

Unit 11. Randomized Algorithms

Algorithms

EE3980

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Quick Sort Revisited

- Algorithm Quick Sort (Algorithm 3.2.5) is shown to have average complexity of $\mathcal{O}(n \lg n)$ and is repeated below.

Algorithm 11.1.1. Quick Sort

```
// Sort  $A[low : high]$  into nondecreasing order.
// Input:  $A[low : high]$ , int  $low$ ,  $high$ ; Output:  $A[low : high]$  sorted.
1 Algorithm QuickSort( $A$ ,  $low$ ,  $high$ )
2 {
3     if ( $low < high$ ) then {
4          $mid := partition(A, low, high + 1)$ ;
5         QuickSort( $A$ ,  $low$ ,  $mid - 1$ );
6         QuickSort( $A$ ,  $mid + 1$ ,  $high$ );
7     }
8 }
```

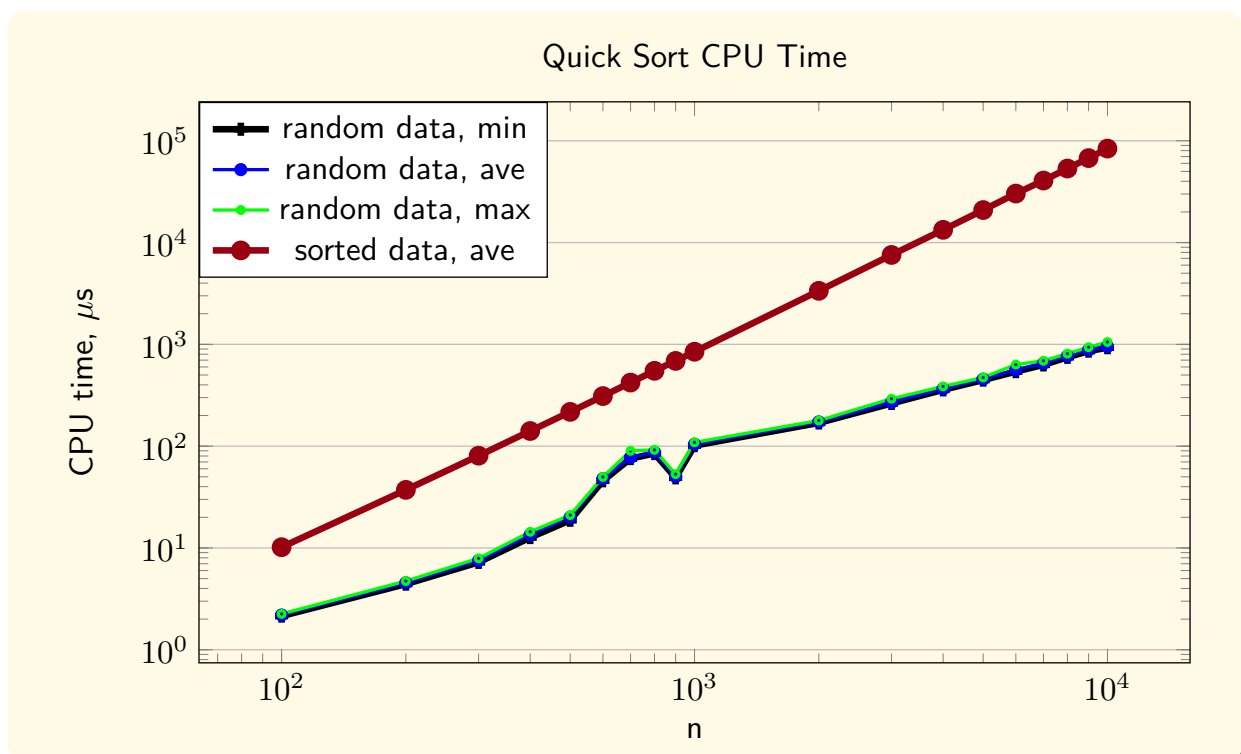
- It is a divide-and-conquer algorithm.
- The divide function **Partition** is repeated as well.
 - It is also known that **Partition** has the worst-case complexity of $\mathcal{O}(n^2)$ and average complexity of $\mathcal{O}(n)$.
 - The latter contributes to Quick Sort's $\mathcal{O}(n \lg n)$ complexity.

