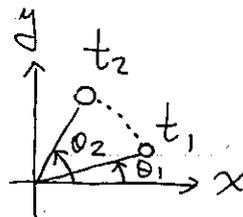


1. 角速度 + 角加速度

~ 平移運動, 定義轉動



Angular displacement: $\Delta\theta = \theta_2 - \theta_1$

($\sim \Delta x = x_2 - x_1$) \rightarrow (CCW)

$\Delta\theta$ 的方向: 逆時針 (counterclockwise) 轉動: > 0

順時針 (clockwise) 轉動: < 0
 \rightarrow CW

右手定則: $x \rightarrow y$ 的方向為 $+z$, $y \rightarrow x$ (順時針) 為 $-z$

\therefore 平均角速度 (average angular velocity) $\bar{\omega} = \frac{\theta_2 - \theta_1}{t_2 - t_1} = \frac{\Delta\theta}{\Delta t}$, ($\sim v = \frac{\Delta x}{\Delta t}$)

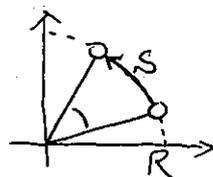
角速度 $\omega = \lim_{\Delta t \rightarrow 0} \bar{\omega} = \lim_{\Delta t \rightarrow 0} \frac{\Delta\theta}{\Delta t} = \frac{d\theta}{dt}$ ($\sim v = dx/dt$), $[\omega] = s^{-1}$

角加速度 $\alpha = \frac{d\omega}{dt} = \frac{d^2\theta}{dt^2}$ ($a = \frac{dv}{dt} = \frac{d^2x}{dt^2}$), $[\alpha] = s^{-2}$

linear vs. angular variables

弧長 $s = R\theta$ (θ 用 radian)

linear speed $v = \frac{ds}{dt} = \frac{d}{dt}(R\theta)$
 $= R \frac{d\theta}{dt} = R\omega$



週期 (period) $T =$ 轉一圈的時間, $\therefore \omega = \frac{2\pi}{T}$ or

$T = \frac{2\pi R}{v} = \frac{2\pi R}{R\omega} = \frac{2\pi}{\omega}$

f : 頻率 (frequency) = 每 sec 轉動的圈數, $\therefore f = \frac{1}{T}$ or

$\omega = 2\pi f = \frac{2\pi}{T}$, $[f] = s^{-1}$. $f = \text{rpm} =$ 每分鐘轉的圈數.
Revolutions per minute

Note: f 和 ω 的單位雖相同: s^{-1} , 但代表的意義不同.

$[\omega]$ 是 $\text{rad} \cdot s^{-1}$, 但 rad 沒單位.



v 是切線 (tangent) 速率 $\Rightarrow \frac{dv}{dt} =$ 切線加速度 a_t (用於 change speed)

$$\therefore a_t = \frac{dv}{dt} = R \frac{d\omega}{dt} = R\alpha$$



而徑向 (radial) 方向的加速度

即向心加速度 (用於 change 方向) $a_r = \frac{v^2}{R} = R\omega^2$

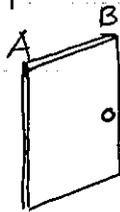
total 的加速度 $\vec{a} = \vec{a}_t + \vec{a}_r = a_t \hat{\theta} + a_r \hat{r}$

Table 10.1 Linear vs. Angular quantities

2. Torque and Newton II for rotation

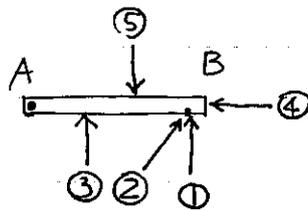
$x \sim \theta, v \sim \omega, a \sim \alpha, F \sim ? \rightarrow$ 描述轉動的難易程度 需有作用力

轉動力門的難易程度



A 為轉軸

top view



用大小相同的力作用在

(i) 不同位置 (ii) 不同方向 如左

轉動難易: ① > ② > ③ > ④ (不動); ①~③ = CCW, ⑤: CW

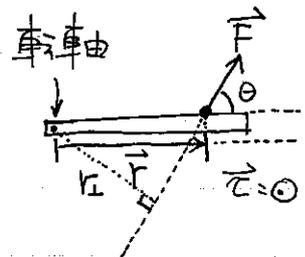
定義 torque (用 $\vec{\tau}$ 表示) $\vec{\tau} = \vec{r} \times \vec{F}$

