EECS205000: Linear Algebra Spring 2019 College of Electrical Engineering and Computer Science National Tsing Hua University		
Η	Homework $#3$ Solutions	
	Coverage: Chapter 1–6	
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Problem 1. (20 points)

- (a) (10 points) Let **P** and **Z** be positive semidefinite matrices such that $\mathbf{P}^2 = \mathbf{Z}^2$. Then $\mathbf{P} = \mathbf{Z}$.
- (b) (10 points) Let $\mathbf{A} \in \mathbb{R}^{n \times n}$ be invertible. Using the result in part (a), prove that there exist unique matrices \mathbf{Q} and \mathbf{P} which are orthogonal and positive-semidefinite matrices, respectively such that $\mathbf{A} = \mathbf{Q}\mathbf{P}$.

Solution:

(a) Let $\alpha = {\mathbf{x}_1, \ldots, \mathbf{x}_n}$ be an orthonormal basis consisting of eigenvectors of **P**. then we have

$$\mathbf{P}\mathbf{x}_i = \lambda_i \mathbf{x}_i, \quad \forall \ \mathbf{x}_i \in \alpha.$$

Then we can write

$$\mathbf{P}^2 \mathbf{x}_i = \lambda_i^2 \mathbf{x}_i = \mathbf{Z}^2 \mathbf{x}_i, \quad \forall \ \mathbf{x}_i \in \alpha.$$
(1)

Consider the case $\lambda_i = 0$. We have

$$\|\mathbf{Z}\mathbf{x}_i\|^2 = \mathbf{x}_i^* \mathbf{Z}^T \mathbf{Z}\mathbf{x}_i = \mathbf{x}_i^* \mathbf{Z}^2 \mathbf{x}_i = \mathbf{x}_i^* \mathbf{P}^2 \mathbf{x}_i = \|\mathbf{P}\mathbf{x}_i\|^2 = 0,$$

which implies that $\mathbf{Z}\mathbf{x}_i = \mathbf{P}\mathbf{x}_i = \mathbf{0}$. Thus \mathbf{Z} and \mathbf{P} have the identical eigenspaces. Now, consider the case $\lambda_i > 0$. By (1) we have

$$(\mathbf{Z}^2 - \lambda_i^2 \mathbf{I})\mathbf{x}_i = (\mathbf{Z} + \lambda_i \mathbf{I})(\mathbf{Z} - \lambda_i \mathbf{I})\mathbf{x}_i = \mathbf{0}.$$
(2)

Here, $\mathbf{Z} + \lambda_i \mathbf{I}$ is invertible since $det(\mathbf{Z} + \lambda_i \mathbf{I}) \neq 0$ (otherwise, $-\lambda_i$ is a eigenvalue of \mathbf{Z} which is impossible). Then we have

$$(\mathbf{Z} - \lambda_i \mathbf{I})\mathbf{x}_i = \mathbf{0},$$

which implies $\mathbf{P}\mathbf{x}_i = \lambda_i \mathbf{x}_i = \mathbf{Z}\mathbf{x}_i$. This means that \mathbf{P} and \mathbf{Z} meet on the same basis α and therefore $\mathbf{P} = \mathbf{Z}$.

(b) By singular value decomposition we have $\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T$ where $\mathbf{U}^T \mathbf{U} = \mathbf{I}$ and $\mathbf{V}^T \mathbf{V} = \mathbf{I}$. Then we can write

$$\mathbf{A} = (\mathbf{U}\mathbf{V}^T)(\mathbf{V}\mathbf{\Sigma}\mathbf{V}^T) = \mathbf{Q}\mathbf{P},$$

where $\mathbf{Q} \triangleq \mathbf{U}\mathbf{V}^T$ is an orthogonal matrix and $\mathbf{P} \triangleq \mathbf{V}\mathbf{\Sigma}\mathbf{V}^T$ is a positive-semidefinite matrix. By contradiction assume $\mathbf{A} = \mathbf{Q}\mathbf{P} = \mathbf{U}\mathbf{Z}$ where \mathbf{Q} , \mathbf{U} are orthogonal matrices and \mathbf{P} , \mathbf{Z} are positive-semidefinite matrices. Since \mathbf{A} is invertible, \mathbf{P} and \mathbf{Z} are also invertible. Then we have

$$\mathbf{U}^T \mathbf{Q} = \mathbf{U}^T \mathbf{Q} \mathbf{P} \mathbf{P}^{-1} = \mathbf{U}^T \mathbf{U} \mathbf{Z} \mathbf{P}^{-1} = \mathbf{Z} \mathbf{P}^{-1}$$