Partition Algorithm

Algorithm 11.1.2. Partition

```
// Partition  $A$  into  $A[low : mid - 1] \leq A[mid]$  and  $A[mid + 1 : high] \geq A[mid]$ .  
// Input:  $A$ , int  $low$ ,  $high$ ; Output:  $j$  that  $A[low : j - 1] \leq A[j] \leq A[j + 1 : high]$ .  
1 Algorithm Partition( $A$ ,  $low$ ,  $high$ )  
2 {  
3      $v := A[low]$ ;  $i := low$ ;  $j := high$ ; // Initialize  
4     repeat { // Check for all elements.  
5         repeat  $i := i + 1$ ; until  $(A[i] \geq v)$ ; // Find  $i$  such that  $A[i] \geq v$ .  
6         repeat  $j := j - 1$ ; until  $(A[j] \leq v)$ ; // Find  $j$  such that  $A[j] \leq v$ .  
7         if  $(i < j)$  then Swap( $A$ ,  $i$ ,  $j$ ); // Exchange  $A[i]$  and  $A[j]$ .  
8     } until  $(i \geq j)$ ;  
9      $A[low] := A[j]$ ;  $A[j] = v$ ; // Move  $v$  to the right position.  
10    return  $j$ ;  
11 }  
12 Algorithm Swap( $A$ ,  $i$ ,  $j$ )  
13 {  
14      $t := A[i]$ ;  $A[i] := A[j]$ ;  $A[j] := t$ ;  
15 }
```

Quick Sort CPU times



- QuickSort works well with random data
- However, with pre-sorted data its complexity is shown to be $\mathcal{O}(n^2)$

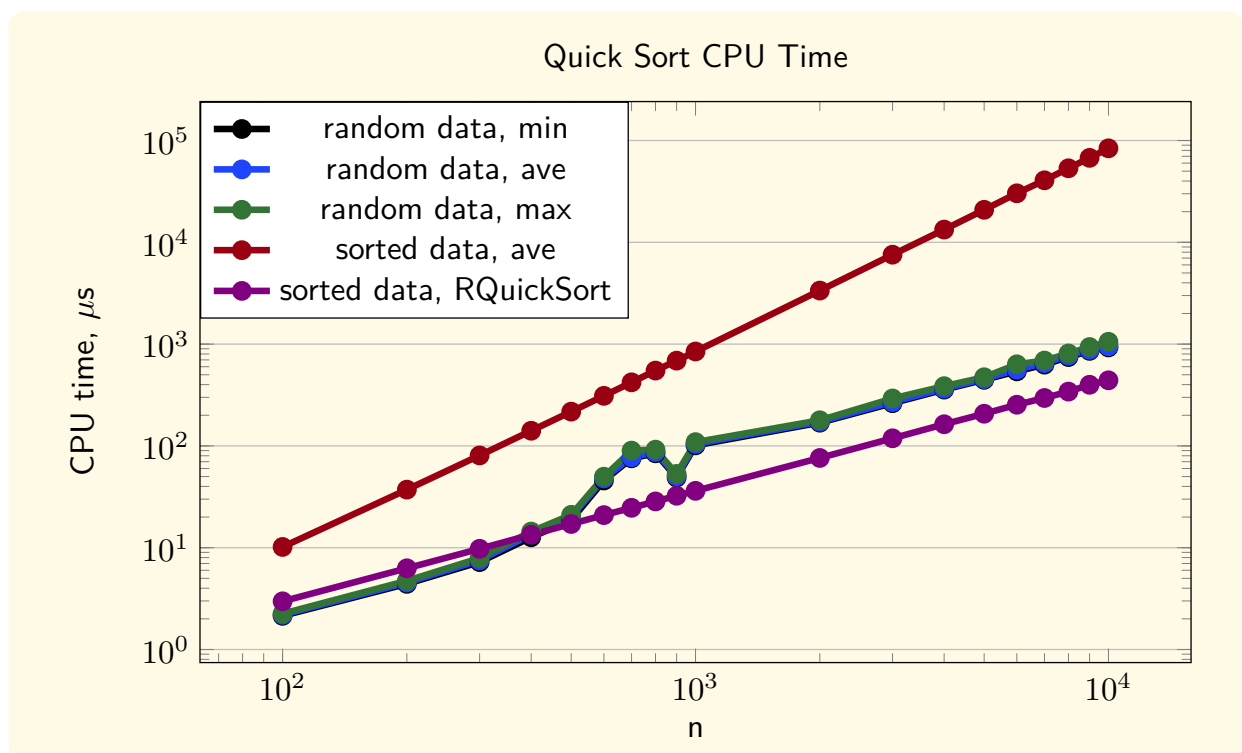
Randomized Quick Sort

- Randomized quick sort (Algorithm 3.2.8), has been proposed to improve the worst-case complexity.

