

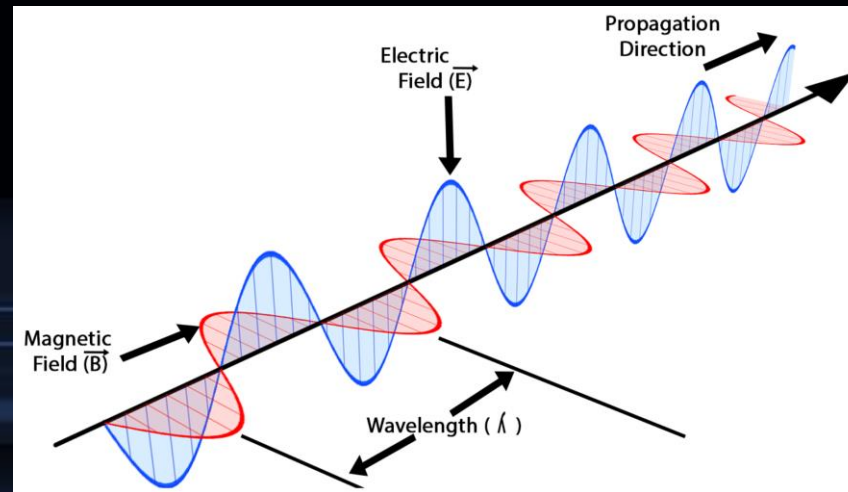
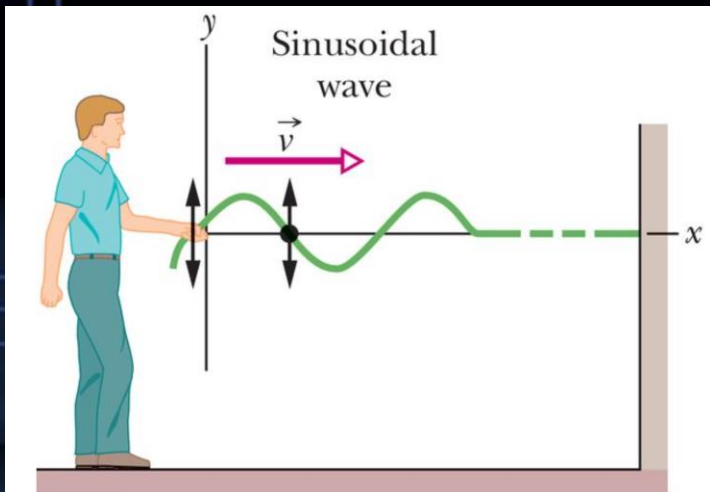
# Course announcement

- Homework set 3 will be posted on eLearn today. It will be due on 11/18 Friday at 5PM.

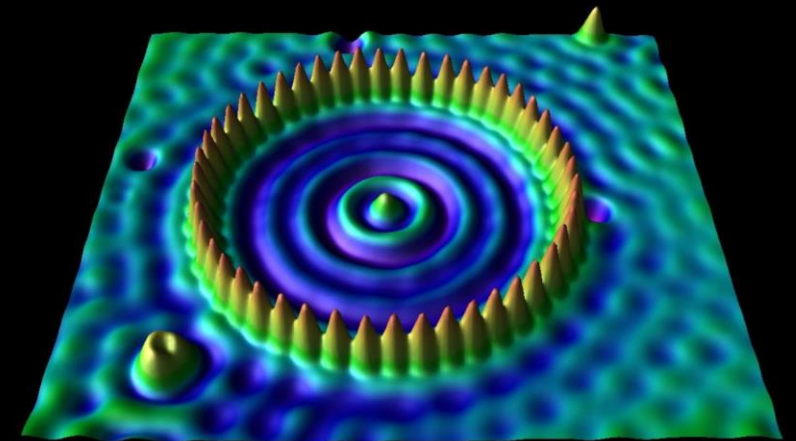
10	11/15(Tue.)	<b>Oscillation and Waves:</b> description of waves
10	11/18(Fri.)	<b>Oscillation and Waves:</b> interference of waves
11	11/22(Tue.)	<b>Oscillation and Waves:</b> propagation of waves
11	11/25(Fri.)	<b>Fluid Motion:</b> Density, Pressure, and Hydrostatic Equilibrium ( <a href="#">Homework4</a> )

# Different types of waves

- Waves are of three main types:  
Mechanical waves.  
Electromagnetic waves.  
Matter waves.



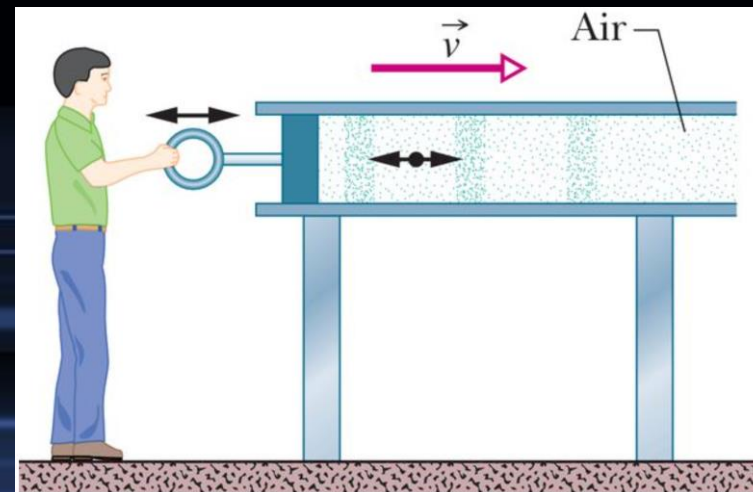
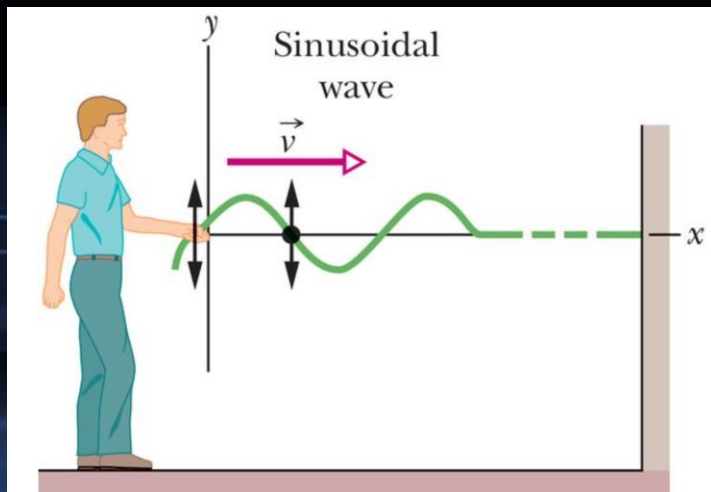
[https://commons.wikimedia.org/wiki/File:Electromagnetic\\_waves.png](https://commons.wikimedia.org/wiki/File:Electromagnetic_waves.png)



<https://www.nisenet.org/catalog/scientific-image-quantum-corrall-top-view>

# Transverse and Longitudinal Waves

- Transverse waves: the displacement of every oscillating element is perpendicular to the direction of travel of the wave.
- Longitudinal waves: the displacement of the oscillating elements is parallel to the direction of the wave's travel.