Since \mathbf{Q} , \mathbf{U} are orthogonal matrices, then $\mathbf{Z}\mathbf{P}^{-1}$ is also an orthogonal matrix. Then we have

$$(\mathbf{Z}\mathbf{P}^{-1})^T\mathbf{Z}\mathbf{P}^{-1} = \mathbf{P}^{-1}\mathbf{Z}^T\mathbf{Z}\mathbf{P}^{-1} = \mathbf{I},$$

which implies that $\mathbf{Z}^2 = \mathbf{P}^2$. Since \mathbf{Z} and \mathbf{P} are positive-semidefinite matrices, then by part (a) we have $\mathbf{Z} = \mathbf{P}$.

Problem 2. (15 points) Let A be an invertible matrix.

- (a) (5 points) Show that for any eigenvalue λ of **A**, λ^{-1} is an eigenvalue of **A**⁻¹.
- (b) (5 points) Show that the eigenspace of **A** corresponding to λ is the same as the eigenspace of \mathbf{A}^{-1} corresponding to λ^{-1} .
- (c) (5 points) Show that if **A** is invertible and diagonalizable, then \mathbf{A}^{-1} is also diagonalizable.

Solution:

(a) We know $\mathbf{A}\mathbf{x} = \lambda \mathbf{x}$ where $\lambda \neq 0$ (otherwise if $\lambda = 0$, $\mathbf{A}\mathbf{x} = 0$, $\mathbf{x} \neq \mathbf{0}$ which implies \mathbf{A} is NOT INVERTIBLE). Then we can write

$$\mathbf{A}^{-1}\mathbf{A}\mathbf{x} = \lambda \mathbf{A}^{-1}\mathbf{x} \implies \lambda^{-1}\mathbf{x} = \mathbf{A}^{-1}\mathbf{x}$$

(b) Let E_{λ} be the eigenspace of **A** corresponding to λ and $E_{\lambda^{-1}}$ be the eigenspace of \mathbf{A}^{-1} corresponding to λ^{-1} . If $\mathbf{x} \in E_{\lambda}$, we have

$$\mathbf{A}\mathbf{x} = \lambda \mathbf{x} \implies \lambda^{-1}\mathbf{x} = \mathbf{A}^{-1}\mathbf{x},$$

and hence $\mathbf{x} \in E_{\lambda^{-1}}$. Conversely, if $\mathbf{x} \in E_{\lambda^{-1}}$ we have

$$\mathbf{A}^{-1}\mathbf{x} = \lambda^{-1}\mathbf{x} \implies \mathbf{x} = \lambda^{-1}\mathbf{A}\mathbf{x} \implies \mathbf{A}\mathbf{x} = \lambda\mathbf{x}$$

and hence $\mathbf{x} \in E_{\lambda}$.

(c) Let **A** be diagonalizable and we can write $\mathbf{A} = \mathbf{SDS}^{-1}$ where $\mathbf{D} = \text{Diag}([\lambda_1, \dots, \lambda_n])$ is a diagonal matrix containing the eigenvalues of **A**. Since **A** and **S** are invertible, then we have

$$A^{-1} = (SDS^{-1})^{-1} = SD^{-1}S^{-1}$$

where $\mathbf{D}^{-1} = \text{Diag}([\lambda_1^{-1}, \dots, \lambda_n^{-1}])$. Thereby, \mathbf{A}^{-1} is diagonalizable.

Problem 3. (20 points) The matrix $\mathbf{A} \in \mathbb{R}^{n \times n}$ can be written as $\mathbf{A} = \mathbf{L}\mathbf{D}\mathbf{U}$, where \mathbf{L} and \mathbf{U} are lower unitriangular and upper unitriangular matrices, respectively, and \mathbf{D} is a diagonal matrix. Show that $\mathbf{L}\mathbf{D}\mathbf{U}$ decomposition can be reduced to $\mathbf{A} = \mathbf{L}\mathbf{D}\mathbf{L}^T$ if \mathbf{A} is a nonsingular symmetric matrix.