$$\therefore \tau = |\vec{r}| \times |\vec{F}| \times \sin\theta$$

$$= F \cdot r \cdot \sin\theta$$

$$= F \cdot r_L$$

$$r_L = \text{level arm} = r \sin\theta$$



右手定則是 $\vec{\tau}$ 的方向

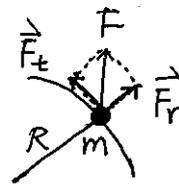
2D: \odot out of page

\otimes into the page



- Newton II for linear: $F = m a$
for angular: $\tau = ? \times \alpha$

For the simplest case = 質點 m



$$F_t = m a_t$$

$$\tau = R F_t = m R a_t = m R \cdot R \alpha = m R^2 \alpha$$

$$\equiv I \alpha \text{ (Newton II for rotation), where } I = m R^2$$

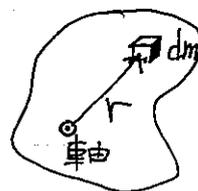
I : 轉動慣量 (rotational inertia or moment of inertia)

\therefore system of particles: $I = \sum m_i r_i^2$

$r_i = m_i$ 到轉軸的距離。

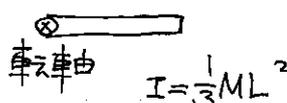
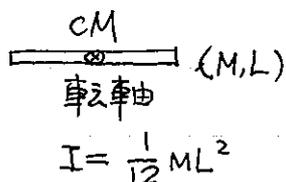
\therefore for 連續體: $I = \int r^2 dm$

(\sim CM 的作法) \Rightarrow 例題



- 平行軸 (parallel-axis) 定理 for I

例子:



兩平行轉軸相距 d , 其中之一通過 CM 形成的轉動慣量為 I_{cm}
則另一軸的 $I = I_{cm} + M d^2$, M 為連續體之 mass.



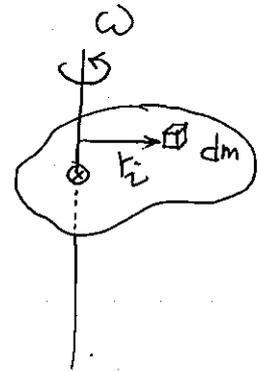
3. Rotational energy

o k

Consider a continuous body rotating about an axis with angular velocity ω .
 The body is divided into small elements dm , each at a distance r_i from the axis of rotation.

$$dK = \frac{1}{2} (dm) (v^2) = \frac{1}{2} (dm) (r_i \omega)^2$$

$$= \frac{1}{2} \omega^2 \cdot r_i^2 \cdot dm$$



$$\therefore \text{total rotational energy } K = \int dK = \frac{1}{2} \omega^2 \int r_i^2 dm = \frac{1}{2} I \omega^2$$

$$\text{rotational } K = \frac{1}{2} I \omega^2$$

o Work in rotational motion

work-energy theorem: $W = \Delta K$

$$\text{In rotation, } W = \int_{\theta_i}^{\theta_f} \tau d\theta \quad (\sim W = \int_{x_1}^{x_2} F(x) dx)$$

$$\Delta K_{\text{rot}} = \frac{1}{2} I (\omega_f^2 - \omega_i^2)$$

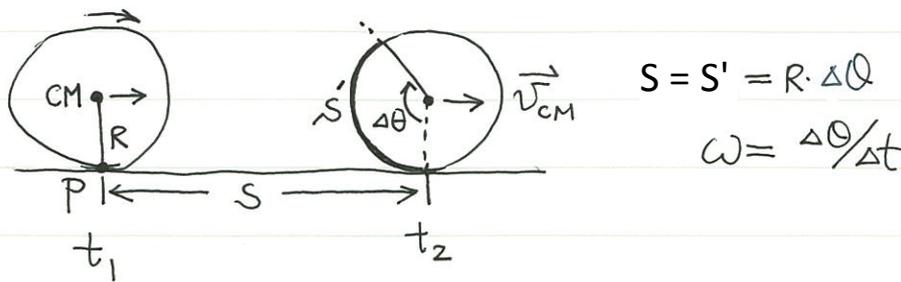
If τ is constant, $W = \tau (\theta_f - \theta_i)$