# Description of wave

- Use wave on a string as an example. Imagine a sinusoidal wave traveling in the positive direction of an x axis. The elements oscillate parallel to the y axis. At time t, the displacement  $y(x,t)$  of the element located at position x is given by

The diagram shows the equation  $y(x,t) = y_m \sin(kx - \omega t)$  with various parts labeled. The word "Displacement" is written in green above the entire equation. "Amplitude" is written in green above  $y_m$ . "Oscillating term" is written in green above the sine function. "Phase" is written in green above the argument of the sine function,  $(kx - \omega t)$ . "Angular wave number" is written in blue below  $k$ . "Position" is written in blue below  $x$ . "Time" is written in blue below  $t$ . "Angular frequency" is written in blue below  $\omega$ .

$$y(x,t) = y_m \sin(kx - \omega t)$$

# GENERAL PHYSICS B1

## OSCILLATION & WAVE

Damped, Forced Oscillation, and Wave

2022/11/11

# Today's topic

- Description of Wave
- Wave speed on a stretched string
- Wave equation

# Description of wave

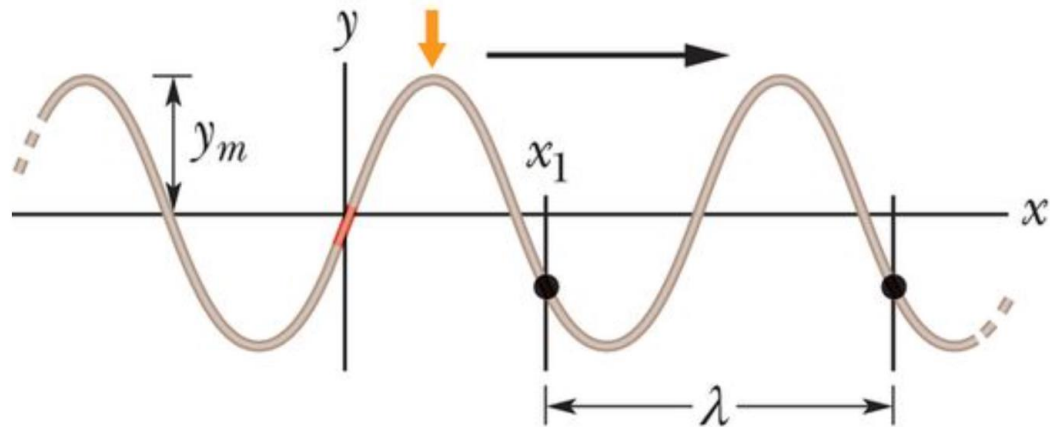
- Use wave on a string as an example. Imagine a sinusoidal wave traveling in the positive direction of an x axis. The elements oscillate parallel to the y axis. At time t, the displacement  $y(x,t)$  of the element located at position x is given by

The diagram shows the equation  $y(x,t) = y_m \sin(kx - \omega t)$  with various parts labeled. The word "Displacement" is written in green above the entire equation. "Amplitude" is written in green above  $y_m$ . "Oscillating term" is written in green above the sine function. "Phase" is written in green above the argument of the sine function,  $(kx - \omega t)$ . "Angular wave number" is written in blue below  $k$ . "Position" is written in blue below  $x$ . "Time" is written in blue below  $t$ . "Angular frequency" is written in blue below  $\omega$ .

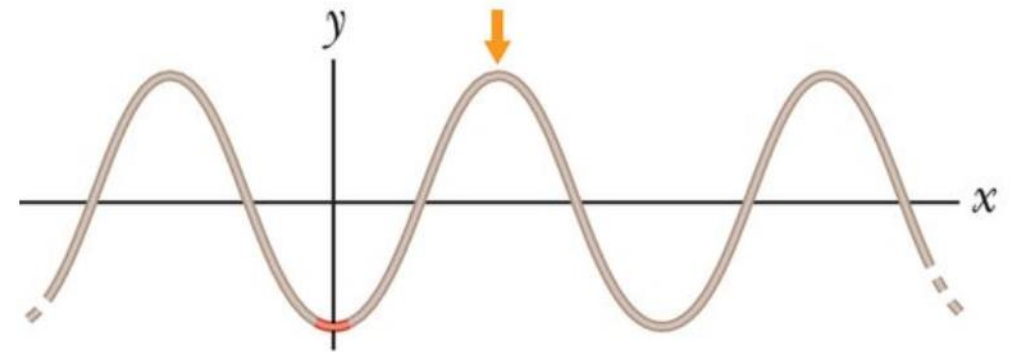
$$y(x,t) = y_m \sin(kx - \omega t)$$



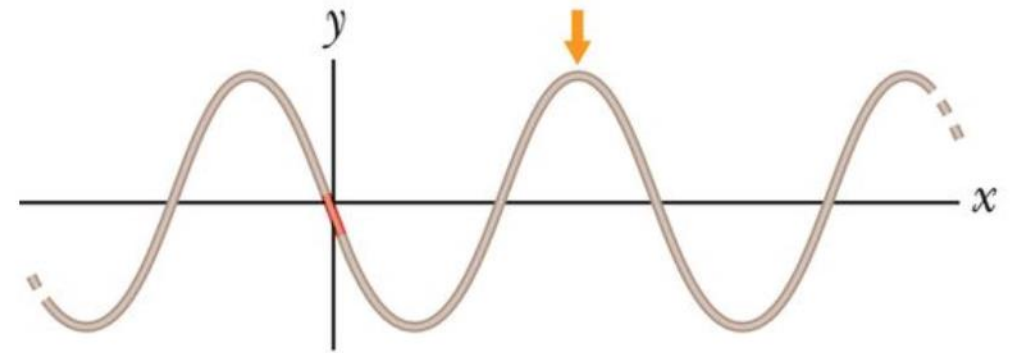
Watch this spot in this series of snapshots.



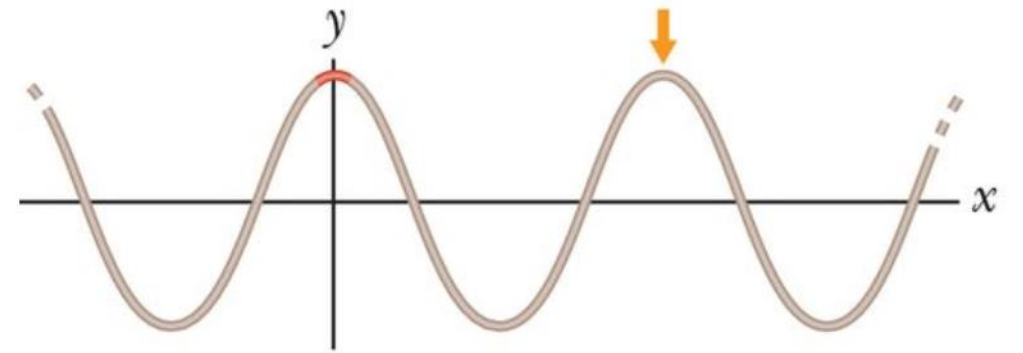
- $k = \frac{2\pi}{\lambda}$  (angular wave number)
- phase of the wave is the *argument* ( $kx - \omega t$ ) of the sine: a wave traveling to positive  $x$  direction



(b)

