### Unit 2.1 Stack, Queue and Trees



# **Stacks**

A stack is a linear list that can store elements to be fetched later, and the element fetched from the stack is the last one stored.

```
Last In First Out (LIFO).
```
- Stack can be implemented using a simple array and an integer that represents the top position.
- Assume the array is *stack*[1 : *n*] with *n* elements and the stack index is *top*, which is initialized to 0.
- The following algorithm inserts an element into the stack.

#### Algorithm 2.1.1. Stack Push – Array

```
// Push an element into the stack.
  // Input: item to be inserted; Output: none.
1 Algorithm StkPush(item)
2 {
3 if (top \ge n) then error ("Stack is full! ");<br>4 else {
      else \{5 top := top + 1;
6 stack[top] := item; // Store item.
7 }
8 }
```
# Stack — Pop

• To fetch an item from the stack.

#### Algorithm 2.1.2. Stack Pop – Array

```
// Pop the top element from the stack and return its value.
  // Input: none; Output: item on top of the stack.
1 Algorithm StkPop()
2 {
3 if (top < 1) then error ("Stack is empty!");
4 else {
5 item := stack[top];
6 top := top - 1;<br>7 return item :
           7 return item ;
8 }
9 }
```
• Both StkPush and StkPop algorithms have the time complexity of  $\mathcal{O}(1)$ 

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- $\bullet$  It is independent of the size of the stack,  $n$ .
- And also independent of the number of items stored, *top*.

# Stack — Status Check

Two functions are useful to check the status of the stack.

### Algorithm 2.1.3. Stack Empty Check

```
// Check if the stack is empty.
  // Input: none; Output: true if stack empty otherwise false.
1 Algorithm StkEmpty()
2 {
3 if (top = 0) then return true;
4 else return false ;
5 }
```
### Algorithm 2.1.4. Stack Full Check

```
// Check if the stack is Full.
  // Input: none; Output: true if stack full otherwise false.
1 Algorithm StkFull()
2 {
3 if (top = n) then return true;
4 else return false ;
5 }
```
### Stack — Dynamically Allocated Array

- The array *stack* can be either a static array or a dynamically allocated array.
- Using static array, then the number of items to be stored is limited by the size, *n*, of the array.
- Using a dynamically allocated array, the array size, *n*, can be enlarged and then employ the realloc function to adjust the stack space.
	- This is more flexible to handle problems in different sizes.
- **•** Stack can also be implemented using linked list
- Assuming NODE is a structure defined as

```
struct NODE {
   TYPE data; // for data storage
   struct NODE *link; // pointer to the next node
}
```
NODE pointer *LStack* is now the linked list to store the items. *LStack* is initialized to NULL.

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- **•** The variable *top* is no longer needed.

### Stacks in Linked List

```
Algorithm 2.1.5. Stack Push – Linked List
```

```
// Push an element into the stack.
    // Input: item to be inserted; Output: none.
  1 Algorithm LStkPush(item)
  2 {
  3 \qquad temp := new NODE;4 temp \rightarrow data := item; temp \rightarrow link := LStack;5 LStack := temp;6 }
Algorithm 2.1.6. Stack Pop – Linked List
    // Pop the top element from the stack and return its value.
    // Input: none; Output: item on top of the stack.
  1 Algorithm LStkPop()
  2 {
  \exists if (LStack = NULL) then error ("Stack is empty!");
  4 else {
  5 item := LStack \rightarrow data; temp := LStack; LStack := temp \rightarrow link;<br>6 free temp: return item :
              6 free temp ; return item ;
  7 }
  8<sup>°</sup>
```
- With enough computer resources, stack implemented using linked list should not have stack full issue.
	- Thus, no StkFull check is needed.
- Stack empty check is equivalent to check if *LStack* is NULL.
- Again, either LStkPush or LStkPop algorithm is of  $\mathcal{O}(1)$  time complexity.
	- Independent to stack size or the number of items stored.
- The space complexity of the array stack is  $\Theta(n)$ , where *n* is the size of the array.
- The space complexity of linked list stack is Θ(*m*), where *m* is the number of items stored.
- The linked list stack appears to be more memory efficient, since  $m < n$ .

#### Queue

Queue is another linear list to store data, but the data fetched is the first one stored.

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- First in First out (FIFO).
- Queue can also be implemented using simple array.
- Assume the array is *Q*[1 : *n*] with *n* elements.
	- Two integer variables: *head* for the front of the queue, and *tail* for the rear of the queue.
- The following algorithm stores an item onto the queue.

