \end{bmatrix} + z \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 4 \\ 2 \end{bmatrix}$$

(Very easy to see that  $x=0$ ,  $y=0$ ,  $z=2$  in the solution)

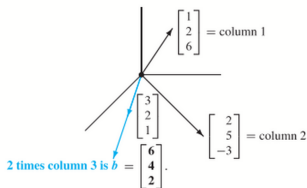


Figure 14: Column picture:  $(x, y, z) = (0, 0, 2)$  because  $2(3, 2, 1) = (6, 4, 2) = \mathbf{b}$ .

$$\left( 0 \begin{bmatrix} 1 \\ 2 \\ 6 \end{bmatrix} + 0 \begin{bmatrix} 2 \\ 5 \\ -3 \end{bmatrix} + 2 \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} = \mathbf{b} \right)$$

## Matrix Picture

$$\begin{matrix} \begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 2 \\ 6 & -3 & 1 \end{bmatrix} & \begin{bmatrix} x \\ y \\ z \end{bmatrix} & = & \begin{bmatrix} 6 \\ 4 \\ 2 \end{bmatrix} \\ A & \mathbf{x} & & \mathbf{b} \end{matrix}$$

## Multiplication by rows

$$A\mathbf{x} = \begin{bmatrix} (\text{row1}) \cdot \mathbf{x} \\ (\text{row2}) \cdot \mathbf{x} \\ (\text{row3}) \cdot \mathbf{x} \end{bmatrix}$$

## Multiplication by columns

$$A\mathbf{x} = x(\text{col.1}) + y(\text{col.2}) + z(\text{col.3})$$



## Identify Matrix

ones on the "main diagonal"

$$I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow I\mathbf{x} = \mathbf{x}$$

## Matrix notation

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} = \begin{bmatrix} A(1,1) & A(1,2) \\ A(2,1) & A(2,2) \end{bmatrix}$$

## Linear independence

**Q: Given a matrix  $A$ , can we solve  $A\mathbf{x} = \mathbf{b}$  for every possible vector  $\mathbf{b}$**

## From column picture

**Q: Do linear combination of columns of  $A$  fill the entire space? (2D OR 3D)**

**If not, we say  $A$  is singular**

**$\Rightarrow$  columns of  $A$  are linearly dependent**

**(For 2D, linear combination of column vectors lies on a point, or a line )**

**(For 3D, linear combination of column vectors lies on a point, line, or plane)**

**worked ex 2.1A 2.1B**