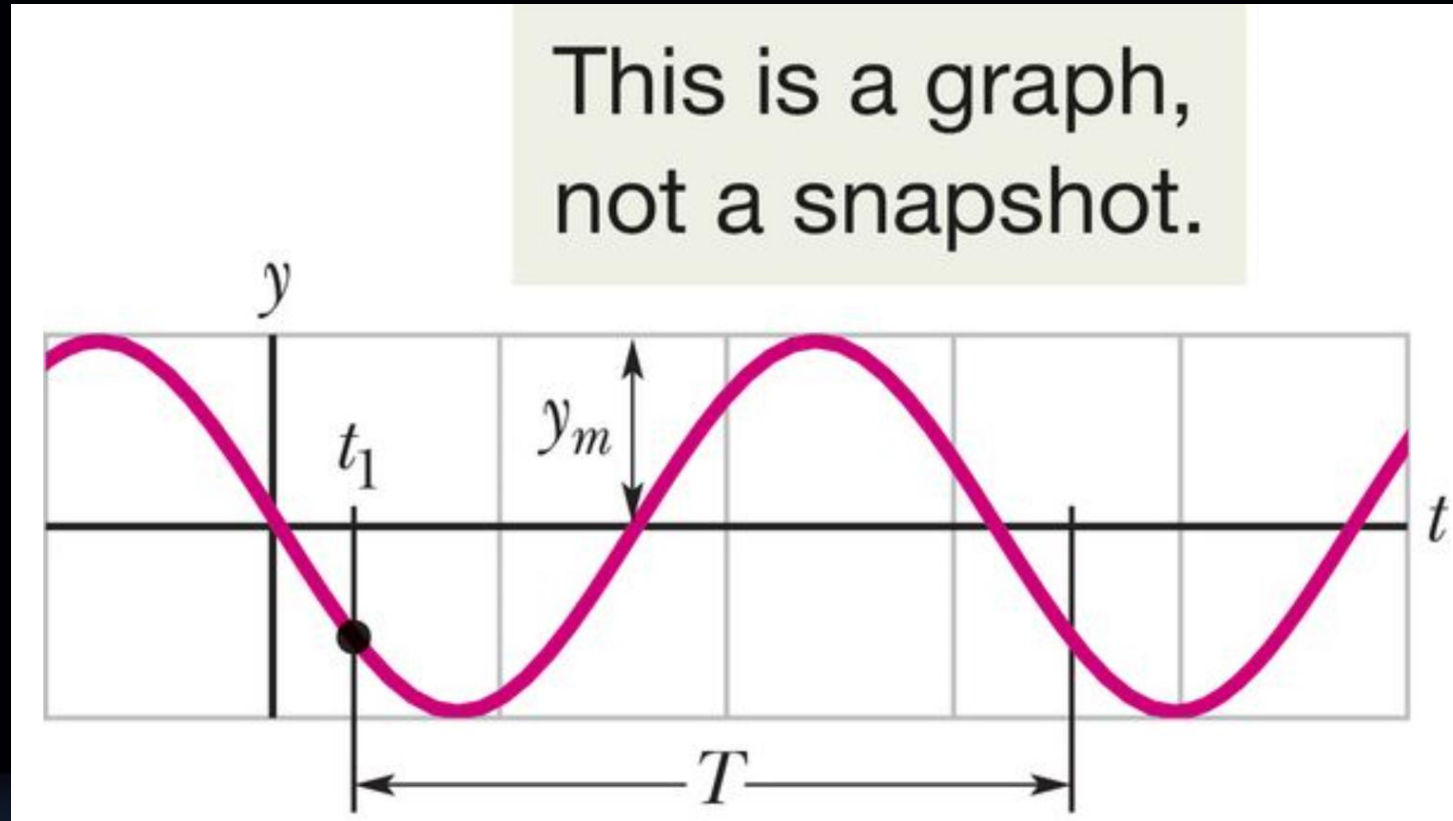


(c)



(d)

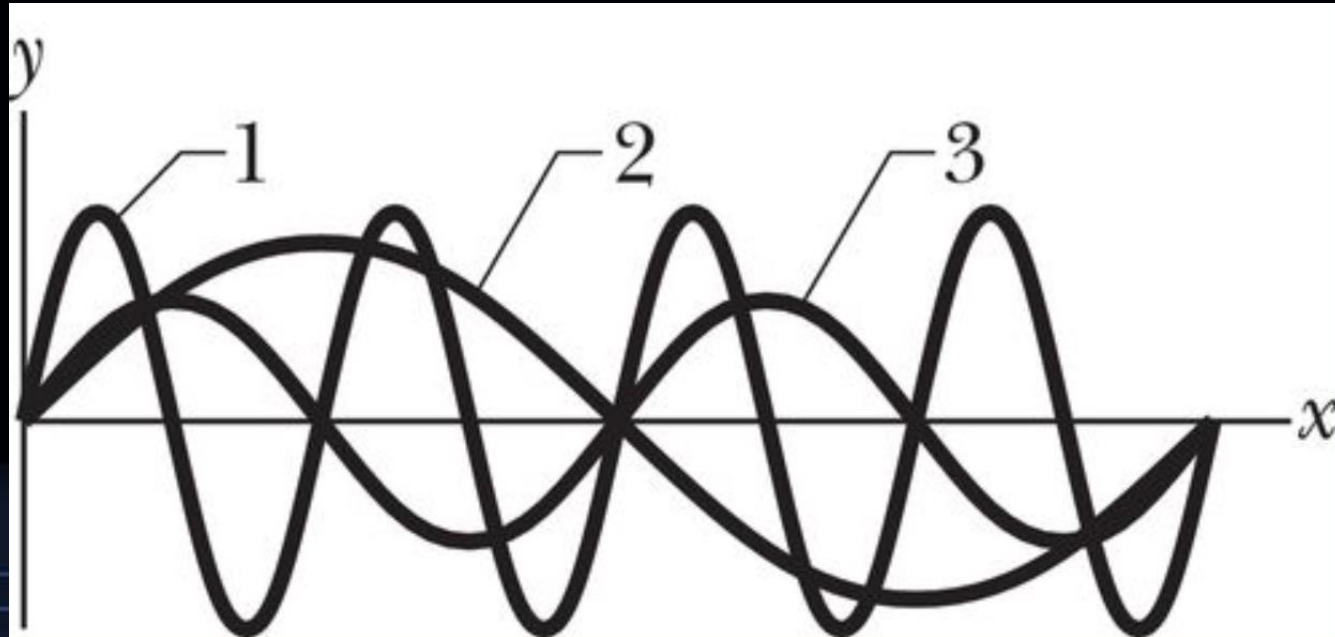
# Angular frequency and frequency of wave



- $\omega = \frac{2\pi}{T}$  (angular wave frequency)
- $f = \frac{1}{T} = \frac{\omega}{2\pi}$  (frequency)

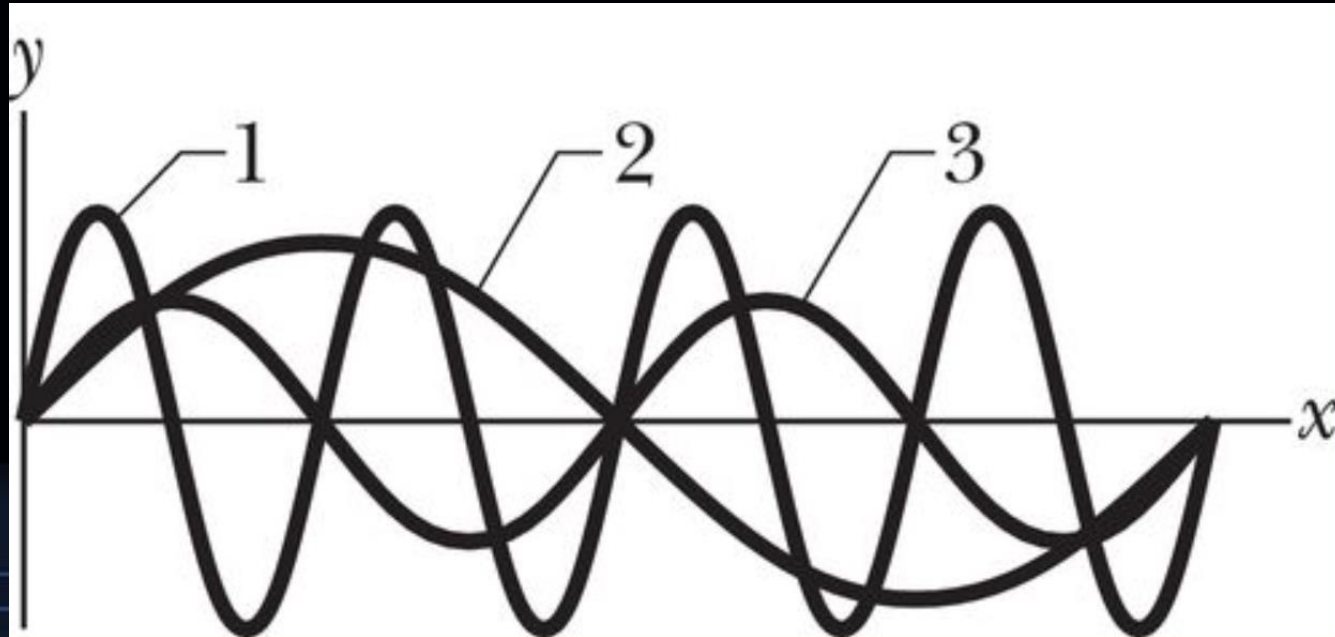
# Example

The phases for the waves are given by (a)  $2x - 4t$ , (b)  $4x - 8t$ , and (c)  $8x - 16t$ . Which phase corresponds to which wave in the figure?



# Example

The phases for the waves are given by (a)  $2x - 4t$ , (b)  $4x - 8t$ , and (c)  $8x - 16t$ . Which phase corresponds to which wave in the figure?