#### Algorithm 2.1.7. Enqueu.

```
// Insert the item into the queue.
  // Input: item to be inserted; Output: none.
1 Algorithm Enqueue(item)
2 {
3 tail := (tail + 1) \text{ mod } n;4 if (head = tail) then error (" Queue is full! ");
5 else {
6 Q[tail] := item;7 }
8 }
```
#### Queue, II Algorithm 2.1.8. Queue Empty. // Check if the queue is empty or not. // Input: none; Output: *true* if queue is empty otherwise *false*. 1 Algorithm EmptyQ() 2 { 3 if (*head* = *tail*) then return true ; 4 else return false ; 5 } Algorithm 2.1.9. Dequeue. // Retrieve the item from the queue. // Input: none; Output: the first *item* of the queue. 1 Algorithm Dequeue() 2 { 3 if  $Empty(Q()$  then error ("Queue is empty!"); 4 else { 5  $head := (head + 1) \mod n;$ 6  $item := Q[head]$ ; 7 return *item* ; 8 }  $\overline{9}$ Algorithms (Stack, queue and trees) Unit 2.1 Stack, Queue and Trees Mar. 7, 2019

# Stack and Queue

- Time complexities of both Enqueue() and Dequeue() algorithms are  $\mathcal{O}(1)$ .
	- Space complexities are  $\Theta(n)$ , *n* is the size of the array *Q*.
- Queue also can be implemented using linked list
- Both stack and queue are useful data structures to store temporary data.
	- Storing and retrieving data are very efficient.
- Stack is Last In First Out
	- A simple array with an addition variable is sufficient.
- Queue is First In First Out
	- An simple array with two additional variables.
	- The array elements are used in a circular fashion.
	- Enlarging queue size is a little more complicated than stack.
- Both can also be implemented using linked lists.
	- Space utilization is more efficient.
	- Time complexity remains the same.
- A group of *n* persons have been gathered. There might be a celebrity in the group such that everyone knows the celebrity while the celebrity knows no one. Is there a way to identify the celebrity quickly?
- The relationship of the persons of the group can be represented by an  $n \times n$ matrix, A, such that if person *i* knows person *j* then  $A[i, j] = 1$ , otherwise  $A[i, j] = 0$ . For simplicity,  $A[i, i] = 1$  is also assumed.
- **•** If person *k* is the celebrity, then we have  $A[i, k] = 1, 1 \le i \le n$ , and  $A[k, j] = 0, 1 \leq j \leq n$  and  $j \neq k$ .

$$
A[i,k]=1, \qquad 1 \leq i \leq n, \qquad (2.1.1)
$$

$$
A[k,j] = 0, \qquad 1 \le j \le n \text{ and } j \ne k. \tag{2.1.2}
$$

• The brute force approach is to check all  $A[i, j]$ ,  $1 \leq i, j \leq n$  against the equations (2.1.1) and (2.1.2).

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It is apparent the brute force approach is  $\mathcal{O}(n^2)$ .

# Celebrity Problem, II

• An alternative to identifying the celebrity is

#### Algorithm 2.1.10. Celebrity Identification – Generic Algorithm

```
// Given n \times n matrix A find the celebrity satisfies Eqs (2.1.1) and (2.1.2).
   // Input: Array A, int n; ; Output: Celebrity k, or "None".
 1 Algorithm Celebrity(A, n)
 2 {
 3 Form a set S := \{1, 2, \dots, n\}; // S initialized to n elements.
 4 while |S| > 1 do \{ / / S has more then one element.<br>5 choose two elements u, v \in S:
              choose two elements u, v \in S;
 6 if A[u, v] = 1 then S := S - \{u\}; // Remove u.<br>7 else S := S - \{v\}; // Remove v.
              else S := S - \{v\}; // Remove v.
 8 }
 9 let k be the only element in S; // k is the candidate for celebrity.
10 for i := 1 to n do // Verify k is the celebrity.
11 if i \neq k then {<br>12 if A[i, k] \neqif A[i, k] \neq 1 or A[k, i] \neq 0 then return "None";
13 }
14 return k ;
15 }
```
- In Algorithm  $(2.1.10)$  line 6,  $A[u, v]$  is checked.
	- $\bullet$  If  $A[u, v] = 1$  then *u* cannot be the celebrity therefore it is removed from set *S*;
	- $\bullet$  On the other hand, if  $A[u, v] = 0$  then *v* is not the celebrity and is removed.
- Therefore, each iteration of the loop (lines 4–8) one element is removed from *S*.
	- After *n* − 1 iterations, one element is left and it should be a candidate for the celebrity.