Algorithm 11.1.3. Randomized Quick Sort

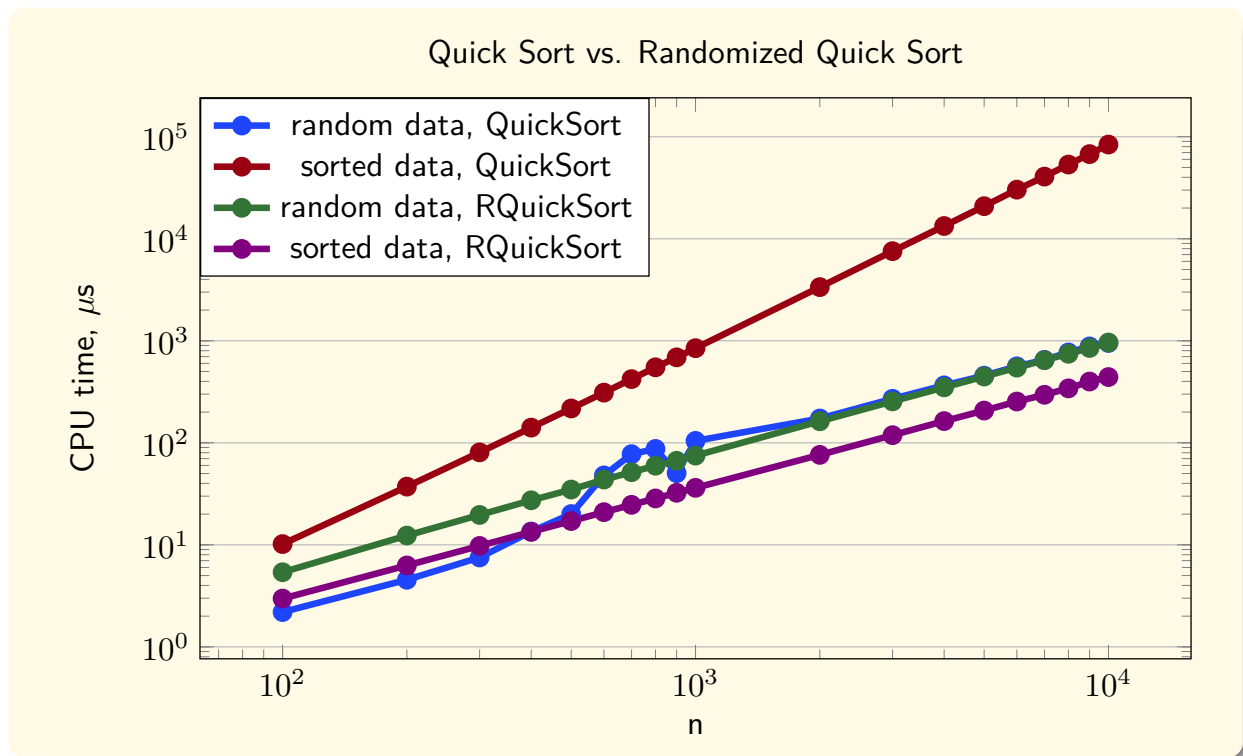
```
// Sort  $A[low : high]$  into nondecreasing order.  
// Input:  $A[low : high]$ , int  $low$ ,  $high$ ; Output:  $A[low : high]$  sorted.  
1 Algorithm RQuickSort( $A, low, high$ )  
2 {  
3   if ( $low < high$ ) then {  
4     if ( $(high - low) > 5$ ) then  
5       Swap( $A, low + (\text{Random}() \bmod (high - low + 1)), low$ );  
6        $mid := \text{Partition}(A, low, high + 1)$ ;  
7       QuickSort( $A, low, mid - 1$ );  
8       QuickSort( $A, mid + 1, high$ );  
9   }  
10 }
```

Randomized Quick Sort CPU times



- RQuickSort is shown to be very effective in improving the time complexity to $\mathcal{O}(n \lg n)$.

Randomized Quick Sort CPU times



- For random data, **RQuickSort** and **QuickSort** have similar CPU times.
- Randomized Quick Sort maintains worst-case complexity to $\mathcal{O}(n \lg n)$.
- Randomized algorithms can be effective in some applications.