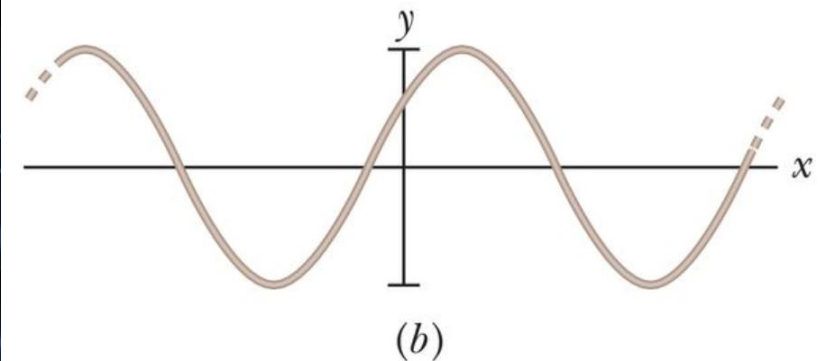
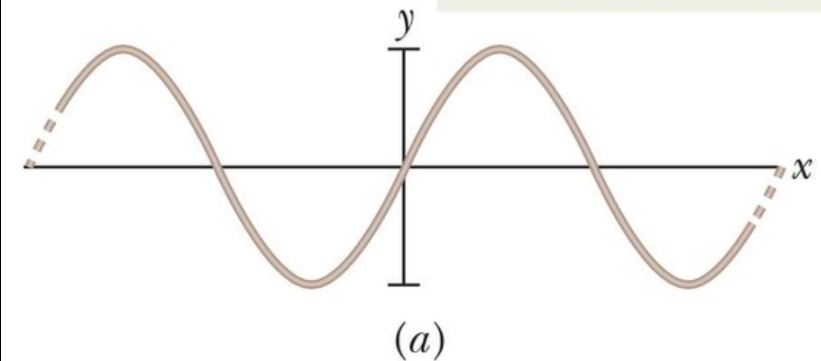
Ans: 1-(c), 2-(a), and 3-(b).  $k = \frac{2\pi}{\lambda}$ : longer wavelength, smaller k

# The phase constant

- A value of  $\phi$  can be chosen so that the function gives some other displacement and slope at  $x = 0$  when  $t = 0$ .

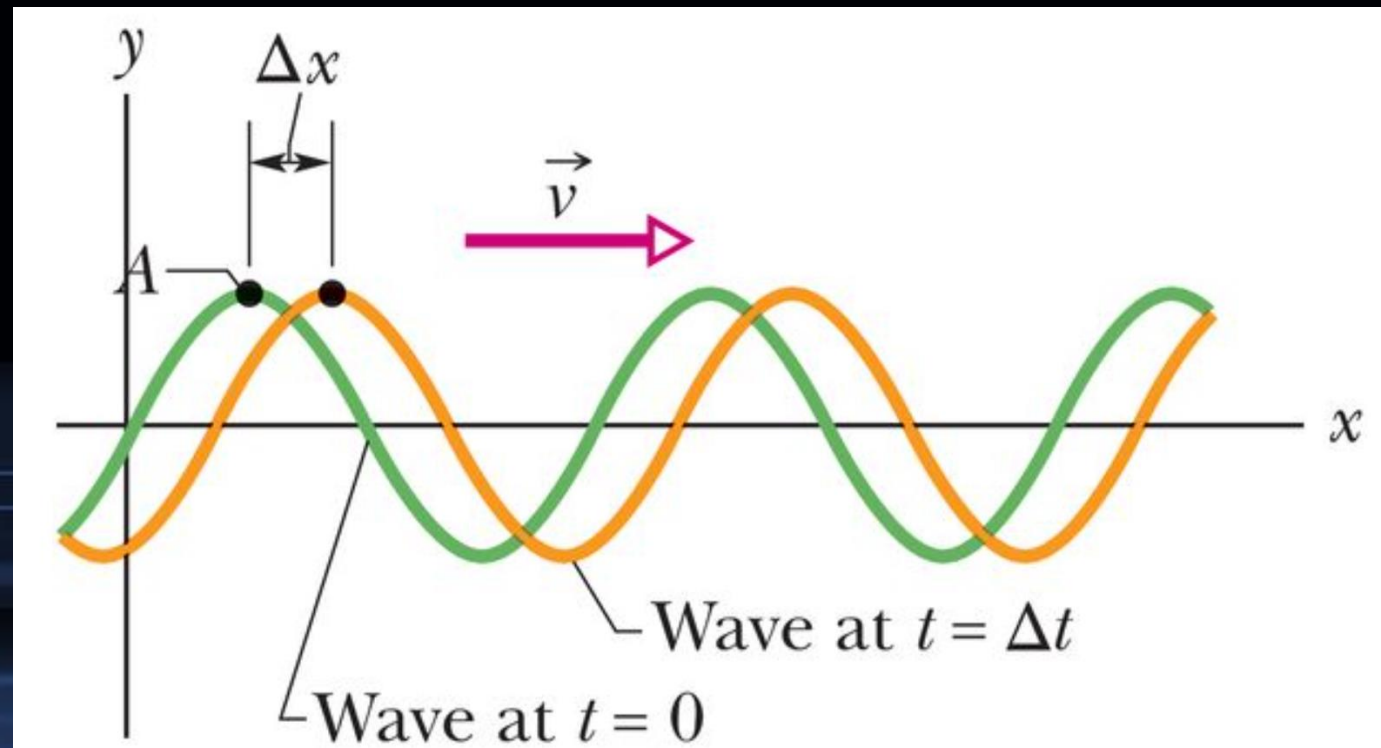
$$y = y_m \sin(kx - \omega t + \phi)$$

The effect of the phase constant  $\phi$  is to shift the wave.



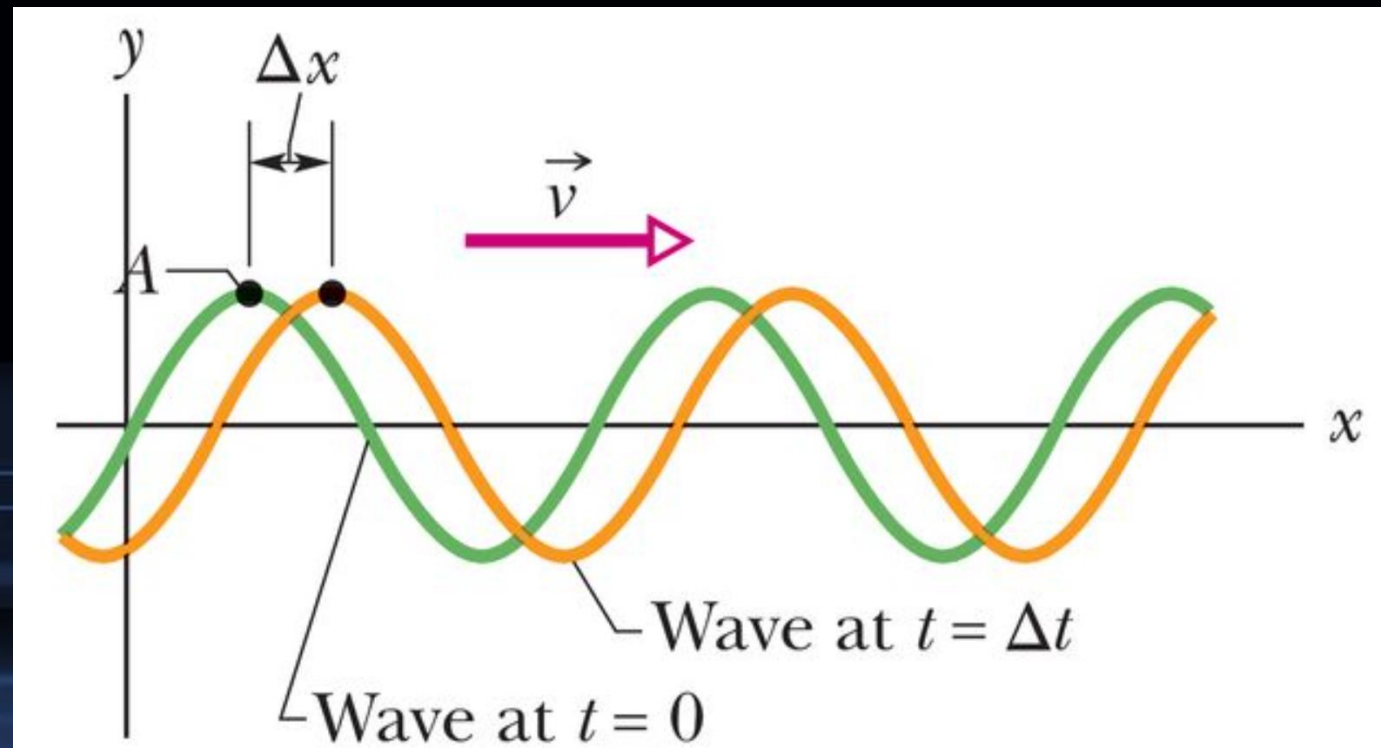
# The speed of a traveling wave

- The wave is traveling in the positive direction of  $x$ , the entire wave pattern moving a distance  $\Delta x$  in that direction during the interval  $\Delta t$ . The ratio  $\Delta x/\Delta t$  (or, in the differential limit,  $dx/dt$ ) is the wave speed  $v$ .