4. Rolling motion

Rolling

Rolling = $s' = s$, 有滑動則 $s' > s$ or $s' < s$
slipping



(i) 滾輪轉動的切線速率 $v = R\omega$

(ii) Δt 內, CM 移動的距離 = s , \therefore 滾輪的

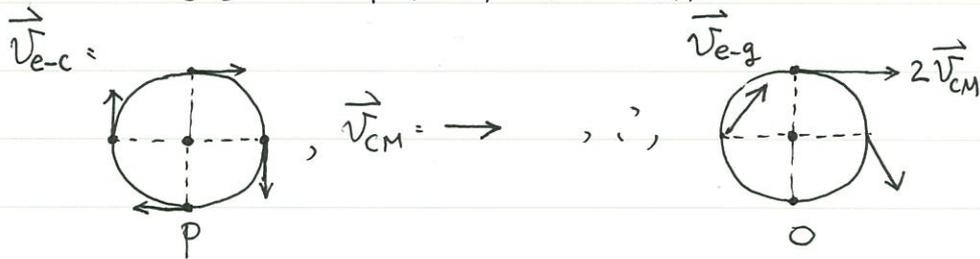
$$v_{CM} = \frac{s}{\Delta t} = R \frac{\Delta\theta}{\Delta t} = R\omega \text{ (向右)}$$

(iii) 滾輪邊緣上的點相對於地的速度 = ?

e = edge points, c = center of mass, g = ground

$$\vec{v}_{e-g} = \vec{v}_{e-c} + \vec{v}_{c-g}, \text{ 其中 } \vec{v}_{c-g} = \vec{v}_{CM}$$

$$\vec{v}_{e-c} = \text{切線速度}, v_{e-c} = v_{CM} = R\omega$$



v_{e-g} 在 top 點最大 = $2v_{CM}$
在接地點 P 為 0.

K of rolling

± 地面觀察者所測之 $K =$ 以 CM 為軸的轉動 + CM 的平移運動

$$\therefore K = K_{rot} + K_{transl} = \frac{1}{2} I_{CM} \omega^2 + \frac{1}{2} M v_{CM}^2$$

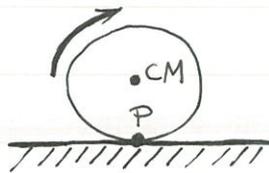
Since $v_{CM} = R\omega$

$$\therefore K = \frac{1}{2} (I_{CM} + MR^2) \omega^2 = \frac{1}{2} I_P \omega^2 \text{ (平行軸定理)}$$

where I_P : 以接地點 P 為軸的轉動慣量.



Rolling and friction



- (i) No slipping 時，
 接地點 P 對地是靜止的，∴ 若有 friction，則
 在此點的 friction 是 static \Rightarrow friction 不作功 (位移為 0)。
 \Rightarrow 能量守恆 $\Delta E = 0$ works! ($\Delta E = W_{nc}$)

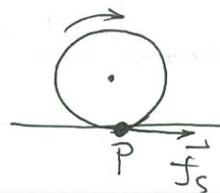
no slipping, $v_{cm} = R\omega$, $\therefore \frac{d}{dt} v_{cm} = a_{cm} = R \frac{d\omega}{dt} = R\alpha$

$\therefore \boxed{a_{cm} = R\alpha}$ for rolling.

若有 slipping, 則 $a_{cm} \neq R\alpha$.

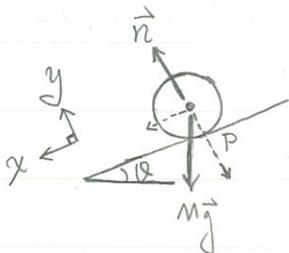
- (ii) 靜摩擦力 \vec{f}_s (用「防止滑動」想)

When $a_{cm} > 0$ and no slipping,
 加速往右 rolling, 為防止產生
 slipping, \vec{f}_s 作用在滾輪的
 接地點為向右方向。



if $a_{cm} < 0$, then \vec{f}_s ← P

- (iii) 斜坡上的滾輪 M, 如要產生 pure rolling, 則 $\vec{f}_s = ?$



\rightarrow Think: M 滑動下斜坡。為使滑動不產生，
 作用在 M 的 \vec{f}_s 方向必需是 \nearrow 。

重力 $M\vec{g}$ 及 \vec{n} 作用在 CM, level arm $r_c = 0$
 對 M 的 $\tau = 0$ 。唯一的 τ 來自 f_s 。

$\therefore \tau = Rf_s = I_{cm}\alpha = I_{cm}a_{cm}/R \quad (1)$
 Newton II in x: $Mg\sin\theta - f_s = Ma_{cm} \quad (2)$