Randomized Selection Algorithm

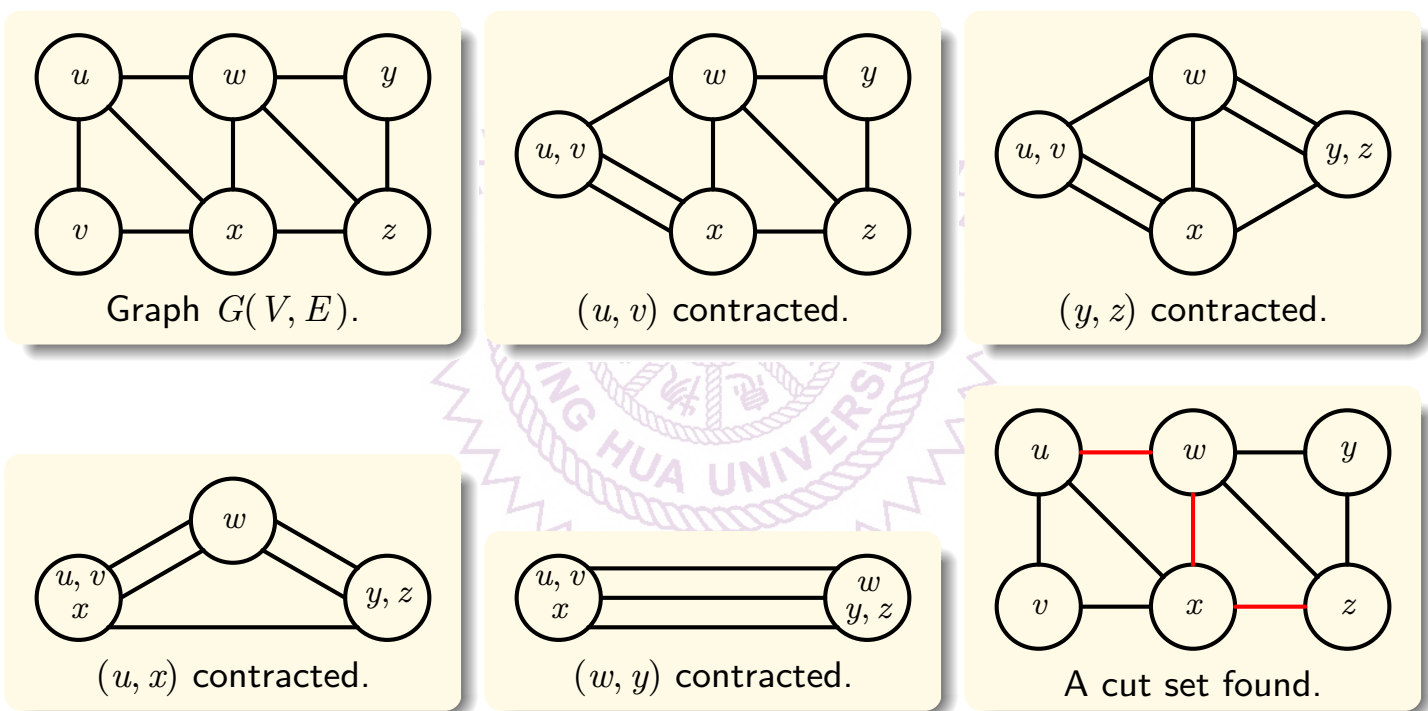
- The **Partition** algorithm is also used in **Select1**, Algorithm (tcb3.3.1).
- Similar randomization technique, **line 5** of Algorithm **RQuickSort** can be applied to improve performance.
- Overall average complexity does not change.
- But, CPU tends to get better with randomization.
 - Chance of getting worst-case performance is very small.
 - Smaller for larger n .

Min-Cut Problem

- Given a undirected graph, $G(V, E)$, $|V| = n$, and $|E| = e$, an **edge cut**, or **cut**, in G is a subset $C \subset E$ such that C 's removal disconnects G into two or more components.
- A **minimum cut** is a cut with minimum $|C|$.
- Given an edge $(u, v) \in E$, $u, v \in V$, (u, v) is **contracted** if vertices u and v are merged into one, all edges connecting u and v are deleted, and all other edges are retained.
- Note that contraction of an edge may result in multiple edges connecting two vertices, but no self-loops, so G may become a multigraph after contraction.

Edge Contraction and a Cut

- Using edge contraction to find a cut set.