# The speed of a traveling wave

- If point A retains its displacement as it moves, the phase must remain a constant:  $kx - \omega t = \text{constant}$ .
- Thus the wave speed is  $\frac{dx}{dt} = v = \frac{\omega}{k} = \frac{\lambda}{T} = \lambda f$



# Direction of wave propagation

- With the concept of wave speed, one can find that:

$$y(x, t) = y_m \sin(kx - \omega t + \phi)$$

is a wave traveling to positive x direction with positive wave speed  $v = \frac{\omega}{k}$ .

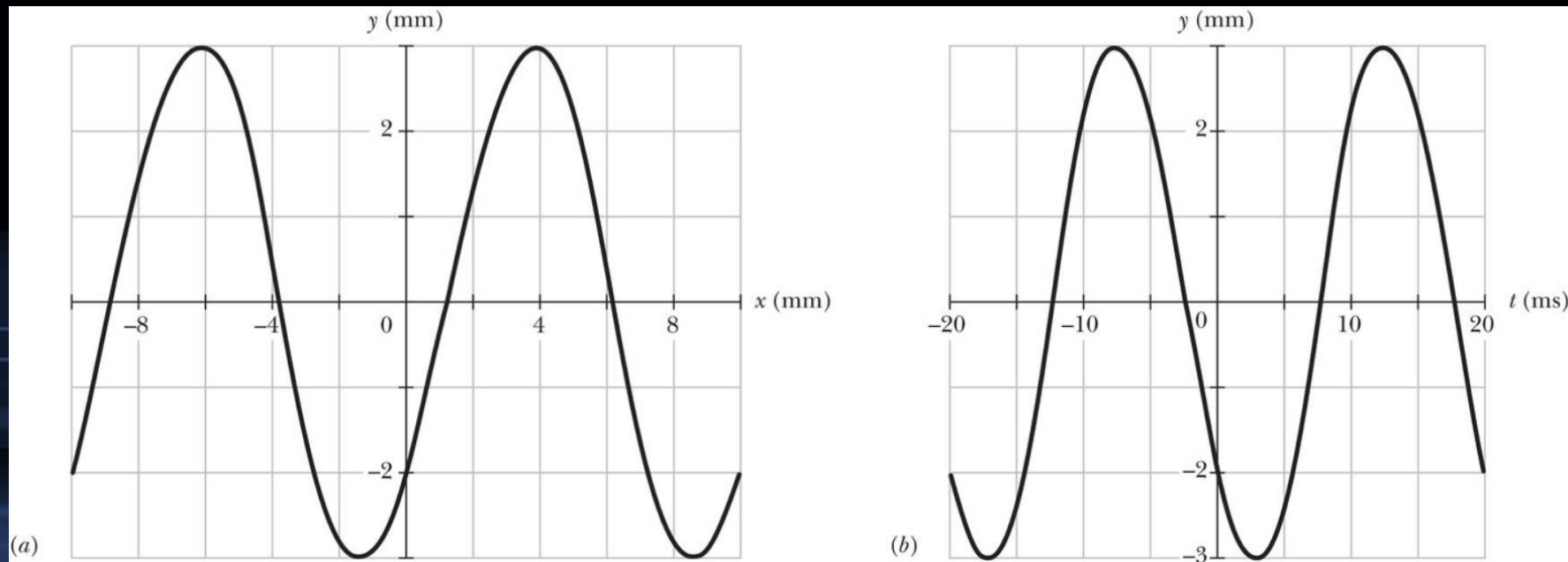
$$y(x, t) = y_m \sin(kx + \omega t + \phi)$$

is a wave traveling to negative x direction with negative wave speed  $v = -\frac{\omega}{k}$ .

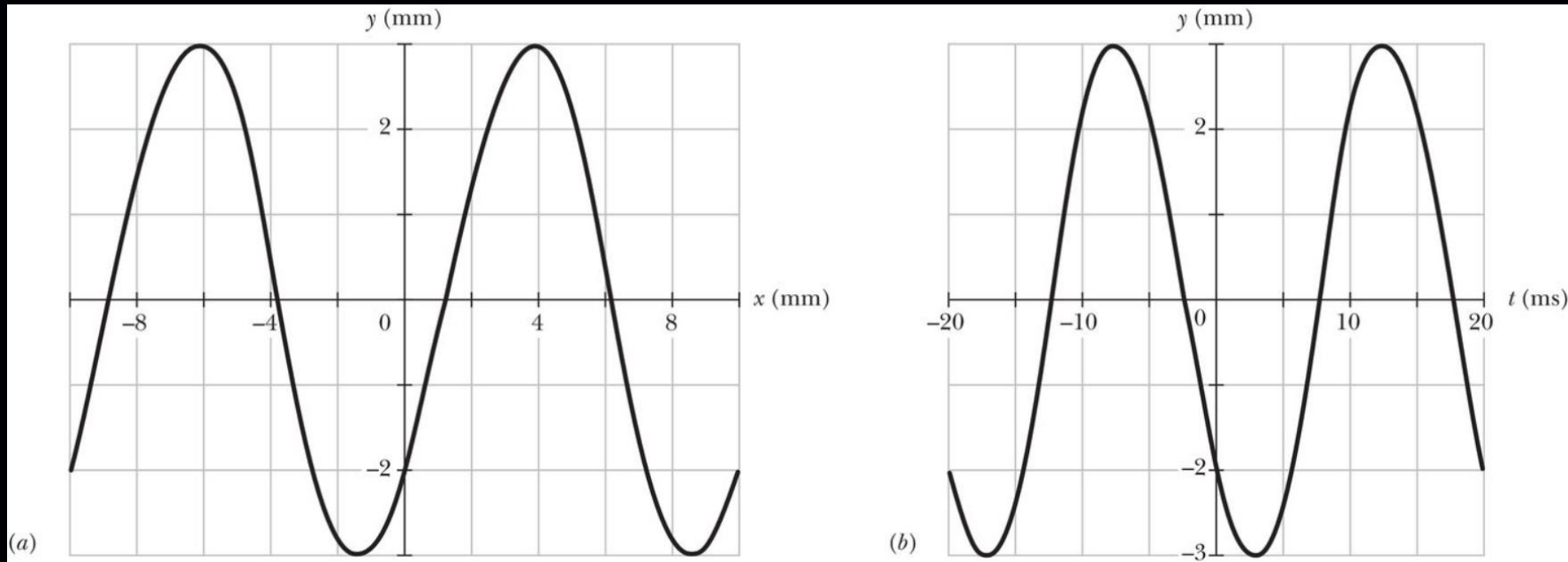


# Example

A transverse wave traveling along an  $x$  axis has the form given by  $y(x, t) = y_m \sin(kx \pm \omega t + \phi)$ . Figure (a) gives the displacements of string elements as a function of  $x$ , all at time  $t = 0$ . Figure (b) gives the displacements of the element at  $x = 0$  as a function of  $t$ . Find the values of the quantities .