$f_s = \frac{Mg\sin\theta}{1 + \frac{MR^2}{I_{cm}}}$

Wolfson Example 10.2

風力發電機的blade (扇葉) 長 28m,
有風時, 以 21 rpm 轉動, 風停時, 以
等角加速度 0.12 rad/s^2 減慢轉動, 則
在停業前, 共轉多少圈?

$$\sim v_f^2 = 0 = v_i^2 + 2a \cdot \Delta x$$

$$\omega_f^2 - \omega_i^2 = 2\alpha \cdot (\Delta\theta)$$

$$\omega_f = 0, \omega_i = 21 \text{ rpm} = 21 \times \frac{2\pi}{60} \text{ rad/s, and}$$

$$\alpha = -0.12 \text{ rad/s}^2$$

$$\therefore 0 - \left(\frac{21 \times 2\pi}{60}\right)^2 = 2 \cdot (-0.12) \cdot \Delta\theta$$

$$\Rightarrow \Delta\theta = 20 \text{ rad} = \frac{20}{2\pi} = 3.2 \text{ revolutions}$$

or change the unit of α

$$\alpha = -0.12 \text{ rad} \cdot \text{s}^{-2} = -0.12 \cdot \frac{\text{revolution}}{2\pi} \cdot \left(\frac{1}{60} \text{ min}\right)^{-2}$$

$$= -0.12 \times \frac{1}{2\pi} \times 60^2 \cdot \text{revolution} \cdot \text{min}^{-2}$$

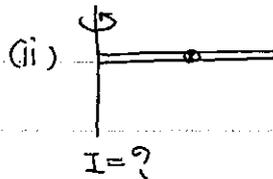
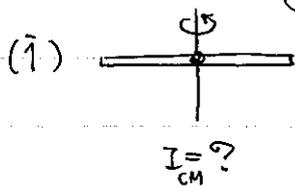
$$\text{then } 0 - 21^2 = -2 \times 0.12 \times \frac{1}{2\pi} \times 60^2 \times (\Delta\theta) \text{ here } [\Delta\theta] = \text{revolution}$$

$$\therefore \Delta\theta = 3.2 \text{ revolutions,}$$

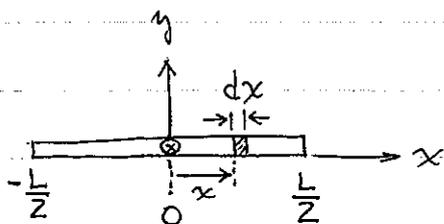


Wolfson Example 10.5: 1D I

uniform 1D rod, long L and mass M



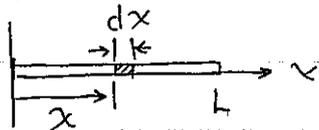
(i)



切割成長度為 dx 的 dm
 $\Rightarrow dm = \lambda \cdot dx = \frac{M}{L} \cdot dx$

$$\begin{aligned} \therefore I_{CM} &= \int_{-L/2}^{L/2} x^2 \cdot dm = \frac{M}{L} \int_{-L/2}^{L/2} x^2 dx = \frac{2M}{L} \int_0^{L/2} x^2 \cdot dx = \frac{2M}{L} \times \frac{1}{3} \times \left(\frac{L}{2}\right)^3 \\ &= \frac{1}{12} ML^2 \end{aligned}$$

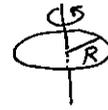
(ii) Similar to (i)



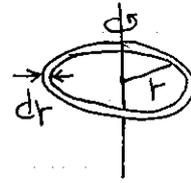
$$\begin{aligned} I &= \int_0^L x^2 \cdot dm = \frac{M}{L} \int_0^L x^2 \cdot dx = \frac{1}{3} ML^2 = M \cdot \left(\frac{L}{2}\right)^2 + \frac{1}{12} ML^2 \\ &= Md^2 + I_{CM} \quad \text{— 平行軸定理。} \end{aligned}$$

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Wolfson Example 10.7: 2D I
 Uniform disk of radius R and mass M , $I_{cm} = ?$



將 disk 分割成不同半徑 r , 但相同寬度 dr 的同心 ring = dm



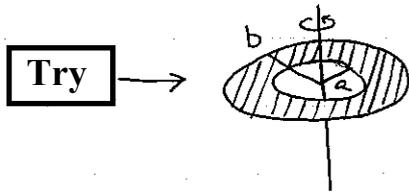
ring 的面積
 $dA = \text{長} \times \text{寬}$
 $= 2\pi r \cdot dr$