- Though a cut set if found, it is not the minimum cut set.

Min-Cut Algorithm

- Using edge contraction, we can find a cut set.
- The following randomized algorithm tries to find a minimum cut set.

Algorithm 11.1.4. Min Cut

```
// Find min-cut given a graph.
// Input:  $G(V, E)$ ; Output: min-cut set  $C \subset E$ .
1 Algorithm MinCut( $V, E, C$ )
2 {
3    $C = E$ ; // Initialize cut set to  $E$ .
4   for  $i := 1$  to  $r$  do { // repeat  $r$  times.
5      $V' := V$ ;  $E' := E$ ; // Initialize  $V'$  and  $E'$ .
6     while ( $|V'| > 2$ ) do { // Contract until two vertices remaining.
7       choose  $(u, v) \in E'$  randomly ;
8       Contract( $V', E', (u, v)$ ); // Perform contraction.
9     }
10    if ( $|E'| < |C|$ ) then  $C := E'$ ; //  $E'$  is a cut set.
11  }
12 }
```

Min-Cut Algorithm Analysis

- When only two vertices remaining in V' (line 6 of (Algorithm 11.1.4), E' is a cut set.
- We will analyze the probability of finding the minimum cut of the inner loop, lines 5-10, of the MinCut algorithm.
- Assuming $|C| = k$, that is, there are k edges in C , then
 1. The minimum vertex degree is k , otherwise removing a smaller number of edges would isolate the vertex which contradicts to the assumption.
 2. The minimum number of edges is then $kn/2$ for G is a undirected graph.
- Since C is the min-cut, the first edge selected cannot be in C , and the probability of not selecting min-cut edge is

$$1 - \frac{k}{kn/2} = 1 - \frac{2}{n}. \quad (11.1.1)$$

- By the same reason, the probability of not selecting the a min-cut edge on the 2nd selection is

$$1 - \frac{k}{k(n-1)/2} = 1 - \frac{2}{n-1}. \quad (11.1.2)$$

Min-Cut Algorithm Analysis, II

- And, for the i -th selection the probability of not selecting a min-cut edge is

$$1 - \frac{k}{k(n-i+1)/2} = 1 - \frac{2}{n-i+1}. \quad (11.1.3)$$

- The loop terminates when there are two vertices left, with $i = n - 2$, and the probability of not selecting edges in C is

$$1 - \frac{k}{k(n - (n - 2) + 1)/2} = 1 - \frac{2}{3}. \quad (11.1.4)$$

- All conditions, Eq. (11.1.1 – 11.1.4), must be met and we have the probability of getting the min-cut set as

$$\begin{aligned} P(C = \text{min-cut}) &= \left(1 - \frac{2}{n}\right) \left(1 - \frac{2}{n-1}\right) \cdots \left(1 - \frac{2}{3}\right) \\ &= \frac{n-2}{n} \cdot \frac{n-3}{n-1} \cdot \frac{n-4}{n-2} \cdots \frac{2}{4} \cdot \frac{1}{3} \\ &= \frac{2}{n(n-1)} \\ &< \frac{2}{n^2}. \end{aligned} \quad (11.1.5)$$

Min-Cut Algorithm Analysis, III

- Thus, the probability of not getting the min-cut in one iteration is

$$1 - \frac{2}{n(n-1)} \geq 1 - \frac{2}{n^2}. \quad (11.1.6)$$

The equality holds for $n \gg 1$.

- The inner loop is repeated r times, and the probability of not getting the min-cut is then

$$\left(1 - \frac{2}{n(n-1)}\right)^r \geq \left(1 - \frac{2}{n^2}\right)^r. \quad (11.1.7)$$

Conversely, the probability of getting min-cut is

$$1 - \left(1 - \frac{2}{n(n-1)}\right)^r \leq 1 - \left(1 - \frac{2}{n^2}\right)^r. \quad (11.1.8)$$

- Setting $r = \frac{n^2}{2}$, assuming large n we have the probability of getting the min-cut be

$$1 - \left(1 - \frac{2}{n^2}\right)^{n^2/2} = 1 - \frac{1}{e}. \quad (11.1.9)$$

The last equation comes from Eq. (1.4.21).