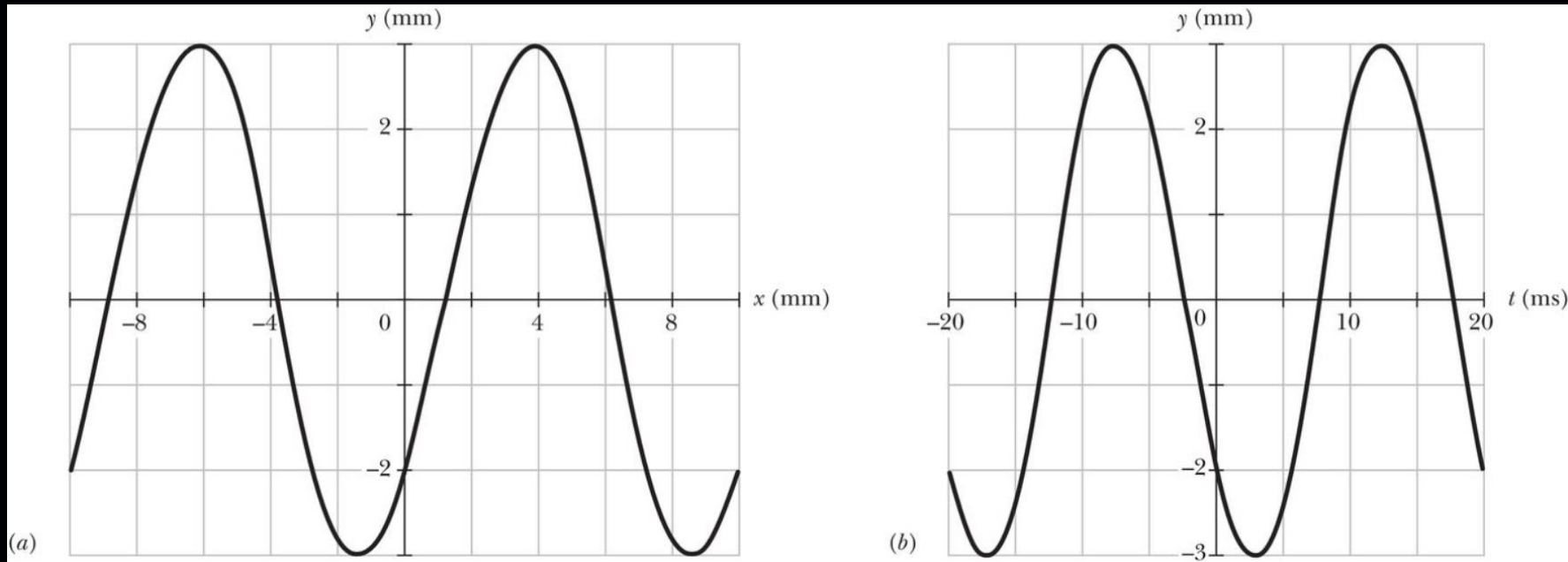


# Example



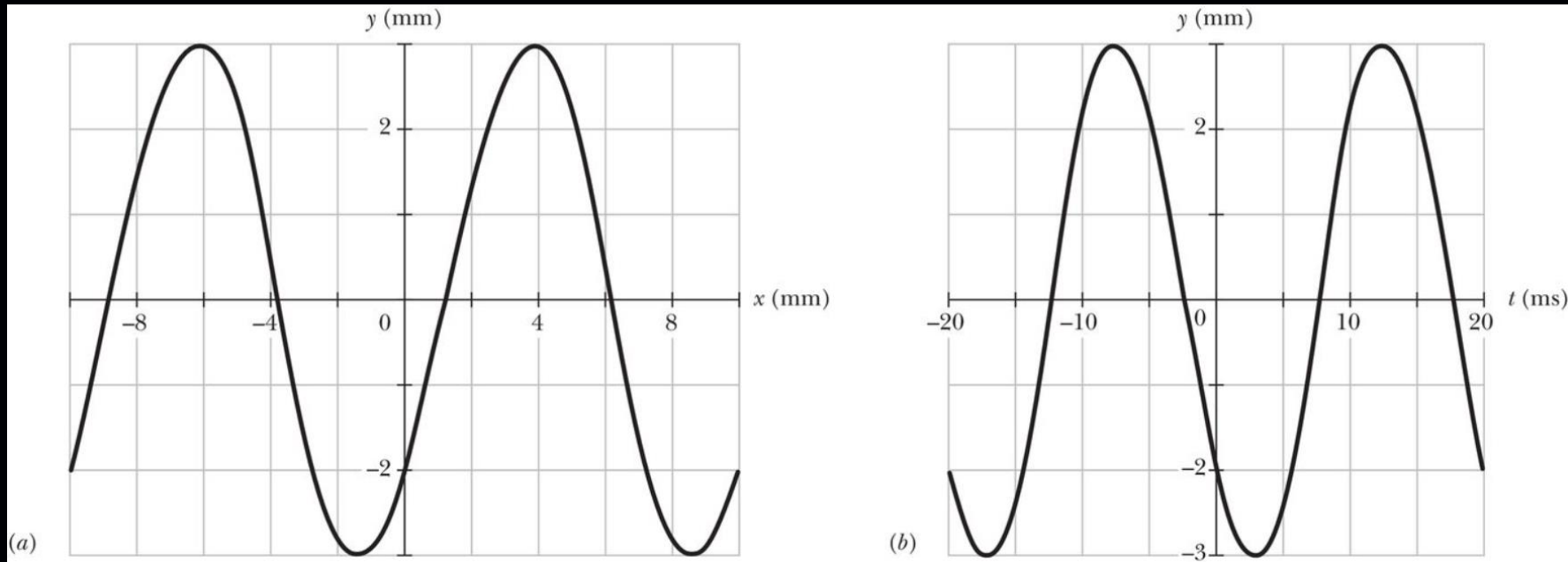
- Amplitude of wave  $y_m$ : The wave is oscillating between  $+y_m$  and  $-y_m$ . In both figure, the wave oscillating between  $+3$ mm and  $-3$ mm. Therefore  $y_m = 3$ mm

# Example



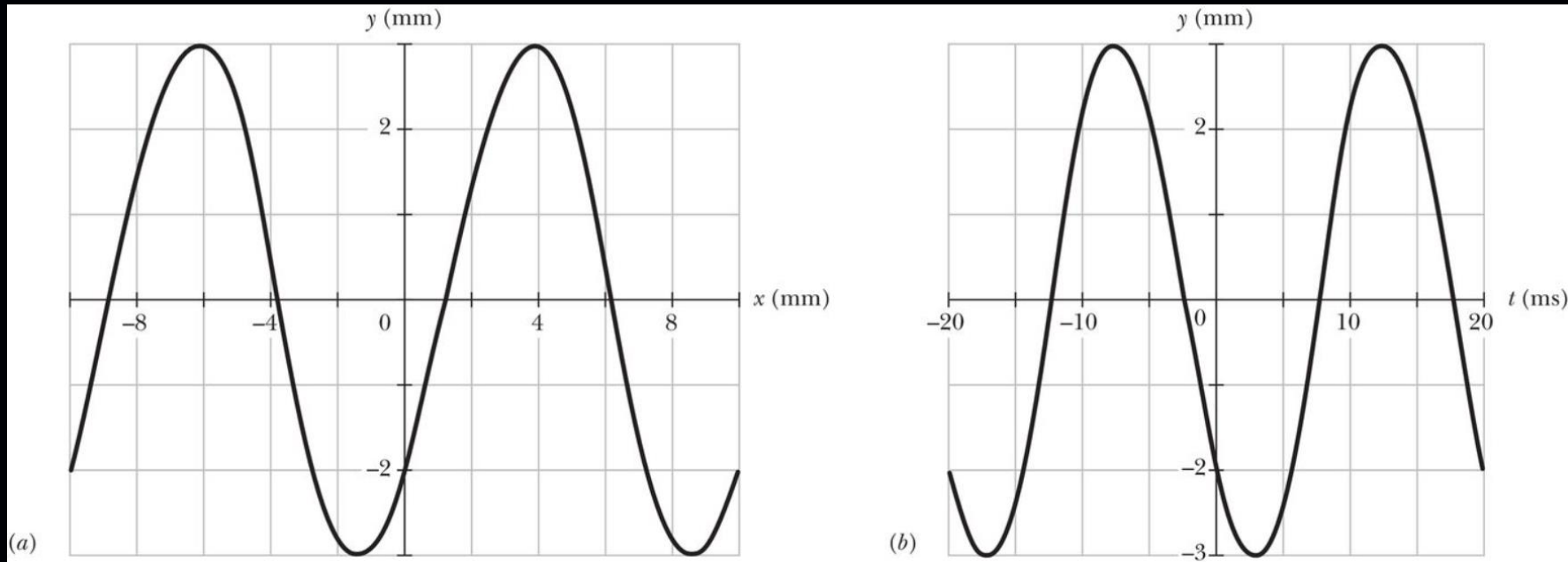
- Angular wave number  $k$ : We will find out wavelength  $\lambda$  first and use  $k = \frac{2\pi}{\lambda}$  to find out angular wave number. From figure (a), we can find out  $\lambda = 10\text{mm}$ . Therefore  $k = 200\pi \text{ rad/m}$