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- **•** The complexity is  $\Theta(n)$ .
- Lines 10–13 verify if the candidate is, indeed, the celebrity.
	- **•** The complexity is  $\Theta(n)$ .
- **•** Thus, the total complexity is  $\Theta(n)$ .
- In fact, matrix *A* is accessed  $3(n-1)$  times over all.

# Celebrity Identification using Array

Algorithm (2.1.10) can be implemented using array for *S* as

#### Algorithm 2.1.11. Celebrity Identification – Using Array

```
// Given n \times n matrix A find the celebrity satisfies Eqs (2.1.1) and (2.1.2).
   // Input: Array A, int n; ; Output: Celebrity k, or "None".
 1 Algorithm Celebrity_A(A, n)
 2 {
 3 for i := 1 to n do S[i] := i; // Initialize array S.
 4 u := 1; v := n;
 5 while u < v do \frac{1}{s} // S has more than one element left.
 6 if A[u, v] = 1 then u := u + 1; // Remove u.
 7 else v := v − 1 ; // Remove v.
 8 }
 9 k := u; \frac{1}{k} is the candidate for celebrity.
10 for i := 1 to n do // Verify k is the celebrity.
11 if i \neq k then {<br>12 if A[i, k] \neqif A[i, k] \neq 1 or A[k, i] \neq 0 then return "None";
13 }
14 return k ;
15 }
```
### Celebrity Identification using Stack

Algorithm (2.1.10) can be implemented using stack for *S* as

### Algorithm 2.1.12. Celebrity Identification – Using Stack

```
// Given n \times n matrix A find the celebrity satisfies Eqs (2.1.1) and (2.1.2).
   // Input: Array A, int n; ; Output: Celebrity k, or "None".
 1 Algorithm Celebrity_S(A, n)
 2 {
 3 for i := 1 to n do StkPush(i); // Initialize stack.
 4 for i := 1 to n - 1 do \frac{1}{1} Repeat n - 1 times
 5 u := \text{StkPop}(x); v := \text{StkPop}(x);
 6 if A[u, v] = 1 then \text{StkPush}(v); // Remove u.
7 else StkPush(u) ; // Remove v.
8 }
9 k := StkPop(); // k is the candidate for celebrity.
10 for i := 1 to n do // Verify k is the celebrity.
11 if i \neq k then {
12 if A[i, k] \neq 1 or A[k, i] \neq 0 then return "None";
13 }
14 return k ;
15 }
```
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# Celebrity Identification using Queue

Algorithm (2.1.10) can be implemented using queue for *S* as

### Algorithm 2.1.13. Celebrity Identification – Using Queue

```
// Given n \times n matrix A find the celebrity satisfies Eqs (2.1.1) and (2.1.2).
   // Input: Array A, int n; ; Output: Celebrity k, or "None".
 1 Algorithm Celebrity_Q(A, n)
 2 {
 3 for i := 1 to n do Enqueue(i); // Initialize stack.
 4 for i := 1 to n - 1 do \frac{1}{2} Repeat n - 1 times<br>5 u := \text{Dequeue}(): v := \text{Dequeue}():
              u := Dequeue(); v := Dequeue();
 6 if A[u, v] = 1 then Enqueue(v); // Remove u.
 7 else Enqueue(u) ; // Remove v.
 8 }
 9 k := \text{Dequeue}(); // k is the candidate for celebrity.
10 for i := 1 to n do // Verify k is the celebrity.
11 if i \neq k then {<br>12 if A[i, k] \neqif A[i, k] \neq 1 or A[k, i] \neq 0 then return "None";
13 }
14 return k ;
15 }
```
- Algorithms Celebrity A (2.1.11), Celebrity S (2.1.12) and Celebrity Q  $(2.1.13)$  implement Algorithm Celebrity<sub>\_G</sub>  $(2.1.10)$  using different data structures for *S*.
- All of them have the same time complexity Θ(*n*).
- In Algorithm Celebrity  $A(2.1.11)$  if  $u$  or  $v$  is the candidate, then it is not changed for the rest of the iterations.
- In Algorithm Celebrity S (2.1.12) if the candidate has been popped from the stack, it also remains on top of the stack for the rest of the iterations.
- In Algorithm Celebrity Q (2.1.13), however, the candidate is enqueued to the end of the queue.

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• The candidate is evaluated at most  $\lceil \lg n \rceil$  times.

### Summary

- **•** Stacks and queues
	- Insert, delete and status check
	- Array and linked list representations
- Celebrity problem
	- With array
	- With stack
	- With queue