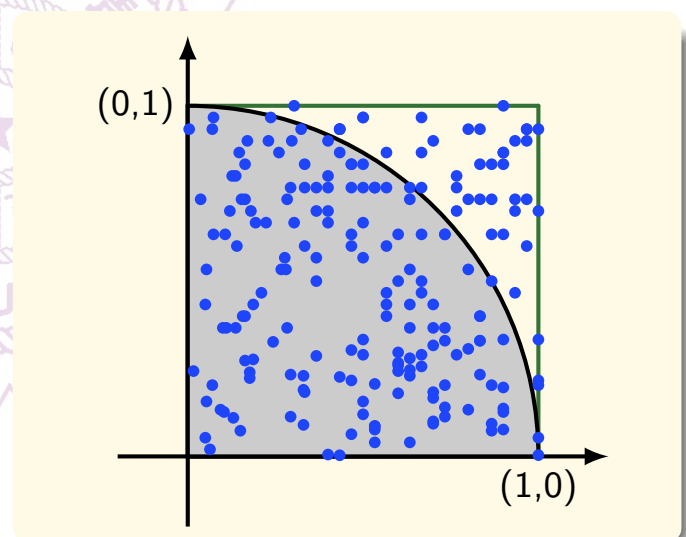
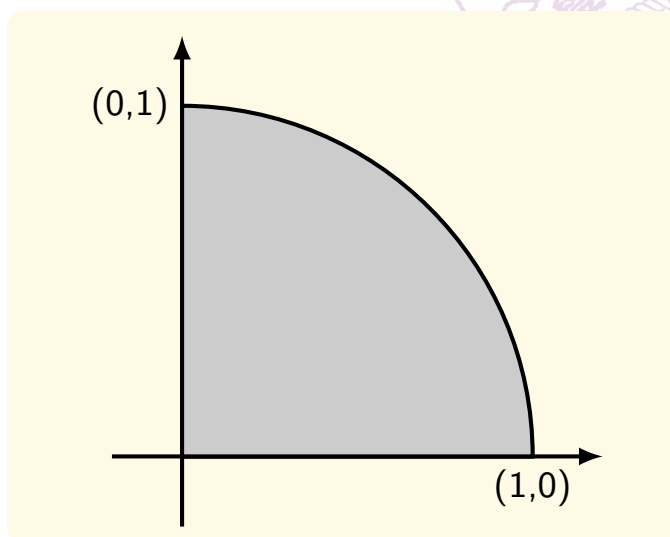
- The overall time complexity is
 - Each **Contract** takes $\mathcal{O}(n)$ operations.
 - $n - 2$ **Contact** performed for one iteration, $\mathcal{O}(n^2)$.
 - Repeating $n^2/2$ times result in $\mathcal{O}(n^4)$ complexity.

Las Vegas vs. Monte Carlo algorithms

- In this **MinCut** randomized algorithm, Algorithm (11.1.4), to find a minimum cutting set, Eq. (11.1.8) shows as the number of iterations increases, the probability of getting the right answer increases as well.
- At the end of each iteration, we have a cut set. But, it is not necessarily the minimum cut set.
- The algorithm can stop for any integer number of iterations, but not guaranteeing the optimal answer.
- This is called the **Monte Carlo** type of randomized algorithm.
- In contrast, the Randomized Quick Sort, Algorithm (11.1.1) always produces the right answer.
- The latter is called the **Las Vegas** type of randomized algorithm.

Monte Carlo Integration

- Closed form solution for integration can be difficult to carry out.
- Numerical integration is usually preferred.
- An alternative approach is the Monte Carlo method.



Monte Carlo Integration – Algorithm

- Given a function $f(x)$, the definite integral is to be solved for.