則 dm 形成的轉動慣量

$$\begin{aligned} dI &= r^2 dm = r^2 \cdot \sigma \cdot dA \\ &= r^2 \cdot \frac{M}{\pi R^2} \cdot 2\pi r \cdot dr \\ &= \frac{2M}{R^2} r^3 \cdot dr \end{aligned}$$

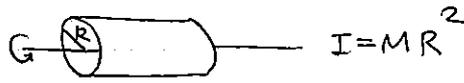
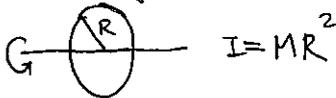
σ : 單位面積的 mass = $\frac{M}{\pi R^2}$

$$\therefore I = \int dI = \frac{2M}{R^2} \int_0^R r^3 \cdot dr = \frac{1}{2} MR^2$$

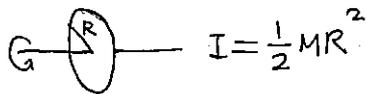


$$I_{cm} = \frac{1}{2} M(a^2 + b^2)$$

1D ring



2D disk



Cylinder

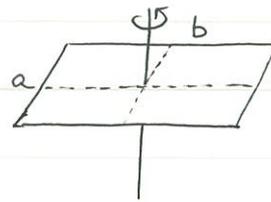


\Rightarrow 徑率軸方向延伸長度形成的 3D 物體, 其 2D 具相同的 I



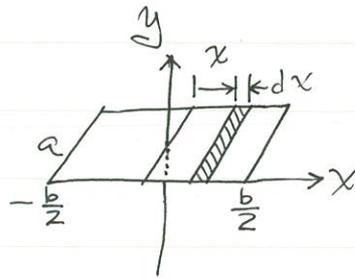
Wolfson Extra Example of 2D I

如 Table 10.2 的 2D 长方形
具 uniform mass M , 则 $I_{cm} = ?$



斜线的 $dm = \sigma \cdot dA$

$$\begin{aligned} \therefore dm &= \frac{M}{ab} \cdot a \cdot dx \\ &= \frac{M}{b} \cdot dx \end{aligned}$$



$$\sigma = \frac{M}{ab}$$

$$dI_{cm} = \frac{1}{12} dm \cdot a^2 \quad \text{and} \quad dI = dI_{cm} + dm \cdot x^2 \quad (\text{平行轴定理})$$

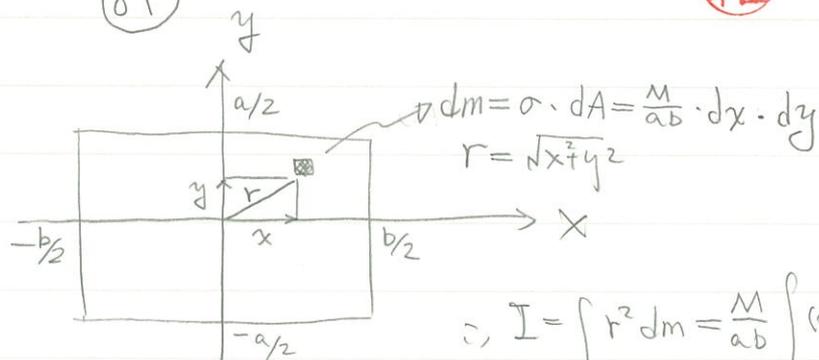
$$\therefore I = \int dI = \int_{-b/2}^{b/2} \left(\frac{1}{12} \cdot a^2 \cdot \frac{M}{b} \cdot dx + \frac{M}{b} \cdot dx \cdot x^2 \right)$$

$$= \frac{M}{12} (a^2 + b^2) \quad (\text{增加厚度, 仍是相同的 } I)$$

Note: As $a \rightarrow 0$ or $b \rightarrow 0 \Rightarrow$ 1D rod.

(1)

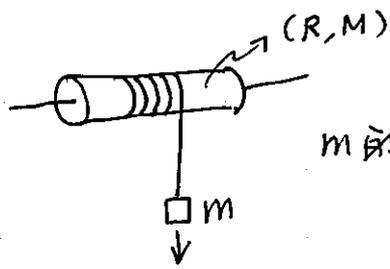
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$$\begin{aligned} dm &= \sigma \cdot dA = \frac{M}{ab} \cdot dx \cdot dy \\ r &= \sqrt{x^2 + y^2} \end{aligned}$$

$$\begin{aligned} \therefore I &= \int r^2 dm = \frac{M}{ab} \int (x^2 + y^2) dx dy \\ &= \frac{1}{12} (a^2 + b^2) \end{aligned}$$