# Example



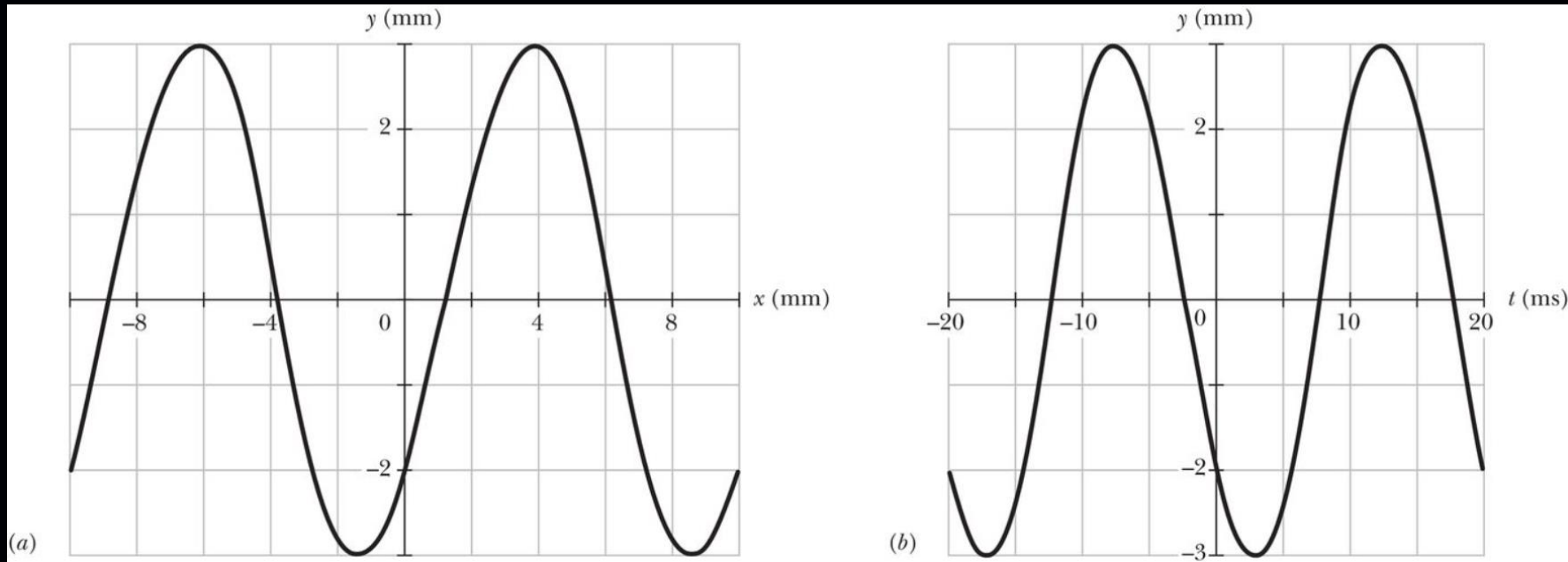
- Angular wave frequency  $\omega$ : We will find out period  $T$  first and use  $\omega = \frac{2\pi}{T}$  to find out angular wave frequency. From figure (b), we can find out  $T = 20\text{ms}$ . Therefore  $\omega = 100\pi \text{ rad/s}$

# Example



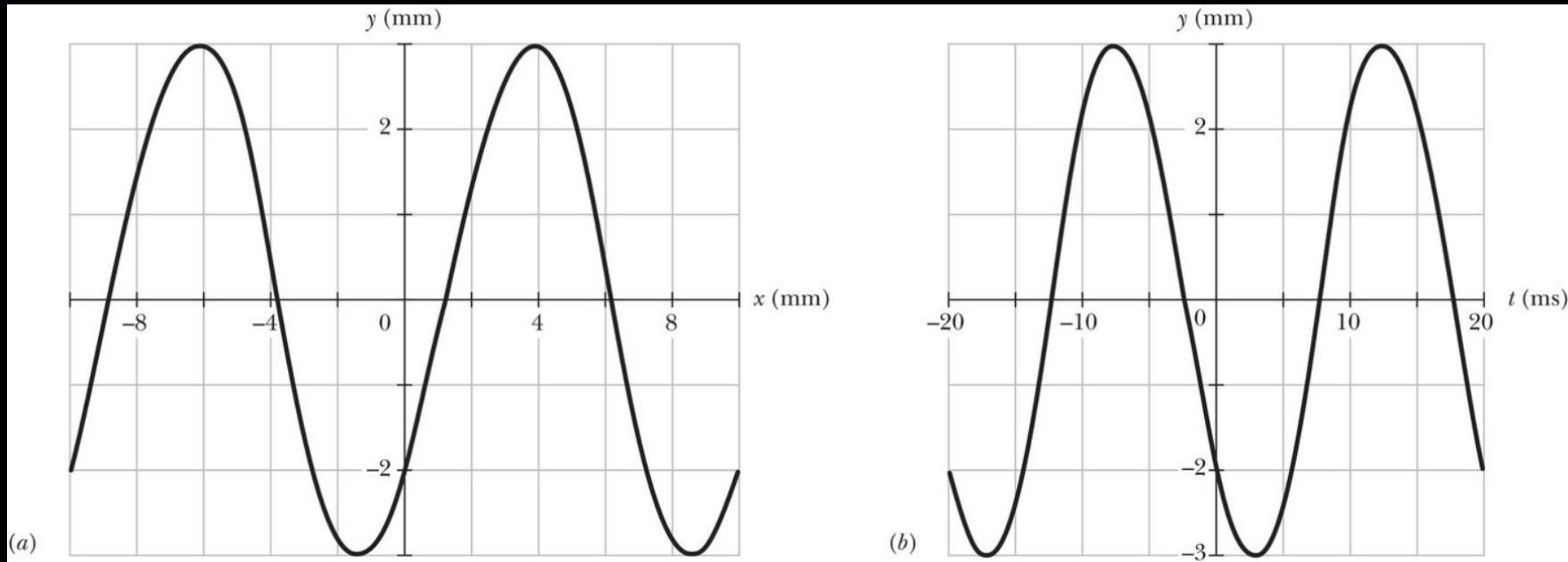
- Direction of travel: From (b), we know that the point  $x=0$  is oscillating **toward negative** first when  $t$  is increasing from 0. This can only happen when the wave is moving to the **right** in figure (a). Thus, it should be  $kx - \omega t$

# Example



- Phase constant  $\phi$ : From (a), we know that at  $y(x = 0, t = 0) = 3 \sin(\phi) = -2 \text{ mm}$ . This gives  $\phi = \sin^{-1}\left(-\frac{2}{3}\right) = -0.73 \text{ rad}$