$$\int_{x=a}^b f(x) dx \quad (11.1.10)$$

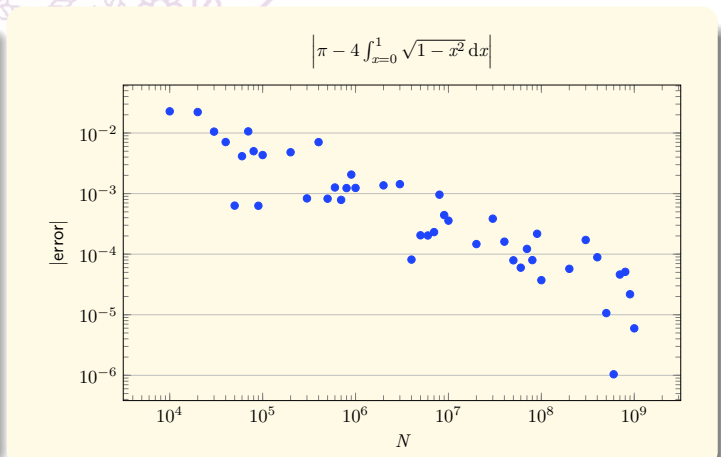
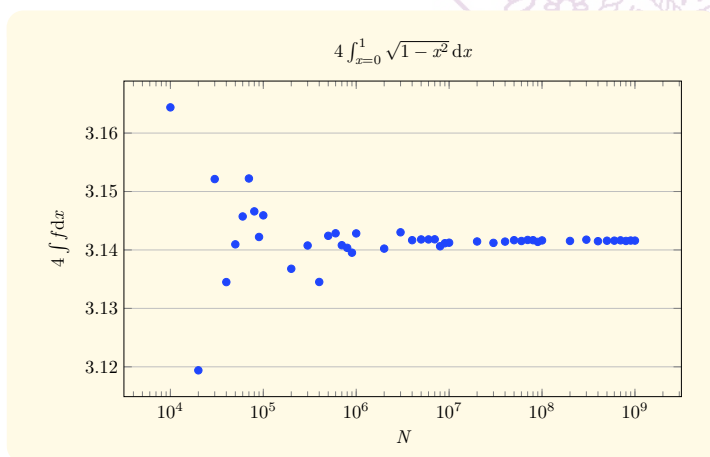
It is assumed that $0 \leq f(x) \leq h$, $a \leq x \leq b$.

Algorithm 11.1.5. Monte Carlo Integration

```
// To find  $\int_{x=a}^b f(x) dx$ ,  $0 \leq f(x) \leq h$ .  
// Input:  $a, b, h$ ; Output: integral.  
1 Algorithm Integrate( $a, b, h$ )  
2 {  
3      $I := 0$ ;  
4     for  $i := 1$  to  $N$  do {  
5          $x := \text{rand}(a, b)$ ;  
6          $y := \text{rand}(0, h)$ ;  
7         if  $y \leq f(x)$  then  $I := I + 1$ ;  
8     }  
9     return  $I/N \times (b - a) \times h$ ;  
10 }
```

Monte Carlo Integration – Analysis

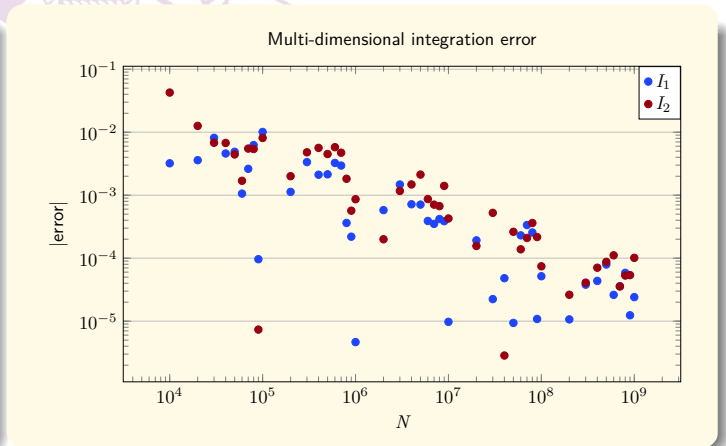
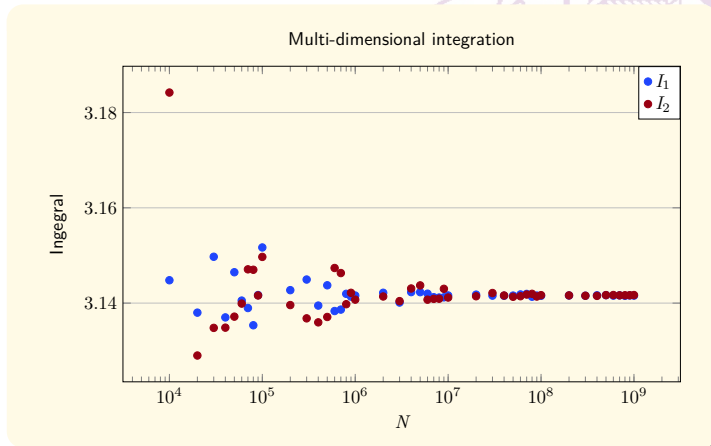
- It is also assumed $\text{rand}(a, b)$ function generates a random number uniformly in the range $[a, b]$.
- The loop, lines 4-8, executes N times, thus the time complexity is $\Theta(N)$.
- As N increases, the function should return value approaches the real integral.