Solution:

Suppose **A** is a nonsingular symmetric matrix. By LDU decomposition we have $\mathbf{A} = \mathbf{LDU}$ where **L** and **U** are lower unitriangular and upper unitriangular matrices (and hence invertible) with all the diagonal entries equal to unity, respectively, and **D** is a diagonal matrix. Clearly, $(\mathbf{U}^{-1})^T \mathbf{A} \mathbf{U}^{-1}$ is symmetric and we can write

$$(\mathbf{U}^{-1})^T \mathbf{A} \mathbf{U}^{-1} = (\mathbf{U}^{-1})^T \mathbf{L} \mathbf{D} \mathbf{U} \mathbf{U}^{-1} = (\mathbf{U}^{-1})^T \mathbf{L} \mathbf{D}$$

Since $(\mathbf{U}^{-1})^T \mathbf{L} \mathbf{D}$ is symmetric and $(\mathbf{U}^{-1})^T$ is lower unitriangular matrix, those imply that $(\mathbf{U}^{-1})^T \mathbf{L} \mathbf{D}$ is a diagonal matrix. Besides, $(\mathbf{U}^{-1})^T \mathbf{L}$ is a diagonal matrix since \mathbf{D} is diagonal matrix. Due to that $(\mathbf{U}^{-1})^T$ and \mathbf{L} are lower unitriangular matrices, it implies that $(\mathbf{U}^T)^{-1}\mathbf{L} = \mathbf{I}_n$ where \mathbf{I}_n is the $n \times n$ identity matrix. Hence, $\mathbf{L} = \mathbf{U}^T$.

Problem 4. (15 points) The Frobenius norm defined for $\mathbf{A} \in \mathbb{C}^{n \times n}$ by $\|\mathbf{A}\|_F = (\operatorname{Tr}(\mathbf{A}^H \mathbf{A}))^{1/2}$ where $\operatorname{Tr}(\cdot)$ denotes the trace of a matrix. Show that

$$\|\mathbf{A}\|_F \le (\operatorname{rank}(\mathbf{A}))^{1/2} \|\mathbf{A}\|_2$$

where $\|\mathbf{A}\|_2 = \max_{\|\mathbf{x}\|_2=1} \|\mathbf{A}\mathbf{x}\|_2$ and \mathbf{x} is an $n \times 1$ vector.

Solution:

We know that rank(\mathbf{A}) = rank($\mathbf{A}^{H}\mathbf{A}$) and the eigenvalues of $\mathbf{A}^{H}\mathbf{A}$ are ordered as $\lambda_{max}(\mathbf{A}^{H}\mathbf{A}) = \lambda_{1} \geq \lambda_{2} \geq \dots \geq \lambda_{r} > \lambda_{r+1} = \dots = \lambda_{n} = 0$. Then we have

$$\|\mathbf{A}\|_F = (\operatorname{Tr}(\mathbf{A}^H \mathbf{A}))^{1/2} = \left(\sum_{i=1}^n \lambda_i(\mathbf{A}^H \mathbf{A})\right)^{1/2} \le (\operatorname{rank}(\mathbf{A}))^{1/2} \lambda_{max}^{1/2}(\mathbf{A}^H \mathbf{A}).$$

On the other hand, since $\mathbf{A}^{H}\mathbf{A}$ is Hermitian we can write $\mathbf{A}^{H}\mathbf{A} = \mathbf{U}\mathbf{D}\mathbf{U}^{H}$ where \mathbf{U} is a unitary matrix and \mathbf{D} is diagonal. Then we have

$$\|\mathbf{A}\|_{2}^{2} = \max_{\|\mathbf{x}\|_{2}=1} \|\mathbf{A}\mathbf{x}\|_{2}^{2} = \max_{\|\mathbf{x}\|_{2}=1} \mathbf{x}^{H} \mathbf{A}^{H} \mathbf{A}\mathbf{x} = \max_{\|\mathbf{x}\|_{2}=1} \mathbf{x}^{H} \mathbf{U} \mathbf{D} \mathbf{U}^{H} \mathbf{x} = \max_{\|\mathbf{y}\|_{2}=1} \mathbf{y}^{H} \mathbf{D} \mathbf{y} = \max_{\|\mathbf{y}\|_{2}=1} \sum_{i=1}^{n} \lambda_{i} |y_{i}|^{2} \le \lambda_{max} (\mathbf{A}^{H} \mathbf{A}),$$

and for **x** to be the corresponding eigenvector of $\lambda_{max}(\mathbf{A}^H \mathbf{A})$, $\|\mathbf{A}\mathbf{x}\|_2$ attains its maximum and hence $\|\mathbf{A}\|_2 = \lambda_{max}^{1/2}(\mathbf{A}^H \mathbf{A})$ and thereby

$$\|\mathbf{A}\|_F \le (\operatorname{rank}(\mathbf{A}))^{1/2} \|\mathbf{A}\|_2.$$