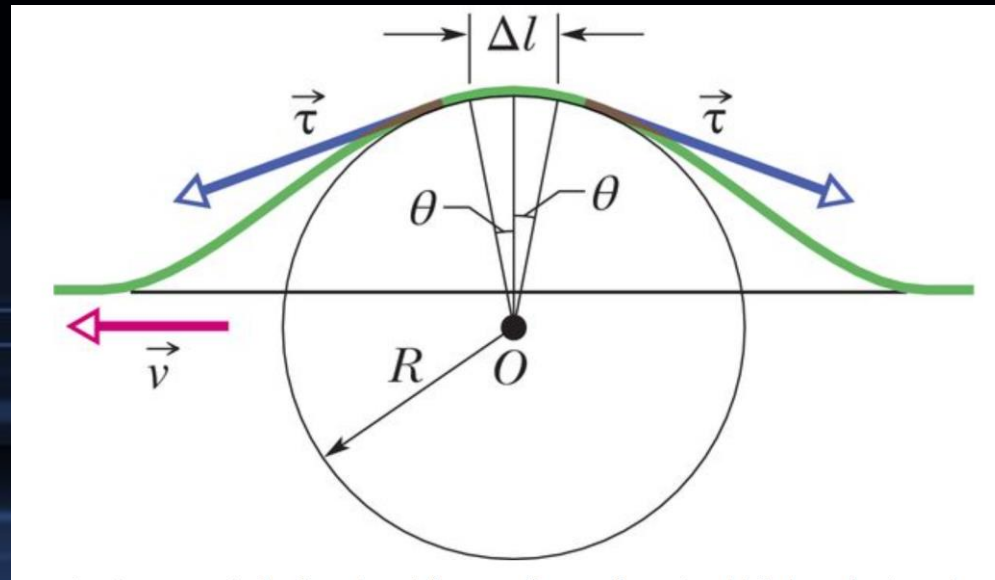
# Example



- Therefore we have  $y(x, t) = 3\text{mm} \sin(200\pi x - 100\pi t - 0.73)$

# Wave speed on a stretched string

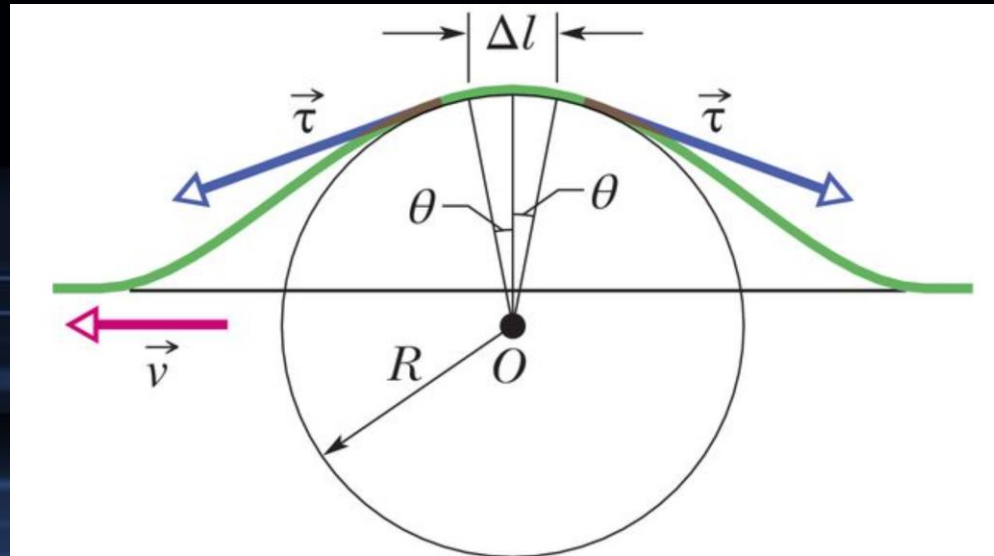
- What is a wave speed of a stretched string? Let's analyze in the following way:  
consider a single symmetrical pulse moving from left to right along a string with speed  $v$ .





# Wave speed on a stretched string

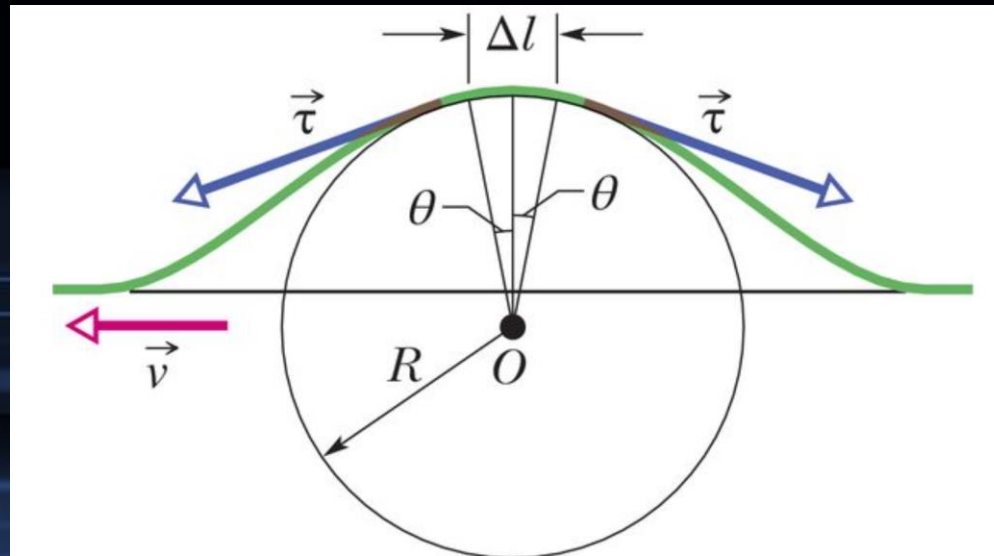
Consider a small string element of length  $\Delta l$  within the pulse, an element that forms an arc of a circle of radius  $R$  and subtending an angle  $2\theta$  at the center of that circle. A force  $\vec{\tau}$  with a magnitude equal to the tension in the string pulls tangentially on this element at each end.



# Wave speed on a stretched string

A radial restoring force with magnitude  $F = 2\tau\sin\theta \approx \tau \frac{\Delta l}{R}$

The mass of the element is  $\Delta m = \mu\Delta l$ , where  $\mu$  is the unit mass of the string.



# Wave speed on a stretched string

Considering it as a uniform circular motion, the force provide a centripetal acceleration:  $a = \frac{v^2}{R}$  to the mass  $\Delta m = \mu \Delta l$ .

Thus, we have  $\tau \frac{\Delta l}{R} = \mu \Delta l a = \mu \Delta l \frac{v^2}{R}$

There fore we can get  $v = \sqrt{\frac{\tau}{\mu}}$ , which is the wave speed of the stretched string.

# Energy of a wave traveling along string

- The kinetic energy  $dK$  associated with a string element of mass  $dm = \mu dx$  is given by  $dK = \frac{1}{2} dm u^2$ , where  $u$  is the transverse speed of the oscillating string element.
- $$dK = \frac{1}{2} dm \left( \frac{dy}{dt} \right)^2 = \frac{1}{2} dm \left( \frac{dy_m \sin(kx - \omega t + \phi)}{dt} \right)^2 =$$
$$\frac{1}{2} \mu dx y_m^2 \omega^2 \cos^2(kx - \omega t + \phi)$$
- Therefore,  $\frac{dK}{dt} = \frac{1}{2} \mu v y_m^2 \omega^2 \cos^2(kx - \omega t + \phi)$ , where  $v = \frac{dx}{dt}$  is the wave speed

# Energy of a wave traveling along string

- The average kinetic energy transfer

$$\left(\frac{dK}{dt}\right)_{avg} = \frac{1}{2} \mu v y_m^2 \omega^2 [\cos^2(kx - \omega t + \phi)]_{avg} = \frac{1}{4} \mu v y_m^2 \omega^2$$

- The average potential energy transfer will be the same amount because the nature of harmonic oscillation. Therefore, the power of the total energy transfer will be

$$P_{avg} = \frac{1}{2} \mu v y_m^2 \omega^2$$

# The wave equation

- By applying Newton's second law to the element's motion, we can derive a general differential equation, called the wave equation, that governs the travel of waves of any type:

$$\frac{\partial^2 y}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 y}{\partial t^2}$$

- The description  $y(x, t) = y_m \sin(kx - \omega t + \phi)$  is the solution of this general differential equation.