Multi-dimensional Integration

- Multi-dimensional integration can also be implemented easily using Monte Carlo approach.
- For example,

$$I_1 = 4 \int_{x=0}^1 \sqrt{1-x^2} dx, \quad I_2 = 6 \int_{x=0}^1 \int_{y=0}^1 \sqrt{1-x^2-y^2} dx dy$$



Monte Carlo Integration and Random Function

- Monte carlo integration algorithms are very easy to implement.
- Solution accuracy appears to increase with number of samples (N).
 - Error decreases linearly with N , but not monotonically.
- Uniformity of random number distribution affects the accuracy.
 - Choosing a good random number generator is very important.
- Multi-dimensional integration is easily generalized from 1-dimensional integration.
- Monte carlo integration is more effective in multi-dimensional integration problems.
- Lower dimension integrations can use more effective deterministic formulas, such as Newton-Cotes formulas.

Matrix Verification Problem

- Given three $N \times N$ matrices, A , B and C , where C approximates $A \times B$, and we need to find if $C = A \times B$.
- Brute force approach
 1. Find $D = A \times B$,
 2. Check if $C[i, j] = D[i, j]$, $1 \leq i, j \leq N$.
- Step 1 is $\Theta(N^3)$ since $D[i, j] = \sum_{k=1}^N A[i, k] \times B[k, j]$ and there are N^2 elements in D .
- Step 2 is $\Theta(N^2)$ time due to N^2 elements.
- Thus, brute force approach is $\Theta(N^3)$.
 - For large N it can be very time consuming.

Matrix Verification – Monte Carlo Approach

- Matrix verification problem can be solved using [Freivald's technique](#).

Algorithm 11.1.6. Matrix Verification

```
// Given  $N \times N$  matrices  $A$ ,  $B$  and  $C$ , check if  $C = A \times B$ .
// Input:  $A$ ,  $B$ ,  $C$ ,  $N$ ; Output: 1: if  $C = A \times B$ , 0: otherwise.
1 Algorithm MatVerify( $A$ ,  $B$ ,  $C$ ,  $N$ )
2 {
3   for  $i := 1$  to  $N$  do // Generate random vector  $r$ ,  $r[i] = 0$  or  $1$ .
4     if RAND(0, 1) < 0.5 then  $r[i] = 0$ ;
5     else  $r[i] = 1$ ;
6    $x := A \times (B \times r)$ ; // Two matrix-vector multiplications.
7    $y := C \times r$ ; // Matrix vector multiplication.
8   for  $i := 1$  to  $N$  do // Check if  $x = y$ .
9     if  $x[i] \neq y[i]$  then return 0;
10  return 1;
11 }
```

- r is an N -vector with $r[i] = 0$ or 1 , $1 \leq i \leq N$.
- `RAND(0, 1)` generates a random number uniformly in the range $[0, 1]$.

Matrix Verification – Analysis

- In the preceding algorithm, loops on lines 3-5 and 8-9 both execute $\mathcal{O}(N)$ times.
- Lines 6 and 7 consist of 3 matrix-vector multiplications, $\Theta(N^2)$.
- Thus, overall complexity is $\Theta(N^2)$.
 - This is much faster than the brute force approach.

Theorem 11.1.7.

Given three $N \times N$ matrices A , B and C , $A \times B \neq C$ and a randomly generated N -vector r , $r[i] = 0$ or 1 , $1 \leq i \leq N$, then the probability that Algorithm `MatVerify` returns 1 is less than or equal to $1/2$.

Proof. Assume that C and $A \times B$ differs only at $C[i, j]$, then $r[j]$ needs to be 1 such that `MatVerify` would return 0. The chance that $r[j] = 1$ is $1/2$, thus proves the theorem. □

- One call to Algorithm `MatVerify` has the failure rate of $1/2$.
- Repeat the algorithm k times one gets the failure rate $(1/2)^k$.
 - The complexity is still $\Theta(N^2)$ for fixed k .
- Thus, this approach can very effective in verifying matrix equality problem.

Summary

- Quick sort revisited
 - Average-case complexity vs. worst-case
- Randomized quick sort
 - Avoiding worst-case complexity
 - Las Vegas type of randomized algorithm
- Graph min-cut problem
- Randomized integration algorithms
- Matrix verification problem
- Monte Carlo type of randomized algorithms
 - Have been used in solving physics problems