Problem 5. (5 points) Let $\mathbf{A} = \begin{bmatrix} 6 & -1 \\ 3 & 2 \end{bmatrix}$. Find a general formula based on n (a positive integer) for \mathbf{A}^n .

Solution:

The idea to solve this problem is by matrix diagonalization where $\mathbf{A} = \mathbf{U}\mathbf{D}\mathbf{U}^{-1}$. For that the characteristic polynomial is

$$det \left(\mathbf{A} - \lambda \mathbf{I}\right) = det \left(\begin{bmatrix} 6 - \lambda & -1 \\ 3 & 2 - \lambda \end{bmatrix} \right) = \lambda^2 - 8\lambda + 15 = 0, \tag{3}$$

which implies $\lambda_1 = 5$ and $\lambda_2 = 3$. Hence, the eigenvalue matrix is

$$\mathbf{D} = \begin{bmatrix} 5 & 0\\ 0 & 3 \end{bmatrix}.$$
 (4)

Then we can obtain the matrix containing the eigenvectors of \mathbf{A} as

$$\mathbf{U} = \begin{bmatrix} 1 & 1/3 \\ 1 & 1 \end{bmatrix}.$$
 (5)

And its inverse can be obtained as

$$\mathbf{U}^{-1} = \frac{1}{2} \begin{bmatrix} 3 & -1\\ -3 & 3 \end{bmatrix}.$$
 (6)

Then we can write

$$\mathbf{A}^{n} = (\mathbf{U}\mathbf{D}\mathbf{U}^{-1})^{n} = (\mathbf{U}\mathbf{D}\mathbf{U}^{-1})(\mathbf{U}\mathbf{D}\mathbf{U}^{-1})\dots(\mathbf{U}\mathbf{D}\mathbf{U}^{-1}) = \mathbf{U}\mathbf{D}^{n}\mathbf{U}^{-1},$$
(7)

and hence we have

$$\mathbf{A}^{n} = \mathbf{U} \begin{bmatrix} 5^{n} & 0\\ 0 & 3^{n} \end{bmatrix} \mathbf{U}^{-1} = \frac{1}{2} \begin{bmatrix} 1 & 1/3\\ 1 & 1 \end{bmatrix} \begin{bmatrix} 5^{n} & 0\\ 0 & 3^{n} \end{bmatrix} \begin{bmatrix} 3 & 1\\ -3 & 3 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 3 \times 5^{n} - 3^{n} & 5^{n} + 3^{n}\\ 3 \times 5^{n} - 3^{n+1} & 5^{n} + 3^{n+1} \end{bmatrix}.$$
 (8)

Problem 6. (5 points) Define the matrix A as

be a $2n \times 2n$ matrix. Find \mathbf{A}^{ℓ} where ℓ is a positive integer number.

Solution:

This matrix can be easily written in block matrix form as

$$\mathbf{A} = \begin{bmatrix} \mathbf{I}_n & \mathbf{0}_n \\ 9\mathbf{I}_n & \mathbf{I}_n \end{bmatrix}$$

Then we have

$$\mathbf{A}^{2} = \begin{bmatrix} \mathbf{I}_{n} & \mathbf{0}_{n} \\ 9\mathbf{I}_{n} & \mathbf{I}_{n} \end{bmatrix} \begin{bmatrix} \mathbf{I}_{n} & \mathbf{0}_{n} \\ 9\mathbf{I}_{n} & \mathbf{I}_{n} \end{bmatrix} = \begin{bmatrix} \mathbf{I}_{n} & \mathbf{0}_{n} \\ 18\mathbf{I}_{n} & \mathbf{I}_{n} \end{bmatrix},$$
$$\mathbf{A}^{3} = \begin{bmatrix} \mathbf{I}_{n} & \mathbf{0}_{n} \\ 18\mathbf{I}_{n} & \mathbf{I}_{n} \end{bmatrix} \begin{bmatrix} \mathbf{I}_{n} & \mathbf{0}_{n} \\ 9\mathbf{I}_{n} & \mathbf{I}_{n} \end{bmatrix} = \begin{bmatrix} \mathbf{I}_{n} & \mathbf{0}_{n} \\ 27\mathbf{I}_{n} & \mathbf{I}_{n} \end{bmatrix},$$