Wolfson Example 10.9



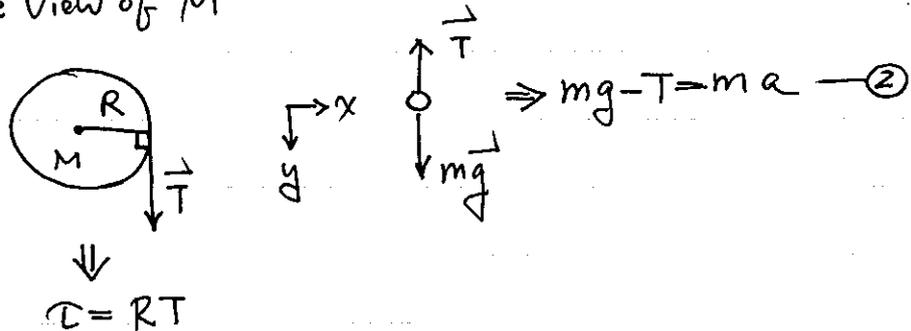
m 的下降 $a = ?$ (在沒有滑動的情形下)

Key: m 的下降加速度 = M 轉動時的切線加速度 a_t

$$\therefore a_t = a = R\alpha = R \cdot \frac{\tau}{I} \quad \text{--- ①}$$

free-body diagrams of M and m

Side view of M



$$\therefore \text{①} \Rightarrow a = R \cdot \frac{\tau}{I} = R \cdot \frac{RT}{\frac{1}{2}MR^2} = \frac{2}{M}T \quad \text{代入 ②}$$

$$mg = T + ma = \left(\frac{M}{2} + m\right)a$$

$$\therefore a = \frac{mg}{\frac{M}{2} + m} = \frac{2mg}{M + 2m} \quad (\text{向下}).$$

Assess: check by $M=0$, $M=0$ 時則無轉動量, $\therefore a$ 應該 = g .

\Rightarrow Yes.

Note: R 沒有出現在 $a = \frac{2mg}{M+2m}$ 中.



Wolfson Example 10.12 and 觀念例題 1.

空心球 (M, R) 靜止從高度 h 的斜坡滾下, 則在坡底球的 speed = ?

Energy conserved, $\therefore E_f = E_i \Rightarrow \Delta K + \Delta U = 0$

$$\Delta K = K_f - K_i = K_f = \frac{1}{2} M v^2 + \frac{1}{2} I \omega^2$$

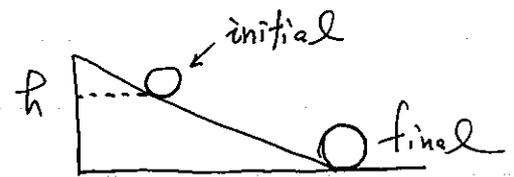
$$\Delta U = 0 - Mgh = -Mgh$$

$$\therefore \frac{1}{2} M v^2 + \frac{1}{2} I \omega^2 = Mgh, \quad I = \frac{2}{5} MR^2 \text{ (for sphere), and } \omega = \frac{v}{R}$$

$$\therefore \frac{1}{2} M v^2 + \frac{1}{2} \times \frac{2}{5} MR^2 \times \frac{v^2}{R^2} = M v^2 \left(\frac{1}{2} + \frac{1}{5} \right) = \frac{7}{10} M v^2 = Mgh$$

$$\therefore v = \sqrt{\frac{10}{7} gh} \quad (\text{# } M, R \text{ 無關})$$

Note: 無 friction 下滑的 $v = \sqrt{2gh}$, 含有滾動的物體, 其在坡底的 speed 是 $<$ 於此值.



又觀念例題: 滾動比賽, 誰先到達坡底?

$$K = \frac{1}{2} M v^2 + \frac{1}{2} I \omega^2 = \text{CM 的平動 } K + \text{轉動 } K$$

$$= \frac{1}{2} M v^2 + \frac{1}{2} I \cdot \frac{v^2}{R^2}$$

\therefore 坡底的 v # I 成反向關係

$I \uparrow, v \downarrow$

例 = 空心球殼 $I = \frac{2}{3} MR^2 \Rightarrow v = \sqrt{\frac{6}{5} gh}$

空心圓柱 $I = \frac{1}{2} MR^2 \Rightarrow v = \sqrt{\frac{4}{3} gh}$

空心圓柱 $I = MR^2 \Rightarrow v = \sqrt{gh}$

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