and finally

$$\mathbf{A}^{\ell} = \begin{bmatrix} \mathbf{I}_n & \mathbf{0}_n \\ 9\ell \mathbf{I}_n & \mathbf{I}_n \end{bmatrix}$$

Problem 7. (5 points) Let V be a finite dimensional vector space with dim(V) = n. Prove that every basis for V contains the same number of vectors.

Solution:

Suppose α is a basis for V containing n vectors and β be any arbitrary basis for V containing m vectors. Then we have:

case 1: if m > n; then, there is a subset $S \subset \beta$ containing n + 1 vectors. Since S is linearly independent and $V = span\{\alpha\}$, then $n + 1 \leq n$ which is a clear contradiction. Hence $m \leq n$.

case 2: if m < n; then, there is a subset $S \subset \alpha$ containing m + 1 vectors. Since S is linearly independent and $V = span\{\beta\}$, then $m + 1 \le m$ which is a clear contradiction. Hence $m \ge n$. Then by case 1 and case 2 we have n = m and the proof is completed.

Problem 8. (10 points) Let $\mathbf{A} = \begin{bmatrix} 2 & 3 & 0 \\ 1 & 3 & 1 \\ 2 & -1 & 4 \end{bmatrix}$. Find \mathbf{J} and invertible \mathbf{S} such that $\mathbf{J} = \mathbf{S}^{-1}\mathbf{A}\mathbf{S}$ where \mathbf{J} is the Jordan expension form of \mathbf{A} .

the Jordan canonical form of \mathbf{A} .

Solution:

First, we need to find the eigenvalues and then we have

$$(2-\lambda)\begin{vmatrix} 3-\lambda & 1\\ -1 & 4-\lambda \end{vmatrix} - 3\begin{vmatrix} 1 & 1\\ 2 & 4-\lambda \end{vmatrix} = 0,$$

after simplification we have $\lambda_1 = 2$, $\lambda_2 = 2$ and $\lambda_3 = 5$. The we have

$$N(\mathbf{A} - 2\mathbf{I}) = span\left\{ \begin{bmatrix} -1\\0\\1 \end{bmatrix} \right\}.$$

Besides,

$$N(\mathbf{A} - 5\mathbf{I}) = span\left\{ \begin{bmatrix} 1\\1\\1 \end{bmatrix} \right\}.$$

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Then the Jordan matrix is

$$\mathbf{J} = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 5 \end{bmatrix}.$$

Moreover, let $\mathbf{S} = [\mathbf{s}_1 \ \mathbf{s}_2 \ \mathbf{s}_3]$ and for this Jordan decomposition we can write

$$AS = SJ$$

which implies that

$$\begin{bmatrix} \mathbf{A}\mathbf{s}_1 & \mathbf{A}\mathbf{s}_2 & \mathbf{A}\mathbf{s}_3 \end{bmatrix} = \begin{bmatrix} 2\mathbf{s}_1 & \mathbf{s}_1 + 2\mathbf{s}_2 & 5\mathbf{s}_3 \end{bmatrix}$$

and hence

$$\mathbf{As}_1 = 2\mathbf{s}_1 \implies (\mathbf{A} - 2\mathbf{I})\mathbf{s}_1 = \mathbf{0},\tag{9}$$

$$\mathbf{As}_2 = \mathbf{s}_1 + 2\mathbf{s}_2 \implies (\mathbf{A} - 2\mathbf{I})\mathbf{s}_2 = \mathbf{s}_1, \tag{10}$$

$$\mathbf{As}_3 = 5\mathbf{s}_3 \implies (\mathbf{A} - 5\mathbf{I})\mathbf{s}_3 = \mathbf{0},\tag{11}$$

$$\mathbf{s}_1, \mathbf{s}_2, \mathbf{s}_3$$
 are linearly independent. (12)

From (9), (10) implies that $(\mathbf{A} - 2\mathbf{I})^2 \mathbf{s}_2 = \mathbf{0}$ and together with (2) implies that $\mathbf{s}_2 \in N((\mathbf{A} - 2\mathbf{I})^2)$ but $\mathbf{s}_2 \notin N(\mathbf{A} - 2\mathbf{I})$, thereby we have

$$\mathbf{s}_2 = \begin{bmatrix} 1/3\\ -1/3\\ 0 \end{bmatrix}.$$

Then

$$\mathbf{s}_1 = \begin{bmatrix} -1\\0\\1 \end{bmatrix} \in N(\mathbf{A} - 2\mathbf{I}).$$

Then choose \mathbf{s}_3 such that $\mathbf{s}_3 \in N(\mathbf{A} - 5\mathbf{I})$ and being linearly independent with \mathbf{s}_1 and \mathbf{s}_2 as

$$\mathbf{s}_3 = \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}.$$

Hence the matrices can be obtained as

$$\mathbf{S} = \begin{bmatrix} -1 & 1/3 & 1\\ 0 & -1/3 & 1\\ 1 & 0 & 1 \end{bmatrix}, \quad \mathbf{S}^{-1} = \begin{bmatrix} -1/3 & -1/3 & 2/3\\ 1 & -2 & 1\\ 1/3 & 1/3 & 1/3 \end{bmatrix}.$$

Problem 9. (10 points) Consider the matrix $\mathbf{A} = \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}$.

- (a) (5 points) Find the complete solution for the equation $\frac{d\mathbf{x}(t)}{dt} = \mathbf{A}\mathbf{x}(t)$ with the initial condition $\mathbf{x}(0) = \begin{bmatrix} 0 & 2 \end{bmatrix}^T$.
- (b) (5 points) Find the singular value decomposition as $\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T$ using diagonalization of the matrix $\mathbf{A}^T \mathbf{A}$.

Solution:

(a) We need first to find the eigenvalues and eigenvector of this matrix. We have $\mathbf{A} = \mathbf{Q}\mathbf{\Lambda}\mathbf{Q}^{-1}$ where

$$\mathbf{\Lambda} = \begin{bmatrix} 2+i & 0\\ 0 & 2-i \end{bmatrix}, \quad \mathbf{Q} = \begin{bmatrix} i & -i\\ 1 & 1 \end{bmatrix}, \quad \mathbf{Q}^{-1} = \frac{1}{2} \begin{bmatrix} -i & 1\\ i & 1 \end{bmatrix}.$$

We know the complete solution for the above linear differential equation is as follows

$$\mathbf{x}(t) = C_1 e^{(2+i)t} \begin{bmatrix} i\\1 \end{bmatrix} + C_2 e^{(2-i)t} \begin{bmatrix} -i\\1 \end{bmatrix},$$

where by the initial condition we can obtain $C_1 = C_2 = 1$. Hence, we have

$$\mathbf{x}(t) = e^{(2+i)t} \begin{bmatrix} i \\ 1 \end{bmatrix} + e^{(2-i)t} \begin{bmatrix} -i \\ 1 \end{bmatrix}.$$

(b) To find the singular value decomposition, we have

$$\mathbf{A}^{T}\mathbf{A} = \mathbf{V}\mathbf{\Sigma}^{T}\mathbf{U}\mathbf{U}^{T}\mathbf{\Sigma}\mathbf{V}^{T} = \mathbf{V}\mathbf{\Sigma}^{2}\mathbf{V}^{T} = \begin{bmatrix} 5 & 0 \\ 0 & 5 \end{bmatrix}, \quad \mathbf{V} = \mathbf{I},$$

where **I** is the identity matrix. Clearly, we have $\mathbf{A}\mathbf{u}_1 = \sigma_1\mathbf{v}_1$ and $\mathbf{A}\mathbf{u}_2 = \sigma_2\mathbf{v}_2$ where $\sigma_1 = \sigma_2 = \sqrt{5}$. Then we can obtain

$$\mathbf{u}_1 = \frac{\sqrt{5}}{5} \begin{bmatrix} 2\\-1 \end{bmatrix}, \quad \frac{\sqrt{5}}{5} \begin{bmatrix} 1\\2 \end{bmatrix}$$

And therefore,

$$\mathbf{U} = \frac{\sqrt{5}}{5} \begin{bmatrix} 2 & 1\\ -1 & 2 \end{bmatrix}.$$